Statistics Toolbox

For Use with MATLAB®

User's Guide

Version 2.1

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Before You Begin

This introduction describes how to begin using the Statistics Toolbox. It explains how to use this guide, and points you to additional books for toolbox installation information.

What is the Statistics Toolbox?

The Statistics Toolbox is a collection of tools built on the MATLAB® numeric computing environment. The toolbox supports a wide range of common statistical tasks, from random number generation, to curve fitting, to design of experiments and statistical process control. The toolbox provides two categories of tools:

• Building-block probability and statistics functions
• Graphical, interactive tools

The first category of tools is made up of functions that you can call from the command line or from your own applications. Many of these functions are MATLAB M-files, series of MATLAB statements that implement specialized Statistics algorithms. You can view the MATLAB code for these functions using the statement

```
type function_name
```

You can change the way any toolbox function works by copying and renaming the M-file, then modifying your copy. You can also extend the toolbox by adding your own M-files.

Secondly, the toolbox provides a number of interactive tools that let you access many of the functions through a graphical user interface (GUI). Together, the GUI-based tools provide an environment for polynomial fitting and prediction, as well as probability function exploration.

How to Use This Guide

If you are a new user begin with Chapter 1, *Tutorial*. This chapter introduces the MATLAB statistics environment through the toolbox functions. It describes the functions with regard to particular areas of interest, such as probability distributions, linear and nonlinear models, principal components analysis, design of experiments, statistical process control, and descriptive statistics.

All toolbox users should use Chapter 2, *Reference*, for information about specific tools. For functions, reference descriptions include a synopsis of the function's syntax, as well as a complete explanation of options and operation. Many reference descriptions also include examples, a description of the function's algorithm, and references to additional reading material.

Use this guide in conjunction with the software to learn about the powerful features that MATLAB provides. Each chapter provides numerous examples that apply the toolbox to representative statistical tasks.

The random number generation functions for various probability distributions are based on all the primitive functions, `randn` and `rand`. There are many examples that start by generating data using random numbers. To duplicate the results in these examples, first execute the commands below:

```
seed = 931316785;
rand('seed', seed);
randn('seed', seed);
```

You might want to save these commands in an M-file script called `init.m`. Then, instead of three separate commands, you need only type `init`.

Mathematical Notation

This manual and the Statistics Toolbox functions use the following mathematical notation conventions:

β	Parameters in a linear model.
$E(x)$	Expected value of x. $E(x) = \int t f(t)\, dt$
$f(x \mid a,b)$	Probability density function. x is the independent variable; a and b are fixed parameters.
$F(x \mid a,b)$	Cumulative distribution function.
$I([a, b])$	Indicator function. In this example the function takes the value 1 on the closed interval from a to b and is 0 elsewhere.
p and q	p is the probability of some event. q is the probability of $\sim p$, so $q = 1 - p$.

Typographical Conventions

To Indicate...	This Guide Uses...	Example
Example code	Monospace type.	To assign the value 5 to A, enter `A = 5`

MATLAB output	Monospace type.	MATLAB responds with
		
		`A =`
		`     5`

MATLAB strings	Quoted `'italic'` Monospace type.	`'model'`
Function names	Monospace type.	The cos function finds the cosine of each array element.
Mathematical expressions	Variables in *italics*. Functions, operators, and constants in standard type.	This vector represents the polynomial $p = x^2 + 2x + 3$

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Tutorial

The Statistics Toolbox, for use with MATLAB®, supplies basic statistics capability on the level of a first course in engineering or scientific statistics. The statistics functions it provides are building blocks suitable for use inside other analytical tools.

The Statistics Toolbox has more than 200 M-files, supporting work in the topical areas below:

- Probability distributions
- Parameter estimation
- Descriptive statistics
- Linear models
- Nonlinear models
- Hypothesis tests
- Multivariate statistics
- Statistical plots
- Statistical Process Control
- Design of Experiments

Probability Distributions

The Statistics Toolbox supports 20 probability distributions. For each distribution there are five associated functions. They are:

- Probability density function (pdf)
- Cumulative distribution function (cdf)
- Inverse of the cumulative distribution function
- Random number generator
- Mean and variance as a function of the parameters

Parameter Estimation

The Statistics Toolbox has functions for computing parameter estimates and confidence intervals for data driven distributions (beta, binomial, exponential, gamma, normal, Poisson, uniform and Weibull).

Descriptive Statistics

The Statistics Toolbox provides functions for describing the features of a data sample. These descriptive statistics include measures of location and spread, percentile estimates and functions for dealing with data having missing values.

Linear Models

In the area of linear models the Statistics Toolbox supports one-way and two-way analysis of variance (ANOVA), multiple linear regression, stepwise regression, response surface prediction, and ridge regression.

Nonlinear Models

For nonlinear models there are functions for parameter estimation, interactive prediction and visualization of multidimensional nonlinear fits, and confidence intervals for parameters and predicted values.

Hypothesis Tests

There are also functions that do the most common tests of hypothesis – t-tests and Z-tests.

Multivariate Statistics

The Statistics Toolbox supports methods in Multivariate Statistics, including Principal Components Analysis and Linear Discriminant Analysis.

Statistical Plots

The Statistics Toolbox adds box plots, normal probability plots, Weibull probability plots, control charts, and quantile-quantile plots to the arsenal of graphs in MATLAB. There is also extended support for polynomial curve fitting and prediction.

Statistical Process Control (SPC)

For SPC there are functions for plotting common control charts and performing process capability studies.

Design of Experiments (DOE)

The Statistics Toolbox supports both factorial and D-optimal design. There are functions for generating designs, augmenting designs and optimally assigning units with fixed covariates.

Probability Distributions

Probability distributions arise from experiments where the outcome is subject to chance. The nature of the experiment dictates which probability distributions may be appropriate for modeling the resulting random outcomes. There are two types of probability distributions – *continuous* and *discrete*.

Continuous (data)	Continuous (statistics)	Discrete
Beta	Chi-square	Binomial
Exponential	Noncentral Chi-square	Discrete Uniform
Gamma	F	Geometric
Lognormal	Noncentral F	Hypergeometric
Normal	t	Negative Binomial
Rayleigh	Noncentral t	Poisson
Uniform		
Weibull		

Suppose you are studying a machine that produces videotape. One measure of the quality of the tape is the number of visual defects per hundred feet of tape. The result of this experiment is an integer, since you cannot observe 1.5 defects. To model this experiment you should use a discrete probability distribution.

A measure affecting the cost and quality of videotape is its thickness. Thick tape is more expensive to produce, while variation in the thickness of the tape on the reel increases the likelihood of breakage. Suppose you measure the thickness of the tape every 1000 feet. The resulting numbers can take a continuum of possible values, which suggests using a continuous probability distribution to model the results.

Using a probability model does not allow you to predict the result of any individual experiment but you can determine the probability that a given outcome will fall inside a specific range of values.

Overview of the Functions

MATLAB provides five functions for each distribution:

- Probability density function (pdf)
- Cumulative distribution function (cdf)
- Inverse cumulative distribution function
- Random number generator
- Mean and variance

This section discusses each of these functions.

Probability Density Function (pdf)

The probability density function has a different meaning depending on whether the distribution is discrete or continuous.

For discrete distributions, the pdf is the probability of observing a particular outcome. In our videotape example, the probability that there is exactly one defect in a given hundred feet of tape is the value of the pdf at 1.

Unlike discrete distributions, the pdf of a continuous distribution at a value is not the probability of observing that value. For continuous distributions the probability of observing any particular value is zero. To get probabilities you must integrate the pdf over an interval of interest. For example the probability of the thickness of a videotape being between one and two millimeters is the integral of the appropriate pdf from one to two.

A pdf has two theoretical properties:

- The pdf is zero or positive for every possible outcome.
- The integral of a pdf over its entire range of values is one.

A pdf is not a single function. Rather a pdf is a family of functions characterized by one or more parameters. Once you choose (or estimate) the parameters of a pdf, you have uniquely specified the function.

The pdf function call has the same general format for every distribution in the Statistics Toolbox. The following commands illustrate how to call the pdf for the normal distribution.

```
x = [-3: 0. 1: 3];
f = normpdf(x, 0, 1);
```

The variable f contains the density of the normal pdf with parameters 0 and 1 at the values in x. The first input argument of every pdf is the set of values for which you want to evaluate the density. Other arguments contain as many parameters as are necessary to define the distribution uniquely. The normal distribution requires two parameters, a location parameter (the mean, μ) and a scale parameter (the standard deviation, σ).

Cumulative Distribution Function (cdf)

If *f* is a probability density function, the associated cumulative distribution function *F* is

$$F(x) = P(X \le x) = \int_{-\infty}^{x} f(t)\,dt$$

The cdf of a value *x*, *F(x)*, is the probability of observing any outcome less than or equal to *x*.

A cdf has two theoretical properties.

- The cdf ranges from 0 to 1.
- If *y > x*, then the cdf of *y* is greater than or equal to the cdf of *x*.

The cdf function call has the same general format for every distribution in the Statistics Toolbox. The following commands illustrate how to call the cdf for the normal distribution:

```
x = [-3:0.1:3];
p = normcdf(x,0,1);
```

The variable p contains the probabilities associated with the normal cdf with parameters 0 and 1 at the values in x. The first input argument of every cdf is the set of values for which you want to evaluate the probability. Other arguments contain as many parameters as are necessary to define the distribution uniquely.

Inverse Cumulative Distribution Function

The inverse cumulative distribution function returns critical values for hypothesis testing given significance probabilities. To understand the relationship between a continuous cdf and its inverse function, try the following:

```
x = [-3:0.1:3];
xnew = norminv(normcdf(x,0,1),0,1);
```

How does xnew compare with x? Conversely, try this:

```
p = [0.1:0.1:0.9];
pnew = normcdf(norminv(p, 0, 1), 0, 1);
```

How does pnew compare with p?

Calculating the cdf of values in the domain of a continuous distribution returns probabilities between zero and one. Applying the inverse cdf to these probabilies yields the original values.

For discrete distributions, the relationship between a cdf and its inverse function is more complicated. It is likely that there is no *x* value such that the cdf of *x* yields *p*. In these cases the inverse function returns the first value *x* such that the cdf of *x* equals or exceeds *p*. Try this:

```
x = [0:10];
y = binoinv(binocdf(x, 10, 0.5), 10, 0.5);
```

How does x compare with y?

The commands below show the problem with going the other direction for discrete distributions.

```
p = [0.1:0.2:0.9];
pnew = binocdf(binoinv(p, 10, 0.5), 10, 0.5)

pnew =

    0.1719    0.3770    0.6230    0.8281    0.9453
```

The inverse function is useful in hypothesis testing and production of confidence intervals. Here is the way to get a 99% confidence interval for a normally distributed sample.

```
p = [0.005 0.995];
x = norminv(p, 0, 1)

x =

   -2.5758    2.5758
```

The variable x contains the values associated with the normal inverse function with parameters 0 and 1 at the probabilities in p. The difference $p(2) - p(1)$ is

0.99. Thus, the values in x define an interval that contains 99% of the standard normal probability.

The inverse function call has the same general format for every distribution in the Statistics Toolbox. The first input argument of every inverse function is the set of probabilities for which you want to evaluate the critical values. Other arguments contain as many parameters as are necessary to define the distribution uniquely.

Random Numbers

The methods for generating random numbers from any distribution all start with uniform random numbers. Once you have a uniform random number generator, you can produce random numbers from other distributions either directly or by using inversion or rejection methods.

Direct.   Direct methods flow from the definition of the distribution.

As an example, consider generating binomial random numbers. You can think of binomial random numbers as the number of heads in n tosses of a coin with probability p of a heads on any toss. If you generate n uniform random numbers and count the number that are greater than p, the result is binomial with parameters n and p.

Inversion.   The inversion method works due to a fundamental theorem that relates the uniform distribution to other continuous distributions.

If F is a continuous distribution with inverse F^{-1}, and U is a uniform random number, then $F^{-1}(U)$ has distribution F.

So, you can generate a random number from a distribution by applying the inverse function for that distribution to a uniform random number. Unfortunately, this approach is usually not the most efficient.

Rejection.   The functional form of some distributions makes it difficult or time consuming to generate random numbers using direct or inversion methods. Rejection methods can sometimes provide an elegant solution in these cases.

Suppose you want to generate random numbers from a distribution with pdf f. To use rejection methods you must first find another density, g, and a constant, c, so that the inequality below holds.

$$f(x) \leq cg(x) \forall x$$

You then generate the random numbers you want using the following steps:

1 Generate a random number x from distribution G with density g.

2 Form the ratio $r = \dfrac{cg(x)}{f(x)}$

3 Generate a uniform random number u.

4 If the product of u and r is less than one, return x.

5 Otherwise repeat steps one to three.

For efficiency you need a cheap method for generating random numbers from G and the scalar, c, should be small. The expected number of iterations is c.

Syntax for Random Number Functions. You can generate random numbers from each distribution. This function provides a single random number or a matrix of random numbers, depending on the arguments you specify in the function call.

For example, here is the way to generate random numbers from the beta distribution. Four statements obtain random numbers: the first returns a single number, the second returns a 2-by-2 matrix of random numbers, and the third and fourth return 2-by-3 matrices of random numbers.

```
a = 1;
b = 2;
c = [.1 .5; 1 2];
d = [.25 .75; 5 10];
m = [2 3];
nrow = 2;
ncol = 3;
r1 = betarnd(a, b)
r1 =

    0.4469
```

```
r2 = betarnd(c, d)
r2 =

    0.8931    0.4832
    0.1316    0.2403

r3 = betarnd(a, b, m)
r3 =

    0.4196    0.6078    0.1392
    0.0410    0.0723    0.0782

r4 = betarnd(a, b, nrow, ncol)
r4 =

    0.0520    0.3975    0.1284
    0.3891    0.1848    0.5186
```

Mean and Variance

The mean and variance of a probability distribution are generally simple functions of the parameters of the distribution. The Statistics Toolbox functions ending in stat all produce the mean and variance of the desired distribution given the parameters.

The example shows a contour plot of the mean of the Weibull distribution as a function of the parameters.

```
x = (0.5:0.1:5);
y = (1:0.04:2);
[X,Y] = meshgrid(x,y);
Z = weibstat(X,Y);
[c,h] = contour(x,y,Z,[0.4 0.6 1.0 1.8]);
clabel(c);
```
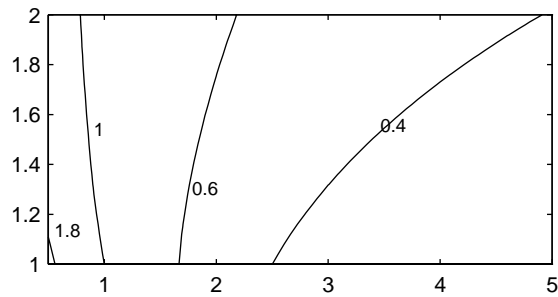
Overview of the Distributions

The Statistics Toolbox supports 20 probability distributions. These are:

- Beta
- Binomial
- Chi-square
- Noncentral Chi-square
- Discrete Uniform
- Exponential
- F
- Noncentral F
- Gamma
- Geometric
- Hypergeometric
- Lognormal
- Negative Binomial
- t
- Noncentral t
- Normal
- Poisson
- Rayleigh
- Uniform
- Weibull

This section gives a short introduction to each distribution.

Beta Distribution

Background.   The beta distribution describes a family of curves that are unique in that they are nonzero only on the interval [0 1]. A more general version of the function assigns parameters to the end-points of the interval.

The beta cdf is the same as the incomplete beta function.

The beta distribution has a functional relationship with the t distribution. If Y is an observation from Student's t distribution with ν degrees of freedom then the following transformation generates X, which is beta distributed:

$$X = \frac{1}{2} + \frac{1}{2}\frac{Y}{\sqrt{\nu + Y^2}}$$

$$if\ Y \sim t(\nu)\ \ then\ \ X \sim \beta\left(\frac{\nu}{2}, \frac{\nu}{2}\right)$$

The Statistics Toolbox uses this relationship to compute values of the t cdf and inverse function as well as generating t distributed random numbers.

Mathematical Definition.   The beta pdf is:

$$y = f(x|a, b) = \frac{1}{B(a, b)}x^{a-1}(1-x)^{b-1}I_{(0, 1)}(x)$$

Parameter Estimation.   Suppose you are collecting data that has hard lower and upper bounds of zero and one respectively. Parameter estimation is the process of determining the parameters of the beta distribution that fit this data best in some sense.

One popular criterion of goodness is to maximize the likelihood function. The likelihood has the same form as the beta pdf on the previous page. But for the pdf, the parameters are known constants and the variable is x. The likelihood function reverses the roles of the variables. Here, the sample values (the xs) are already observed. So they are the fixed constants. The variables are the unknown parameters. Maximum likelihood estimation (MLE) involves calculating the values of the parameters that give the highest likelihood given the particular set of data.

The function betafit returns the MLEs and confidence intervals for the parameters of the beta distribution. Here is an example using random numbers from the beta distribution with $a = 5$ and $b = 0.2$.

```
r = betarnd(5,0.2,100,1);
[phat, pci] = betafit(r)

phat =

    4.5330      0.2301


pci =

    2.8051      0.1771
    6.2610      0.2832
```

The MLE for the parameter, a is 4.5330 compared to the true value of 5. The 95% confidence interval for a goes from 2.8051 to 6.2610, which includes the true value.

Similarly the MLE for the parameter, b is 0.2301 compared to the true value of 0.2. The 95% confidence interval for b goes from 0.1771 to 0.2832, which also includes the true value.

Of course in this made-up example we know the "true value." In experimentation we do not.

Example and Plot. The shape of the beta distribution is quite variable depending on the values of the parameters, as illustrated by this plot.
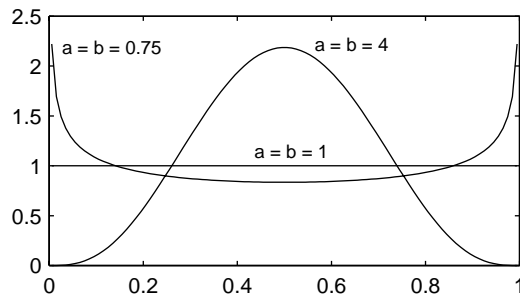
The constant pdf (the flat line) shows that the standard uniform distribution is a special case of the beta distribution.

Binomial Distribution

Background. The binomial distribution models the total number of successes in repeated trials from an infinite population under the following conditions:

- Only two outcomes are possible on each of n trials.
- The probability of success for each trial is constant.
- All trials are independent of each other.

James Bernoulli derived the binomial distribution in 1713 (*Ars Conjectandi*). Earlier, Blaise Pascal had considered the special case where $p = 1/2$.

Mathematical Definition. The binomial pdf is:

$$y = f(x|n, p) = \binom{n}{x} p^x q^{(1-x)} I_{(0, 1, \ldots, n)}(x)$$

$$where \ \binom{n}{x} = \frac{n!}{x!(n-x)!} \ and \ q = 1 - p$$

The binomial distribution is discrete. The pdf is nonzero for zero and the non-negative integers less than n.

Parameter Estimation. Suppose you are collecting data from a widget manufacturing process, and you record the number of widgets within specification in each batch of 100. You might be interested in the probability that an individual widget is within specification. Parameter estimation is the process of determining the parameter, p, of the binomial distribution that fits this data best in some sense.

One popular criterion of goodness is to maximize the likelihood function. The likelihood has the same form as the binomial pdf above. But for the pdf, the parameters (n and p) are known constants and the variable is x. The likelihood function reverses the roles of the variables. Here, the sample values (the xs) are already observed. So they are the fixed constants. The variables are the unknown parameters. Maximum likelihood estimation (MLE) involves calculating the value of p that give the highest likelihood given the particular set of data.

The function binofit returns the MLEs and confidence intervals for the parameters of the binomial distribution. Here is an example using random numbers from the binomial distribution with $n = 100$ and $p = 0.9$.

```
r = binornd(100, 0.9)

r =

    88

[phat, pci] = binofit(r, 100)

phat =

    0.8800


pci =

    0.7998
    0.9364
```

The MLE for the parameter, p is 0.8800 compared to the true value of 0.9. The 95% confidence interval for p goes from 0.7998 to 0.9364, which includes the true value.

Of course in this made-up example we know the "true value" of p.

Example and Plot. The following commands generate a plot of the binomial pdf for $n = 10$ and $p = 1/2$.

```
x = 0: 10;
y = binopdf(x, 10, 0.5);
plot(x, y, '+')
```
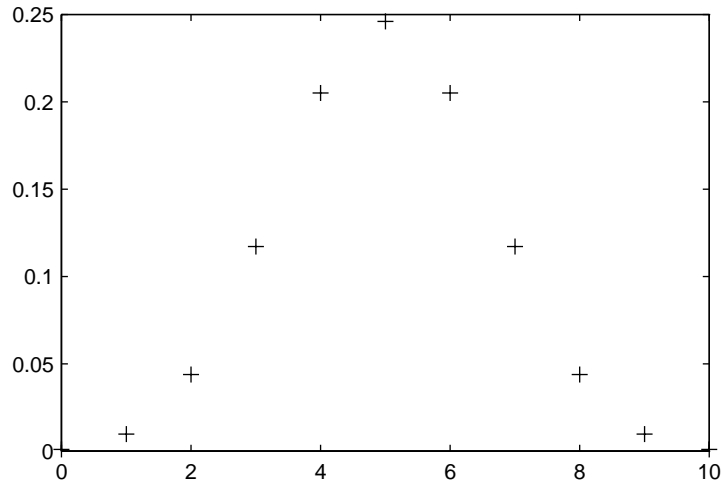

Chi-square (χ^2) Distribution

Background. The χ^2 distribution is a special case of the gamma distribution where $b = 2$, in the equation for gamma distribution below.

$$y = f(x|a, b) = \frac{1}{b^a \Gamma(a)} x^{a-1} e^{-\frac{x}{b}}$$

The χ^2 distribution gets special attention because of its importance in normal sampling theory. If a set of n observations are normally distributed with variance σ^2, and s^2 is the sample standard deviation, then:

$$\frac{(n-1)s^2}{\sigma^2} \sim \chi^2(n-1)$$

The Statistics Toolbox uses the above relationship to calculate confidence intervals for the estimate of the normal parameter σ^2 in the function `normfit`.

Mathematical Definition.   The χ^2 pdf is:

$$y = f(x \mid \nu) = \frac{x^{(\nu - 2)/2} e^{-x/2}}{2^{\frac{\nu}{2}} \Gamma(\nu/2)}$$

Example and Plot.   The χ^2 distribution is skewed to the right especially for few degrees of freedom (ν). The plot shows the χ^2 distribution with four degrees of freedom.

```
x = 0:0.2:15;
y = chi2pdf(x,4);
plot(x,y)
```
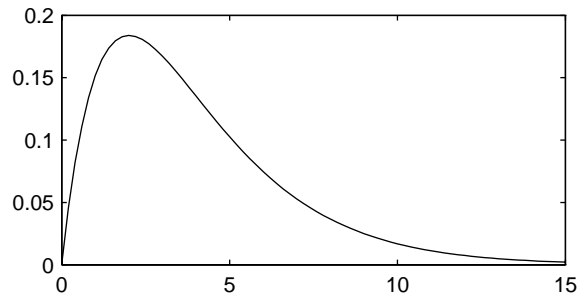

Noncentral Chi-square Distribution

Background.   The χ^2 distribution is actually a simple special case of the noncentral chi-square distribution. One way to generate random numbers with a χ^2 distribution (with ν degrees of freedom) is to sum the squares of ν standard normal random numbers (mean equal to zero.)

What if we allow the normally distributed quantities to have a mean other than zero? The sum of squares of these numbers yields the noncentral chi-square distribution. The noncentral chi-square distribution requires two parameters: the degrees of freedom and the noncentrality. The noncentrality parameter is the sum of the squared means of the normally distributed quantities.

The noncentral chi-square has scientific application in thermodynamics and signal processing. The literature in these areas may refer to it as the Ricean or generalized Rayleigh distribution.

Mathematical Definition.   There are many equivalent formulae for the noncentral chi-square distribution function. One formulation uses a modified Bessel function of the first kind. Another uses the generalized Laguerre polynomials. The Statistics Toolbox computes the cumulative distribution function values using a weighted sum of χ^2 probabilities with the weights equal to the probabilities of a Poisson distribution. The Poisson parameter is one-half of the noncentrality parameter of the noncentral chi-square.

$$F(x|\nu, \delta) = \sum_{j=0}^{\infty} \left(\frac{\left(\frac{1}{2}\delta\right)^j}{j!} e^{-\frac{\delta}{2}} \right) Pr[\chi^2_{\nu + 2j} \leq x]$$

Example and Plot.
```
x = (0: 0. 1: 10)';
p1 = ncx2pdf(x, 4, 2);
p = chi2pdf(x, 4);
plot(x, p, '--', x, p1, '-')
```
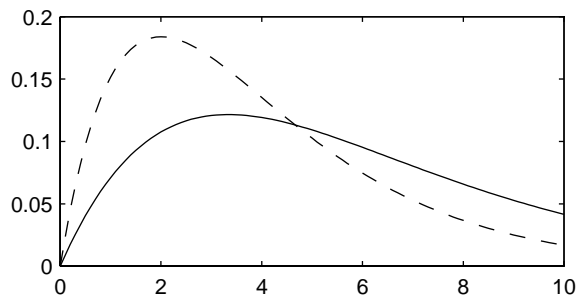

Discrete Uniform Distribution

Background.   The discrete uniform distribution is a simple distribution that puts equal weight on the integers from one to N.

Mathematical Definition. The discrete uniform pdf is:

$$y = f(x|N) = \frac{1}{N}I_{(1, ..., N)}(x)$$

Example and Plot. As for all discrete distributions, the cdf is a step function. The plot shows the discrete uniform cdf for $N = 10$.

```
x = 0: 10;
y = unidcdf(x, 10);
stairs(x, y)
set(gca, 'Xlim', [0 11])
```
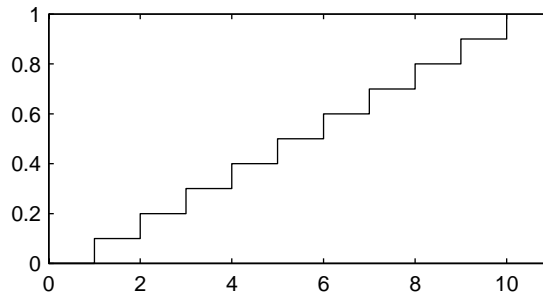

To pick a random sample of 10 from a list of 553 items:

```
numbers = unidrnd(553, 1, 10)

numbers =
    293    372      5    213     37    231    380    326    515    468
```

Exponential Distribution

Background. Like the chi-square, the exponential distribution is a special case of the gamma distribution (obtained by setting $a = 1$ in the equation below.)

$$y = f(x|a, b) = \frac{1}{b^a\Gamma(a)}x^{a-1}e^{-\frac{x}{b}}$$

The exponential distribution is special because of its utility in modeling events that occur randomly over time. The main application area is in studies of lifetimes.

Mathematical Definition. The exponential pdf is:

$$y = f(x|\mu) = \frac{1}{\mu} e^{-\frac{x}{\mu}}$$

Parameter Estimation. Suppose you are stress testing light bulbs and collecting data on their lifetimes. You assume that these lifetimes follow an exponential distribution. You want to know how long you can expect the average light bulb to last. Parameter estimation is the process of determining the parameters of the exponential distribution that fit this data best in some sense.

One popular criterion of goodness is to maximize the likelihood function. The likelihood has the same form as the beta pdf on the previous page. But for the pdf, the parameters are known constants and the variable is *x*. The likelihood function reverses the roles of the variables. Here, the sample values (the *x*s) are already observed. So they are the fixed constants. The variables are the unknown parameters. Maximum likelihood estimation (MLE) involves calculating the values of the parameters that give the highest likelihood given the particular set of data.

The function `expfit` returns the MLEs and confidence intervals for the parameters of the exponential distribution. Here is an example using random numbers from the exponential distribution with $\mu = 700$.

```
lifetimes = exprnd(700, 100, 1);
[muhat, muci] = expfit(lifetimes)
muhat =
  672.8207

muci =

  547.4338
  810.9437
```

The MLE for the parameter, μ is 672 compared to the true value of 700. The 95% confidence interval for μ goes from 547 to 811, which includes the true value.

In our life tests we do not know the true value of μ so it is nice to have a confidence interval on the parameter to give a range of likely values.

Example and Plot. For exponentially distributed lifetimes, the probability that an item will survive an extra unit of time is independent of the current age of the item. The example shows a specific case of this special property.

```
l = 10: 10: 60;
lpd = l+0. 1;
deltap = (expcdf(lpd, 50) -expcdf(l, 50)). /(1-expcdf(l, 50))

deltap =

    0. 0020    0. 0020    0. 0020    0. 0020    0. 0020    0. 0020
```

The plot shows the exponential pdf with its parameter (and mean), *lambda*, set to two.

```
x = 0: 0. 1: 10;
y = exppdf(x, 2);
plot(x, y)
```
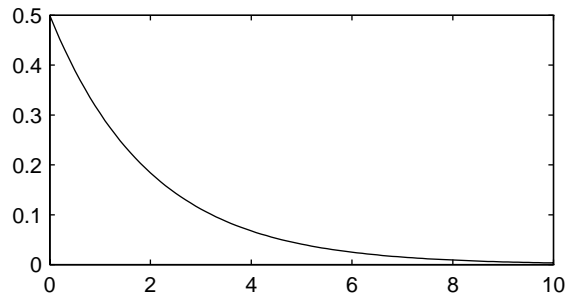

F Distribution

Background. The F distribution has a natural relationship with the chi-square distribution. If χ_1 and χ_2 are both chi-square with v_1 and v_2 degrees of freedom respectively, then the statistic, F is F distributed.

$$F(v_1, v_2) = \frac{\dfrac{\chi_1}{v_1}}{\dfrac{\chi_2}{v_2}}$$

The two parameters, v_1 and v_2, are the numerator and denominator degrees of freedom. That is, v_1 and v_2 are the number of independent pieces information used to calculate χ_1 and χ_2 respectively.

Mathematical Definition. The pdf for the F distribution is:

$$y = f(x|v_1,v_2) = \frac{\Gamma\left[\frac{(v_1 + v_2)}{2}\right]}{\Gamma\left(\frac{v_1}{2}\right)\Gamma\left(\frac{v_2}{2}\right)}\left(\frac{v_1}{v_2}\right)^{\frac{v_1}{2}}\frac{x^{\frac{v_1 - 2}{2}}}{\left[1 + \left(\frac{v_1}{v_2}\right)x\right]^{\frac{v_1 + v_2}{2}}}$$

Example and Plot. The most common application of the F distribution is in standard tests of hypotheses in analysis of variance and regression.

The plot shows that the F distribution exists on the positive real numbers and is skewed to the right.

```
x = 0:0.01:10;
y = fpdf(x, 5, 3);
plot(x, y)
```
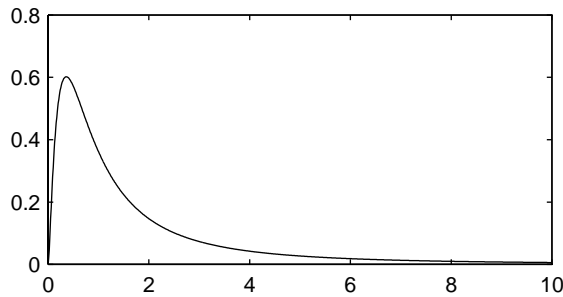

Noncentral F Distribution

Background. As with the χ^2 the F distribution is a special case of the noncentral F distribution. The F distribution is the result of taking the ratio of two χ^2 random variables each divided by its degrees of freedom.

If the numerator of the ratio is a noncentral chi-square random variable divided by its degrees of freedom, the resulting distribution is the noncentral F.

The main application of the noncentral F distribution is to calculate the power of a hypothesis test relative to a particular alternative.

Mathematical Definition.   Similarly to the noncentral chi-square, the Statistics Toolbox calculates noncentral F distribution probabilities as a weighted sum of incomplete beta function using Poisson probabilities as the weights.

$$F(x | \nu_1, \nu_2, \delta) = \sum_{j=0}^{\infty} \left(\frac{\left(\frac{1}{2}\delta\right)^j}{j!} e^{-\frac{\delta}{2}} \right) I \left(\frac{\nu_1 \cdot x}{\nu_2 + \nu_1 \cdot x} \middle| \frac{\nu_1}{2} + j, \frac{\nu_2}{2} \right)$$

where $I(x|a,b)$ is the incomplete beta function with parameters a and b.

Example and Plot.   x = (0.01: 0.1: 10.01)';
    p1 = ncfpdf(x, 5, 20, 10);
    p = fpdf(x, 5, 20);
    plot(x, p, '--', x, p1, '-')
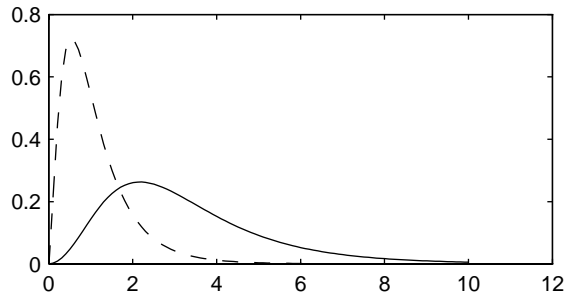
Gamma Distribution

Background.   The gamma distribution is a family of curves based on two parameters. The chi-square and exponential distributions, which are children of the gamma distribution, are one-parameter distributions that fix one of the two gamma parameters.

The gamma distribution has the following relationship with the incomplete gamma function:

$$\Gamma(x|a, b) = gammainc\left(\frac{x}{b}, a\right)$$

For $b = 1$ the functions are identical.

When a is large, the gamma distribution closely approximates a normal distribution with the advantage that the gamma distribution has density only for positive real numbers.

Mathematical Definition.   The gamma pdf is:

$$y = f(x|a, b) = \frac{1}{b^a \Gamma(a)} x^{a-1} e^{-\frac{x}{b}}$$

Parameter Estimation.   Suppose you are stress testing computer memory chips and collecting data on their lifetimes. You assume that these lifetimes follow a gamma distribution. You want to know how long you can expect the average computer memory chip to last. Parameter estimation is the process of determining the parameters of the gamma distribution that fit this data best in some sense.

One popular criterion of goodness is to maximize the likelihood function. The likelihood has the same form as the gamma pdf above. But for the pdf, the parameters are known constants and the variable is x. The likelihood function reverses the roles of the variables. Here, the sample values (the xs) are already observed. So they are the fixed constants. The variables are the unknown parameters. Maximum likelihood estimation (MLE) involves calculating the values of the parameters that give the highest likelihood given the particular set of data.

The function `gamfit` returns the MLEs and confidence intervals for the parameters of the gamma distribution. Here is an example using random numbers from the gamma distribution with $a = 10$ and $b = 5$.

```
lifetimes = gamrnd(10, 5, 100, 1);
[phat, pci] = gamfit(lifetimes)
phat =
    10.9821      4.7258

pci =

     7.4001      3.1543
    14.5640      6.2974
```

Note `phat(1)` = $\hat{a}$ and `phat(2)` = b. The MLE for the parameter, a is 10.98 compared to the true value of 10. The 95% confidence interval for a goes from 7.4 to 14.6, which includes the true value.

Similarly the MLE for the parameter, b is 4.7 compared to the true value of 5. The 95% confidence interval for b goes from 3.2 to 6.3, which also includes the true value.

In our life tests we do not know the true value of a and b so it is nice to have a confidence interval on the parameters to give a range of likely values.

Example and Plot.   In the example the gamma pdf is plotted with the solid line. The normal pdf has a dashed line type.

```
x = gaminv((0.005:0.01:0.995), 100, 10);
y = gampdf(x, 100, 10);
y1 = normpdf(x, 1000, 100);
plot(x, y, '-', x, y1, '-.')
```
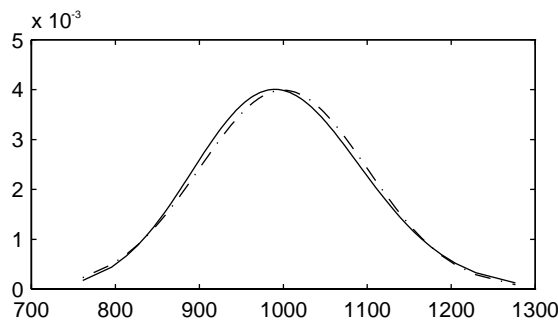
Geometric Distribution

Background.   The geometric distribution is discrete, existing only on the nonnegative integers. It is useful for modeling the runs of consecutive successes (or failures) in repeated independent trials of a system.

The geometric distribution models the number of successes before one failure in an independent succession of tests where each test results in success or failure.

Mathematical Definition.   The geometric pdf is:

$$y = f(x|p) = pq^x I_{(0, 1, K)}(x)$$
$$where \quad q = 1 - p$$

Example and Plot.   Suppose the probability of that a five year old battery failing in cold weather is 0.03. What is the probability of starting 25 consecutive days during a long cold snap?

```
1 - geocdf(25, 0. 03)

ans =

    0. 4530
```

The plot shows the cdf for this scenario.

```
x = 0: 25;
y = geocdf(x, 0. 03);
stairs(x, y)
```
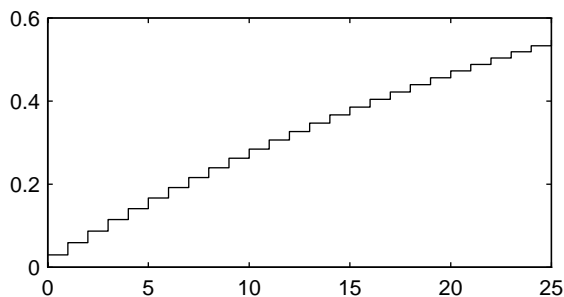
Hypergeometric Distribution

Background.   The hypergeometric distribution models the total number of successes in a fixed size sample drawn without replacement from a finite population.

The distribution is discrete, existing only for nonnegative integers less than the number of samples or the number of possible successes, whichever is greater.

The hypergeometric distribution differs from the binomial only in that the population is finite and the sampling from the population is without replacement.

The hypergeometric distribution has three parameters that have direct physical interpretation. M is the size of the population. K is the number of items with the desired characteristic in the population. n is the number of samples drawn. Sampling "without replacement" means that once a particular sample is chosen, it is removed from the relevant population for drawing the next sample.

Mathematical Definition.   The hypergeometric pdf is:

$$y = f(x|M, K, n) = \frac{\binom{K}{x}\binom{M-K}{n-x}}{\binom{M}{n}}$$

Example and Plot. The plot shows the cdf of an experiment taking 20 samples from a group of 1000 where there are 50 items of the desired type.

```
x = 0: 10;
y = hygecdf(x, 1000, 50, 20);
stairs(x, y)
```
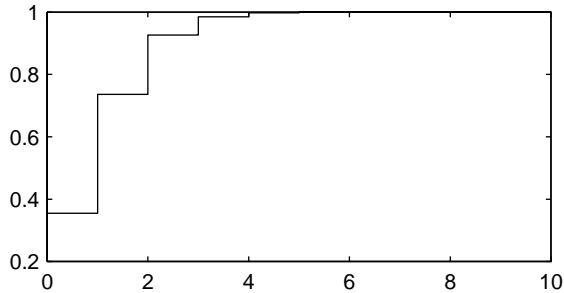

Lognormal Distribution

Background. The normal and lognormal distributions are closely related. If X is distributed lognormal with parameters μ and σ^2, then lnX is distributed normal with parameters μ and σ^2.

The lognormal distribution is applicable when the quantity of interest must be positive, since lnX exists only when the random variable X is positive. Economists often model the distribution of income using a lognormal distribution.

Mathematical Definition. The lognormal pdf is:

$$y = f(x|\mu, \sigma) = \frac{1}{x\sigma\sqrt{2\pi}} e^{\frac{-(\ln x - \mu)^2}{2\sigma^2}}$$

Example and Plot. Suppose the income of a family of four in the United States follows a lognormal distribution with $\mu = \log(20{,}000)$ and $\sigma^2 = 1.0$. Plot the income density.

```
x = (10: 1000: 125010)';
y=lognpdf(x, log(20000), 1.0);
plot(x, y)
set(gca, 'Xtick', [0 30000 60000 90000 120000 ])
set(gca, 'Xticklabels', str2mat('0', '$30,000', '$60,000', ...
'$90,000', '$120,000'))
```
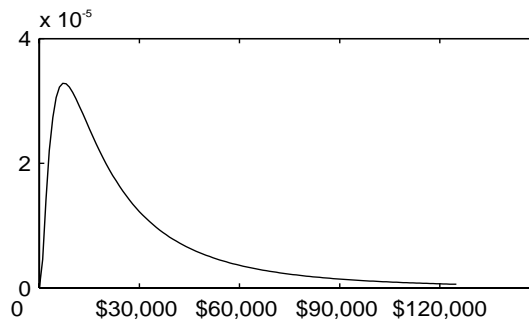

Negative Binomial Distribution

Background. The geometric distribution is a special case of the negative binomial distribution (also called the Pascal distribution). The geometric distribution models the number of successes before one failure in an independent succession of tests where each test results in success or failure.

In the negative binomial distribution the number of failures is a parameter of the distribution. The parameters are the probability of success, p, and the number of failures, r.

Mathematical Definition. The negative binomial pdf is:

$$y = f(x|r, p) = \binom{r + x - 1}{x} p^r q^x I_{(0, 1, \ldots)}(x)$$

$$where \ q = 1 - p$$

Example and Plot.

```
x = (0:10);
y = nbinpdf(x, 3, 0.5);
plot(x, y, '+')
set(gca, 'XLim', [-0.5, 10.5])
```
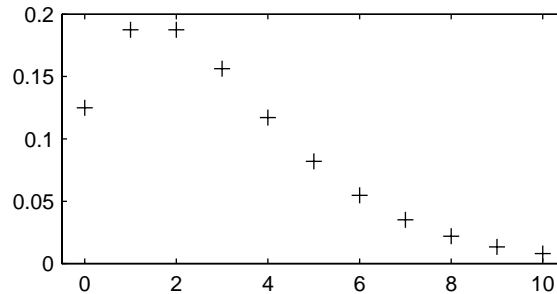

Normal Distribution

Background.   The normal distribution is a two parameter family of curves. The first parameter, μ, is the mean. The second, σ, is the standard deviation. The standard normal distribution (written $\Phi(x)$) sets μ to zero and σ to one.

$\Phi(x)$ is functionally related to the error function, *erf*.

$$erf(x) = 2\Phi(x\sqrt{2}) - 1$$

The first use of the normal distribution was as a continuous approximation to the binomial.

The usual justification for using the normal distribution for modeling is the Central Limit Theorem which states (roughly) that the sum of independent samples from any distribution with finite mean and variance converges to the normal distribution as the sample size goes to infinity.

Mathematical Definition. The normal pdf is:

$$y = f(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{\frac{-(x-\mu)^2}{2\sigma^2}}$$

Parameter Estimation. One of the first applications of the normal distribution in data analysis was modeling the height of school children. Suppose we wish to estimate the mean, μ, and the variance, σ^2, of all the 4th graders in the United States.

We have already introduced maximum likelihood estimators (MLEs). Another desirable criterion in a statistical estimator is unbiasedness. A statistic is unbiased if the expected value of the statistic is equal to the parameter being estimated. MLEs are not always unbiased. For any data sample, there may be more than one unbiased estimator of the parameters of the parent distribution of the sample. For instance, every sample value is an unbiased estimate of the parameter μ of a normal distribution. The minimum variance unbiased estimator (MVUE) is the statistic that has the minimum variance of all unbiased estimators of a parameter.

The minimum variance unbiased estimators of the parameters, μ and σ^2 for the normal distribution are the sample average and variance. The sample average is also the maximum likelihood estimator for μ. There are two common textbook formulae for the variance.

They are:

$$1) \quad s^2 = \frac{1}{n} \sum_{i=1}^{n} (x_i - \bar{x})^2$$

$$2) \quad s^2 = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x})^2$$

$$\text{where} \quad \bar{x} = \sum_{i=1}^{n} \frac{x_i}{n}$$

Equation 1 is the maximum likelihood estimator for σ^2, and equation 2 is the minimum variance unbiased estimator.

The function normfit returns the MVUEs and confidence intervals for μ and σ². Here is a playful example modeling the "heights" (inches) of a randomly chosen 4th grade class.

```
height = normrnd(50, 2, 30, 1);  % Simulate heights.
[mu, s, muci, sci] = normfit(height)
mu =
    50.2025
s =
     1.7946
muci =
    49.5210
    50.8841
sci =
     1.4292
     2.4125
```

Example and Plot.   The plot shows the "bell" curve of the standard normal pdf μ = 0, σ = 1.
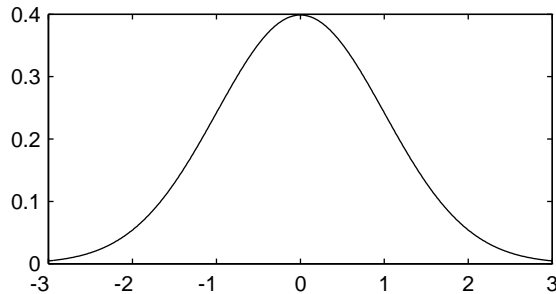
Poisson Distribution

Background.   The Poisson distribution is appropriate for applications that involve counting the number of times a random event occurs in a given amount of time, distance, area, etc. Sample applications that involve Poisson distributions include the number of Geiger counter clicks per second, the number of people walking into a store in an hour, and the number of flaws per 1000 feet of video tape.

The Poisson distribution is a one parameter discrete distribution that takes nonnegative integer values. The parameter, λ, is both the mean and the vari-

ance of the distribution. Thus, as the size of the numbers in a particular sample of Poisson random numbers gets larger, so does the variability of the numbers.

As Poisson (1837) showed, the Poisson distribution is the limiting case of a binomial distribution where N approaches infinity and p goes to zero while $Np = \lambda$.

The Poisson and exponential distributions are related. If the number of counts follows the Poisson distribution, then the interval between individual counts follows the exponential distribution.

Mathematical Definition. The Poisson pdf is:

$$y = f(x|\lambda) = \frac{\lambda^x}{x!} e^{-\lambda} I_{(0, 1, K)}(x)$$

Parameter Estimation. The MLE and the MVUE of the Poisson parameter, λ, is the sample mean. The sum of independent Poisson random variables is also Poisson with parameter equal to the sum of the individual parameters. The Statistics Toolbox makes use of this fact to calculate confidence intervals on λ. As λ gets large the Poisson distribution can be approximated by a normal distribution with $\mu = \lambda$ and $\sigma^2 = \lambda$. The Statistics Toolbox uses this approximation for calculating confidence intervals for values of λ greater than 100.

Example and Plot. The plot shows the probability for each non-negative integer when $\lambda = 5$.

```
x = 0: 15;
y = poisspdf(x, 5);
plot(x, y, '+')
```


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Example and Plot. The plot shows the probability for each non-negative integer when $\lambda = 5$.

```
x = 0: 15;
y = poisspdf(x, 5);
plot(x, y, '+')
```

Rayleigh Distribution

Background. The Rayleigh distribution is a special case of the Weibull distribution substituting 2 for the parameter p in the equation below:

$$y = f\left(x \middle| \frac{b^2}{2}, p\right) = \frac{b^2}{2} p^{p-1} e^{-\frac{b^2}{2} x^p} I_{(0, \infty)}(x)$$

If the velocity of a particle in the x and y directions are two independent normal random variables with zero means and equal variances, then the distance the particle travels per unit time is distributed Rayleigh.

Mathematical Definition. The Rayleigh pdf is:

$$y = f(x|b) = \frac{x}{b^2} e^{\left(\frac{-x^2}{2 b^2}\right)}$$

Example and Plot.
```
x = [0: 0. 01: 2];
p = raylpdf(x, 0. 5);
plot(x, p)
```
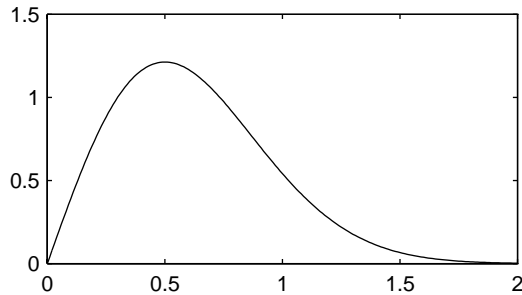

Parameter Estimation. The MLE of the Rayleigh parameter is:

$$b = \frac{\sum\limits_{i=1}^{n} x_i^2}{2 n}$$

Student's t Distribution

Background. The t distribution is a family of curves depending on a single parameter v (the degrees of freedom). As v goes to infinity the t distribution converges to the standard normal distribution.

W. S. Gossett (1908) discovered the distribution through his work at Guinness brewery. At that time, Guinness did not allow its staff to publish, so Gossett used the pseudonym Student.

If x and s are the mean and standard deviation of an independent random sample of size n from a normal distribution with mean μ, and $\sigma^2 = n$, then:

$$t(v) = \frac{x - \mu}{s}$$

$$v = n - 1$$

Mathematical Definition.   Student's t pdf is:

$$y = f(x|v) = \frac{\Gamma\left(\frac{v+1}{2}\right)}{\Gamma\left(\frac{v}{2}\right)} \frac{1}{\sqrt{v\pi}} \frac{1}{\left(1 + \frac{x^2}{v}\right)^{\frac{v+1}{2}}}$$

Example and Plot. The plot compares the t distribution with $v = 5$ (solid line) to the shorter tailed standard normal distribution (dashed line).

```
x = -5: 0. 1: 5;
y = tpdf(x, 5);
z = normpdf(x, 0, 1);
plot(x, y, '-', x, z, '-. ')
```
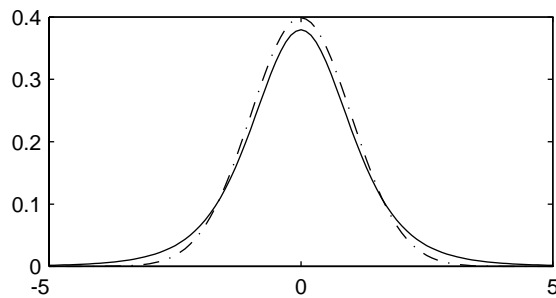
Noncentral t Distribution

Background. The noncentral t distribution is a generalization of the familiar Student's t distribution.

If x and s are the mean and standard deviation of an independent random sample of size n from a normal distribution with mean μ, and $\sigma^2 = n$, then:

$$t(\nu) = \frac{x - \mu}{s}$$

$$\nu = n - 1$$

Suppose that the mean of the normal distribution is not μ. Then the ratio has the noncentral t distribution. The noncentrality parameter is the difference between the sample mean and μ.

The noncentral t distribution allows us to determine the probability that we would detect a difference between x and μ in a t test. This probability is the *power* of the test. As x–μ increases, the power of a test also increases.

Mathematical Definition. The most general representation of the noncentral t distribution is quite complicated. Johnson and Kotz (1970) give a formula for the probability that a noncentral t variate falls in the range [–t, t].

$$Pr((-t) < x < t|(\nu, \delta)) = \sum_{j=0}^{\infty} \left(\frac{\left(\frac{1}{2}\delta^2 \right)^j}{j!} e^{-\frac{\delta^2}{2}} \right) \boldsymbol{I} \left(\frac{x^2}{\nu + x^2} \Big| \frac{1}{2} + j, \frac{\nu}{2} \right)$$

where $I(x|a,b)$ is the incomplete beta function with parameters a and b.

Example and Plot.

```
x = (-5: 0. 1: 5)';
p1 = nctcdf(x, 10, 1);
p = tcdf(x, 10);
plot(x, p, '--', x, p1, '-')
```
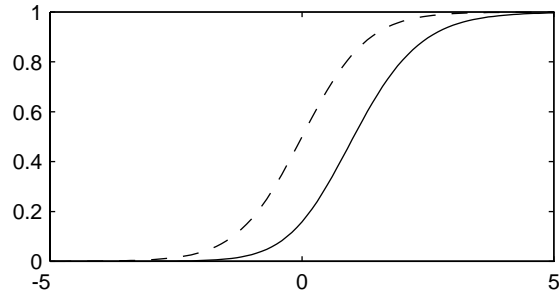

Uniform (Continuous) Distribution

Background.   The uniform distribution (also called rectangular) has a constant pdf between its two parameters a, the minimum, and b, the maximum. The standard uniform distribution ($a = 0$ and $b = 1$) is a special case of the beta distribution, setting both of its parameters to one.

The uniform distribution is appropriate for representing the distribution of round-off errors in values tabulated to a particular number of decimal places.

Mathematical Definition.   The uniform cdf is:

$$p = F(x|a, b) = \frac{x - a}{b - a} I_{[a, b]}(x)$$

Parameter Estimation.   The sample minimum and maximum are the MLEs of a and b respectively.

Example and Plot.   The example illustrates the inversion method for generating normal random numbers using `rand` and `norminv`. Note that the MATLAB function, `randn`, does not use inversion since it is not efficient for this case.

```
u = rand(1000, 1);
x = norminv(u, 0, 1);
hist(x)
```
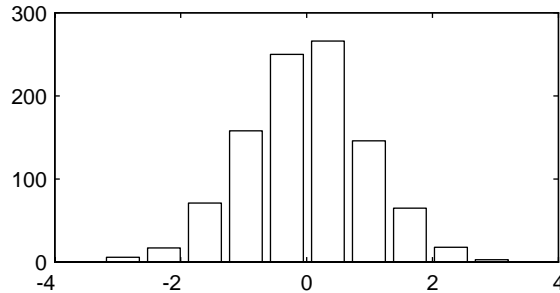

Weibull Distribution

Background.   Waloddi Weibull (1939) offered the distribution that bears his name as an appropriate analytical tool for modeling breaking strength of materials. Current usage also includes reliability and lifetime modeling. The Weibull distribution is more flexible than the exponential for these purposes.

To see why, consider the hazard rate function (instantaneous failure rate). If *f(t)* and *F(t)* are the pdf and cdf of a distribution, then the hazard rate is:

$$h(t) = \frac{f(t)}{1 - F(t)}$$

Substituting the pdf and cdf of the exponential distribution for *f(t)* and *F(t)* above yields a constant. The example on the next page shows that the hazard rate for the Weibull distribution can vary.

Mathematical Definition.   The Weibull pdf is:

$$y = f(x|a, b) = abx^{b-1}e^{-ax^b}I_{(0,\infty)}(x)$$

Parameter Estimation.   Suppose we wish to model the tensile strength of a thin fil-
ament using the Weibull distribution. The function weibfit give MLEs and
confidence intervals for the Weibull parameters.

```
strength = weibrnd(0.5, 2, 100, 1); % Simulated strengths.
[p, ci] = weibfit(strength)

p =

    0.4746    1.9582


ci =

    0.3851    1.6598
    0.5641    2.2565
```

The default 95% confidence interval for each parameter contains the "true"
value.

Example and Plot.   The exponential distribution has a constant hazard function,
which is not generally the case for the Weibull distribution.

The plot shows the hazard functions for exponential (dashed line) and Weibull
(solid line) distributions having the same mean life. The Weibull hazard rate
here increases with age (a reasonable assumption).

```
t = 0:0.1:3;
h1 = exppdf(t,0.6267)./(1 - expcdf(t,0.6267));
h2 = weibpdf(t,2,2)./(1 - weibcdf(t,2,2));
plot(t,h1,'--',t,h2,'-')
```
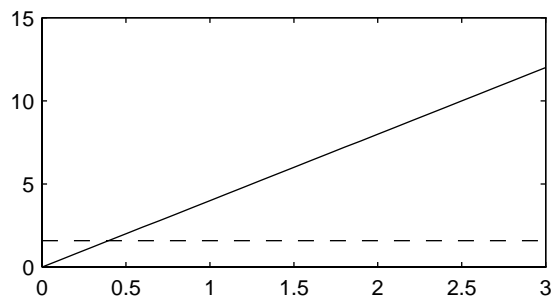
Descriptive Statistics

Data samples can have thousands (even millions) of values. Descriptive statistics are a way to summarize this data into a few numbers that contain most of the relevant information.

Measures of Central Tendency (Location)

The purpose of measures of central tendency is to locate the data values on the number line. In fact, another term for these statistics is measures of location.

The table gives the function names and descriptions.

Measures of Location	
geomean	Geometric Mean.
harmmean	Harmonic Mean.
mean	Arithmetic average (in MATLAB).
median	50th percentile (in MATLAB).
trimmean	Trimmed Mean.

The average is a simple and popular estimate of location. If the data sample comes from a normal distribution, then the sample average is also optimal (minimum variance unbiased estimate of μ).

Unfortunately, outliers, data entry errors, or glitches exist in almost all real data. The sample average is sensitive to these problems. One bad data value can move the average away from the center of the rest of the data by an arbitrarily large distance.

The median and trimmed mean are two measures that are resistant (robust) to outliers. The median is the 50th percentile of the sample, which will only change slightly if you add a large perturbation to any value. The idea behind the trimmed mean is to ignore a small percentage of the highest and lowest values of a sample for determining the center of the sample.

The geometric mean and harmonic mean, like the average, are not robust to outliers. They are useful when the sample is distributed lognormal or heavily skewed.

The example shows the behavior of the measures of location for a sample with one outlier.

```
x = [ones(1,6) 100]

x =

  1     1     1     1     1     1     100

locate = [geomean(x) harmmean(x) mean(x) median(x) ...
trimmean(x,25)]

locate =

    1.9307    1.1647    15.1429    1.0000    1.0000
```

You can see that the mean is far from any data value because of the influence of the outlier. The median and trimmed mean ignore the outlying value and describe the location of the rest of the data values.

Measures of Dispersion

The purpose of measures of dispersion is to find out how spread out the data values are on the number line. Another term for these statistics is measures of spread.

The table gives the function names and descriptions.

Measures of Dispersion	
iqr	Interquartile Range.
mad	Mean Absolute Deviation.
range	Range.
std	Standard Deviation (in MATLAB).
var	Variance.

The range (the difference between the maximum and minimum values) is the simplest measure of spread. But if there is an outlier in the data, it will be the minimum or maximum value. Thus, the range is not robust to outliers.

The standard deviation and the variance are popular measures of spread that are optimal for normally distributed samples. The sample variance is the minimum variance unbiased estimator of the normal parameter σ^2. The standard deviation is the square root of the variance and has the desirable property of being in the same units as the data. That is, if the data is in meters the standard deviation is in meters as well. The variance is in meters^2, which is more difficult to interpret.

Neither the standard deviation nor the variance is robust to outliers. A data value that is separate from the body of the data can increase the value of the statistics by an arbitrarily large amount.

The mean absolute deviation (mad) is also sensitive to outliers. But the mad does not move quite as much as the standard deviation or variance in response to bad data.

The interquartile range (iqr) is the difference between the 75th and 25th percentile of the data. Since only the middle 50% of the data affects this measure, it is robust to outliers.

The example below shows the behavior of the measures of dispersion for a sample with one outlier.

```
x = [ones(1, 6)  100]

x =

      1     1     1     1     1     1    100

stats = [iqr(x)  mad(x)  range(x)  std(x)]

stats =

      0    24.2449    99.0000    37.4185
```

Functions for Data with Missing Values (NaNs)

Most real-world datasets have one or more missing elements. It is convenient to code missing entries in a matrix as NaN (Not a Number.)

Here is a simple example:

```
m = magic(3);
m([1 5 9]) = [NaN NaN NaN]

m =

    NaN     1     6
      3   NaN     7
      4     9   NaN
```

Simply removing any row with a NaN in it would leave us with nothing, But any arithmetic operation involving NaN yields NaN as below.

```
sum(m)

ans =

    NaN   NaN   NaN
```

The NaN functions support the tabled arithmetic operations ignoring NaN.

```
nansum(m)

ans =

      7    10    13
```

NaN functions	
nanmax	Maximum ignoring NaNs.
nanmean	Mean ignoring NaNs.
nanmedian	Median ignoring NaNs.
nanmin	Minimum ignoring NaNs.
nanstd	Standard deviation ignoring NaNs.
nansum	Sum ignoring NaNs.

Percentiles and Graphical Descriptions

Trying to describe a data sample with two numbers, a measure of location and a measure of spread, is frugal but may be misleading.

Another option is to compute a reasonable number of the sample percentiles. This provides information about the shape of the data as well as its location and spread.

The example shows the result of looking at every quartile of a sample containing a mixture of two distributions.

```
x = [normrnd(4, 1, 1, 100)  normrnd(6, 0. 5, 1, 200)];
p = 100*(0: 0. 25: 1);
y = prctile(x, p);
z = [p;  y']

z =

        0    25. 0000    50. 0000    75. 0000   100. 0000
   1. 5172     4. 6842     5. 6706     6. 1804     7. 6035
```

Compare the first two quantiles to the rest.

The box plot is a graph for descriptive statistics. The graph below is a box plot of the data above.
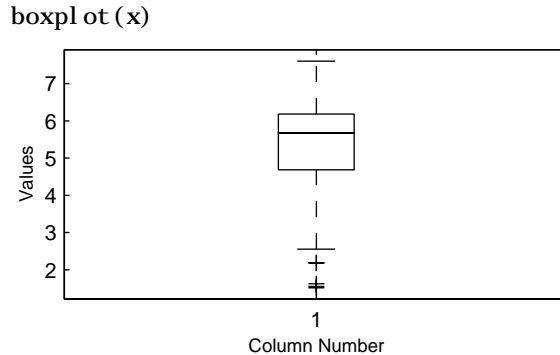
boxplot(x)

The long lower tail and plus signs show the lack of symmetry in the sample values. For more information on box plots see page 1-88.

The histogram is a complementary graph.

hist(x)
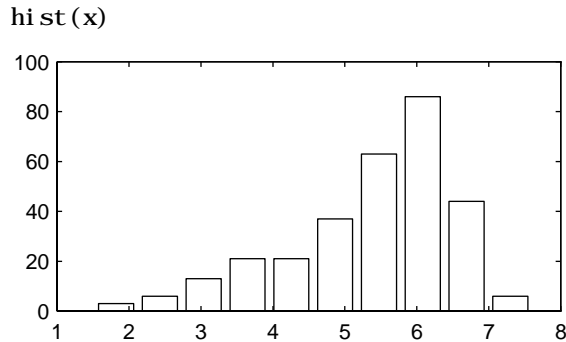
The Bootstrap

In the last decade the statistical literature has examined the properties of resampling as a means to acquire information about the uncertainty of statistical estimators.

The bootstrap is a procedure that involves choosing random samples *with replacement* from a data set and analyzing each sample the same way. Sampling *with replacement* means that every sample is returned to the data set after sampling. So a particular data point from the original data set could

appear multiple times in a given bootstrap sample. The number of elements in each bootstrap sample equals the number of elements in the original data set. The range of sample estimates we obtain allows us to establish the uncertainty of the quantity we are estimating.

Here is an example taken from Efron and Tibshirani (1993) comparing LSAT scores and subsequent law school GPA for a sample of 15 law schools.

```
load lawdata
plot(lsat, gpa, '+')
lsline
```
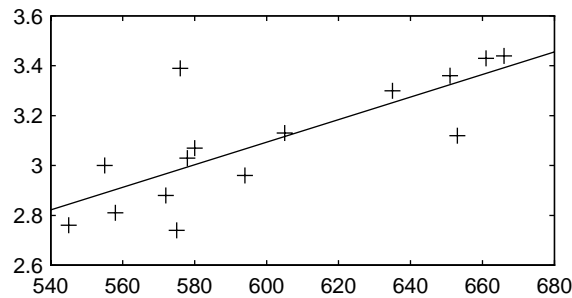

The least squares fit line indicates that higher LSAT scores go with higher law school GPAs. But how sure are we of this conclusion? The plot gives us some intuition but nothing quantitative.

We can calculate the correlation coefficient of the variables using the corrcoef function.

```
rhohat = corrcoef(lsat, gpa)

rhohat =

    1.0000    0.7764
    0.7764    1.0000
```

Now we have a number, 0.7764, describing the positive connection between LSAT and GPA, but though 0.7764 may seem large, we still do not know if it is statistically significant.

Using the bootstrp function we can resample the lsat and gpa vectors as many times as we like and consider the variation in the resulting correlation coefficients.

Here is an example:

```
rhos1000 = bootstrp(1000,'corrcoef',lsat,gpa);
```

This command resamples the lsat and gpa vectors 1000 times and computes the corrcoef function on each sample. Here is a histogram of the result.

```
hist(rhos1000(:,2),30)
```
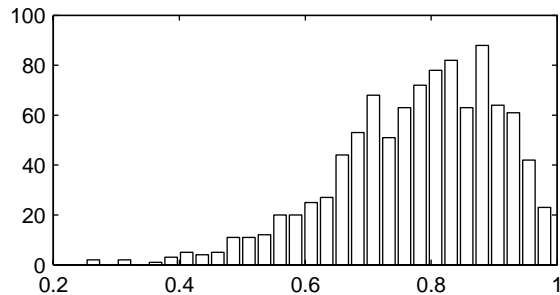

Nearly all the estimates lie on the interval [0.4 1.0].

This is strong quantitative evidence that LSAT and subsequent GPA are positively correlated. Moreover, it does not require us to make any strong assumptions about the probability distribution of the correlation coefficient.

Linear Models

Linear models are problems that take the form:

$$y = X\beta + \varepsilon$$

where

- y is an n by 1 vector of observations
- X is the n by p design matrix for the model
- β is a p by 1 vector of parameters
- ε is an n by 1 vector of random disturbances.

One-way analysis of variance (ANOVA), two-way ANOVA, polynomial regression, and multiple linear regression are specific cases of the linear model.

One-way Analysis of Variance (ANOVA)

The purpose of a one-way ANOVA is to find out whether data from several groups have a common mean. That is, to determine whether the groups are actually different in the measured characteristic.

One-way ANOVA is a simple special case of the linear model. The one-way ANOVA form of the model is:

$$y_{ij} = \alpha_{.j} + \varepsilon_{ij}$$

where

- y_{ij} is a matrix of observations
- $\alpha_{.j}$ is a matrix whose columns are the group means (The "dot j" notation means that α applies to all rows of the jth column.)
- ε_{ij} is a matrix of random disturbances.

The model posits that the columns of y are a constant plus a random disturbance. You want to know if the constants are all the same.

The data below comes from a study of bacteria counts in shipments of milk Hogg and Ledolter (1987). The columns of the matrix hogg represent different

shipments. The rows are bacteria counts from cartons of milk chosen randomly from each shipment. Do some shipments have higher counts than others?

```
load hogg
p = anova1(hogg)

p =

    1.1971e-04

hogg

hogg =

        24     14     11      7     19
        15      7      9      7     24
        21     12      7      4     19
        27     17     13      7     15
        33     14     12     12     10
        23     16     18     18     20
```

The standard ANOVA table has columns for the sums of squares, degrees of freedom, mean squares (SS/df), and F statistic.

ANOVA Table

Source	SS	df	MS	F
Columns	803	4	200.7	9.008
Error	557.2	25	22.29	
Total	1360	29		

You can use the F statistic to do a hypothesis test to find out if the bacteria counts are the same. anova1 returns the p-value from this hypothesis test.

In this case the p-value is about 0.0001, a very small value. This is a strong indication that the bacteria counts from the different tankers are not the same. An F statistic as extreme as the observed F would occur by chance only once in 10,000 times if the counts were truly equal.

The p-value returned by anova1 depends on assumptions about the random disturbances in the model equation. For the p-value to be correct, these disturbances need to be independent, normally distributed and have constant variance.

You can get some graphic assurance that the means are different by looking at the box plots in the second figure window displayed by anova1.
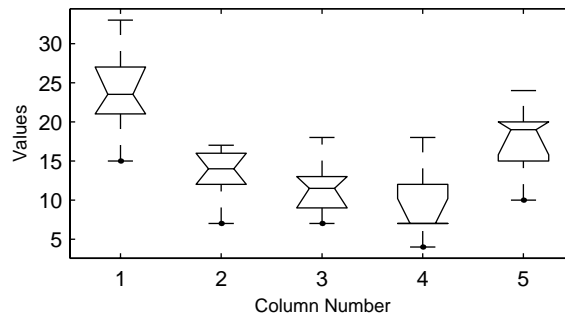
Since the notches in the box plots do not all overlap, this is strong confirming evidence that the column means are not equal.

Two-way Analysis of Variance (ANOVA)

The purpose of two-way ANOVA is to find out whether data from several groups have a common mean. One-way ANOVA and two-way ANOVA differ in that the groups in two-way ANOVA have two categories of defining characteristics instead of one.

Suppose an automobile company has two factories that both make three models of car. It is reasonable to ask if the gas mileage in the cars varies from factory to factory as well as model to model.

There could be an overall difference in mileage due to a difference in the production methods between factories. There is probably a difference in the mileage of the different models (irrespective of the factory) due to differences in design specifications. These effects are called *additive*.

Finally, a factory might make high mileage cars in one model (perhaps because of a superior production line), but not be different from the other factory for other models. This effect is called an *interaction*. It is impossible to detect an interaction unless there are duplicate observations for some combination of factory and car model.

Two-way ANOVA is a special case of the linear model. The two-way ANOVA form of the model is:

$$y_{ijk} = \mu + \alpha_{.j} + \beta_{i.} + \gamma_{ij} + \varepsilon_{ijk}$$

where

- y_{ijk} is a matrix of observations,
- μ is a constant matrix of the overall mean,
- $\alpha_{.j}$ is a matrix whose columns are the group means (the rows of α sum to 0),
- $\beta_{i.}$ is a matrix whose rows are the group means (the columns of β sum to 0),
- γ_{ij} is a matrix of interactions (the rows and columns of γ sum to zero),
- ε_{ijk} is a matrix of random disturbances.

The purpose of the example is to determine the effect of car model and factory on the mileage rating of cars.

```
load mileage
mileage

mileage =

    33.3000    34.5000    37.4000
    33.4000    34.8000    36.8000
    32.9000    33.8000    37.6000
    32.6000    33.4000    36.6000
    32.5000    33.7000    37.0000
    33.0000    33.9000    36.7000

cars = 3;
p = anova2(mileage, cars)

p =

     0.0000     0.0039     0.8411
```

There are three models of cars (columns) and two factories (rows). The reason there are six rows instead of two is that each factory provides three cars of each model for the study. The data from the first factory is in the first three rows, and the data from the second factory is in the last three rows.

The standard ANOVA table has columns for the sums of squares, degrees of freedom, mean squares (SS/df), and F statistics.

ANOVA Table

| Source	SS	df	MS	F
Columns	53.35	2	26.68	234.2
Rows	1.445	1	1.445	12.69
Interaction	0.04	2	0.02	0.1756
Error	1.367	12	0.1139	
Total	56.2	17		

You can use the F statistics to do hypotheses tests to find out if the mileage is the same across models, factories, and model-factory pairs (after adjusting for the additive effects). anova2 returns the p-value from these tests.

The p-value for the model effect is zero to four decimal places. This is a strong indication that the mileage varies from one model to another. An F statistic as extreme as the observed F would occur by chance less than once in 10,000 times if the gas mileage were truly equal from model to model.

The p-value for the factory effect is 0.0039, which is also highly significant. This indicates that one factory is out-performing the other in the gas mileage of the cars it produces. The observed p-value indicates that an F statistic as extreme as the observed F would occur by chance about four out of 1000 times if the gas mileage were truly equal from factory to factory.

There does not appear to be any interaction between factories and models. The p-value, 0.8411, means that the observed result is quite likely (84 out 100 times) given that there is no interaction.

The p-values returned by anova2 depend on assumptions about the random disturbances in the model equation. For the p-values to be correct these disturbances need to be independent, normally distributed and have constant variance.

Multiple Linear Regression

The purpose of multiple linear regression is to establish a quantitative relationship between a group of predictor variables (the columns of X) and a response, y. This relationship is useful for

- Understanding which predictors have the most effect.
- Knowing the direction of the effect (i.e., increasing x increases/decreases y).
- Using the model to predict future values of the response when only the predictors are currently known.

The linear model takes its common form:

$$y = X\beta + \varepsilon$$

- y is an n by 1 vector of observations.
- X is an n by p matrix of regressors.
- β is a p by 1 vector of parameters.
- ε is an n by 1 vector of random disturbances.

The solution to the problem is a vector, b, which estimates the unknown vector of parameters, β. The least-squares solution is :

$$b = \hat{\beta} = (X'X)^{-1}X'y$$

This equation is useful for developing later statistical formulas, but has poor numeric properties. `regress` uses QR decomposition of X followed by the backslash operator to compute b. The QR decomposition is not necessary for computing b, but the matrix, R, is useful for computing confidence intervals.

You can plug b back into the model formula to get the predicted y values at the data points.

$$\hat{y} = Xb = Hy$$
$$H = X(X'X)^{-1}X'$$

Statisticians use a hat (circumflex) over a letter to denote an estimate of a parameter or a prediction from a model. The projection matrix H, is called the hat matrix, because it puts the "hat" on y.

The residuals are the difference between the observed and predicted y values.

$$r = y - \hat{y} = (I - H)y$$

The residuals are useful for detecting failures in the model assumptions, since they correspond to the errors, ε, in the model equation. By assumption, these errors each have independent normal distributions with mean zero and a constant variance.

The residuals, however, are correlated and have variances that depend on the locations of the data points. It is a common practice to scale ("Studentize") the residuals so they all have the same variance.

In the equation below, the scaled residual, t_i, has a Student's t distribution with *(n–p)* degrees of freedom.

$$t_i = \frac{r_i}{\hat{\sigma}_{(i)}\sqrt{1 - h_i}}$$

$$where \ \hat{\sigma}^2_{(i)} = \frac{\|r\|^2}{n - p - 1} - \frac{r_i^2}{(n - p - 1)(1 - h_i)}$$

- t_i is the scaled residual for the *i*th data point
- r_i is the raw residual for the *i*th data point
- n is the sample size
- p is the number of parameters in the model
- h_i is the *i*th diagonal element of H

The left-hand side of the second equation is the estimate of the variance of the errors excluding the *i*th data point from the calculation.

A hypothesis test for outliers involves comparing t_i with the critical values of the t distribution. If t_i is large, this casts doubt on the assumption that this residual has the same variance as the others.

A confidence interval for the mean of each error is:

$$c_i = r_i \pm t_{\left(1 - \frac{\alpha}{2}, \nu\right)} \hat{\sigma}_{(i)}\sqrt{1 - h_i}$$

Confidence intervals that do not include zero are equivalent to rejecting the hypothesis (at a significance probability of α) that the residual mean is zero.

Such confidence intervals are good evidence that the observation is an outlier for the given model.

Example

The example comes from Chatterjee and Hadi (1986) in a paper on regression diagnostics. The dataset (originally from Moore (1975)) has five predictor variables and one response.

```
load moore
X = [ones(size(moore, 1), 1)  moore(:, 1:5)];
```

The matrix, X, has a column of ones, then one column of values for each of the five predictor variables. The column of ones is necessary for estimating the *y*-intercept of the linear model.

```
y = moore(:, 6);
[b, bint, r, rint, stats] = regress(y, X);
```

The *y*-intercept is b(1), which corresponds to the column index of the column of ones.

```
stats

stats =

    0.8107    11.9886     0.0001
```

The elements of the vector stats are the regression R^2 statistic, the F statistic (for the hypothesis test that all the regression coefficients are zero), and the p-value associated with this F statistic.

R^2 is 0.8107 indicating the model accounts for over 80% of the variability in the observations. The F statistic of about 12 and its p-value of 0.0001 indicate that it is highly unlikely that all of the regression coefficients are zero.

`rcoplot(r, rint)`
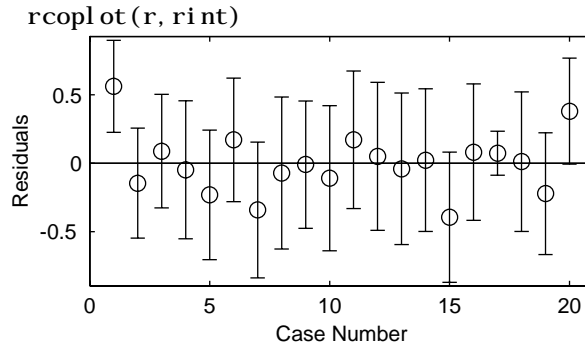
The plot shows the residuals plotted in case order (by row). The 95% confidence intervals about these residuals are plotted as error bars. The first observation is an outlier since its error bar does not cross the zero reference line.

Quadratic Response Surface Models

Response Surface Methodology (RSM) is a tool for understanding the quantitative relationship between multiple input variables and one output variable.

Consider one output, *z*, as a polynomial function of two inputs, *x* and *y*. *z = f(x,y)* describes a two dimensional surface in the space *(x,y,z)*. Of course, you can have as many input variables as you want and the resulting surface becomes a hyper-surface.

For three inputs (x_1, x_2, x_3) the equation of a quadratic response surface is:

$y = b_0 + b_1x_1 + b_2x_2 + b_3x_3 + ...$ (linear terms)

$b_{12}x_1x_2 + b_{13}x_1x_3 + b_{23}x_2x_3 + ...$ (interaction terms)

$b_{11}x_1^2 + b_{22}x_2^2 + b_{33}x_3^2$ (quadratic terms)

It is difficult to visualize a k-dimensional surface in k+1 dimensional space when k>2. The function `rstool` is a GUI designed to make this visualization more intuitive.

An Interactive GUI for Response Surface Fitting and Prediction

The function `rstool` is useful for fitting response surface models. The purpose of `rstool` is larger than just fitting and prediction for polynomial models. This GUI provides an enviroment for exploration of the graph of a multidimensional polynomial.

You can learn about `rstool` by trying the commands below. The chemistry behind the data in `reaction.mat` deals with reaction kinetics as a function of the partial pressure of three chemical reactants: hydrogen, n-pentane, and iso-pentane.

```
load reaction
rstool(reactants, rate, 'quadratic', 0.01, xn, yn)
```

You will see a "vector" of three plots. The dependent variable of all three plots is the reaction rate. The first plot has hydrogen as the independent variable. The second and third plots have n-pentane and isopentane respectively.

Each plot shows the fitted relationship of the reaction rate to the independent variable at a fixed value of the other two independent variables. The fixed value of each independent variable is in an editable text box below each axis. You can change the fixed value of any independent variable by either typing a new value in the box or by dragging any of the 3 vertical lines to a new position.

When you change the value of an independent variable, all the plots update to show the current picture at the new point in the space of the independent variables.

Note that while this example only uses three reactants, `rstool` can accommodate an arbitrary number of independent variables. Interpretability may be limited by the size of the monitor for large numbers of inputs.

The GUI also has two pop-up menus. The **Export** menu facilitates saving various important variables in the GUI to the base workspace. Below the Export menu there is another menu that allows you to change the order of the polynomial model from within the GUI. If you used the commands above, this menu will have the string **Full Quadratic**. Other choices are:

• Linear – has the constant and first order terms only.

• Pure Quadratic – includes constant, linear and squared terms.

• Interactions – includes constant, linear, and cross product terms.

Stepwise Regression

Stepwise regression is a technique for choosing the variables to include in a multiple regression model. Forward stepwise regression starts with no model terms. At each step it adds the most statistically significant term (the one with the highest F statistic or lowest p-value) until there are none left. Backward stepwise regression starts with all the terms in the model and removes the least significant terms until all the remaining terms are statistically significant. It is also possible to start with a subset of all the terms and then add significant terms or remove insignificant terms.

An important assumption behind the method is that some input variables in a multiple regression do not have an important explanatory effect on the response. If this assumption is true, then it is a convenient simplification to keep only the statistically significant terms in the model.

One common problem in multiple regression analysis is multicollinearity of the input variables. The input variables may be as correlated with each other as they are with the response. If this is the case, the presence of one input variable in the model may mask the effect of another input. Stepwise regression used as a canned procedure is a dangerous tool because the resulting model may include different variables depending on the choice of starting model and inclusion strategy.

The Statistics Toolbox uses an interactive graphical user interface (GUI) to provide a more understandable comparison of competing models. You can explore the GUI using the Hald (1960) data set. Here are the commands to get started.

```
load hald
stepwise(ingredients, heat)
```

The Hald data come from a study of the heat of reaction of various cement mixtures. There are 4 components in each mixture, and the amount of heat produced depends on the amount of each ingredient in the mixture.

Stepwise Regression Interactive GUI

The interface consists of three interactively linked figure windows:

- The Stepwise Regression Plot
- The Stepwise Regression Diagnostics Table
- The Stepwise History Plot

All three windows have *hot* regions. When your mouse is above one of these regions, the pointer changes from an arrow to a circle. Clicking on this point initiates some activity in the interface.

Stepwise Regression Plot

This plot shows the regression coefficient and confidence interval for every term (in or out of the model). The green lines represent terms in the model while red lines indicate that the term is not currently in the model.

Statistically significant terms are solid lines. Dotted lines show that the fitted coefficient is not significantly different from zero.

Clicking on a line in this plot toggles its state. That is, a term in the model (green line) gets removed (turns red), and terms out of the model (red line) enter the model (turn green).

The coefficient for a term out of the model is the coefficient resulting from adding that term to the current model.

Scale Inputs. Pressing this button centers and normalizes the columns of the input matrix to have a standard deviation of one.

Export. This pop-up menu allows you to export variables from the stepwise function tothe base workspace.

Close. The **Close** button removes all the figure windows.

Stepwise Regression Diagnostics Figure

This table is a quantitative view of the information in the Stepwise Regression Plot. The table shows the Hald model with the second and third terms removed.

```
                        Confidence Intervals
    Column #    Parameter      Lower       Upper

       1           1.44         1.02        1.86

       2         0.4161       -0.1602      0.9924

       3          -0.41        -1.029      0.2086

       4         -0.614       -0.7615     -0.4664


     RMSE        R-square         F           P

    2.734        0.9725        176.6     1.581e-08
```

Coefficients and Confidence Intervals.   The table at the top of the figure shows the regression coefficient and confidence interval for every term (in or out of the model.) The green rows in the table (on your monitor) represent terms in the model while red rows indicate terms not currently in the model.

Clicking on a row in this table toggles the state of the corresponding term. That is, a term in the model (green row) gets removed (turns red), and terms out of the model (red rows) enter the model (turn green).

The coefficient for a term out of the model is the coefficient resulting from adding that term to the current model.

Additional Diagnostic Statistics.   There are also several diagnostic statistics at the bottom of the table:

- RMSE - the root mean squared error of the current model.
- R-square - the amount of response variability explained by the model.
- F - the overall F statistic for the regression.
- P - the associated significance probability.

Close Button.   Shuts down all windows.

Help Button.   Activates on-line help.

Stepwise History. This plot shows the RMSE and a confidence interval for every model generated in the course of the interactive use of the other windows.

Recreating a Previous Model. Clicking on one of these lines re-creates the current model at that point in the analysis using a *new* set of windows. So, you can thus compare the two candidate models directly.

Nonlinear Regression Models

RSM is an empirical modeling approach using polynomials as local approximations to the true input/output relationship. This empirical approach is often adequate for process improvement in an industrial setting.

In scientific applications there is usually relevant theory that allows us to make a mechanistic model. Often such models are nonlinear in the unknown parameters. Nonlinear models are more difficult to fit, requiring iterative methods that start with an initial guess of the unknown parameters. Each iteration alters the current guess until the algorithm converges.

Mathematical Form

The Statistics Toolbox has functions for fitting nonlinear models of the form:

$$y = f(X, \beta) + \varepsilon$$

where

- y is an n by 1 vector of observations
- f is any function of X and β
- X is an n by p matrix of input variables
- β is a p by 1 vector of unknown parameters to be estimated
- ε is an n by 1 vector of random disturbances

Nonlinear Modeling Example

The Hougen-Watson model (Bates and Watts 1988) for reaction kinetics is one specific example of this type. The form of the model is:

$$rate = \frac{\beta_1 \cdot x_2 - x_3 / \beta_5}{1 + \beta_2 \cdot x_1 + \beta_3 \cdot x_2 + \beta_4 \cdot x_3}$$

where $\beta_1, \beta_2,...,\beta_5$ are the unknown parameters, and x_1, x_2, and x_3 are the three input variables. The three inputs are hydrogen, n-pentane, and isopentane. It is easy to see that the parameters do not enter the model linearly.

The file `reaction.mat` contains simulated data from this reaction.

```
load reaction
who
Your variables are:

beta        rate        xn
model       reactants   yn
```

The Variables

- `rate` is a vector of observed reaction rates 13 by 1.
- `reactants` is a three column matrix of reactants 13 by 3.
- `beta` is vector of initial parameter estimates 5 by 1.
- '*model*' is a string containing the nonlinear function name.
- '*xn*' is a string matrix of the names of the reactants.
- '*yn*' is a string containing the name of the response.

Fitting the Hougen-Watson Model

The Statistics Toolbox provides the function `nlinfit` for finding parameter estimates in nonlinear modeling. `nlinfit` returns the least-squares parameter estimates. That is, it finds the parameters that minimize the sum of the squared differences between the observed responses and their fitted values. It uses the Gauss-Newton algorithm with Levenberg-Marquardt modifications for global convergence.

`nlinfit` requires the input data, the responses, and an initial guess of the unknown parameters. You must also supply a function that takes the input data and the current parameter estimate and returns the predicted responses. In MATLAB this is called a "function" function.

Here is the hougen function:

```
function yhat = hougen(beta,x)
%HOUGEN Hougen-Watson model for reaction kinetics.
%    YHAT = HOUGEN(BETA,X) gives the predicted values of the
%    reaction rate, YHAT, as a function of the vector of
%    parameters, BETA, and the matrix of data, X.
%    BETA must have 5 elements and X must have three
%    columns.
%
%    The model form is:
%    y = (b1*x2 - x3/b5)./(1+b2*x1+b3*x2+b4*x3)
%
%    Reference:
%        [1]  Bates, Douglas, and Watts, Donald, "Nonlinear
%        Regression Analysis and Its Applications", Wiley
%        1988 p. 271-272.

%    Copyright (c) 1993-97 by The MathWorks, Inc.
%    B.A. Jones 1-06-95.

b1 = beta(1);
b2 = beta(2);
b3 = beta(3);
b4 = beta(4);
b5 = beta(5);

x1 = x(:,1);
x2 = x(:,2);
x3 = x(:,3);


yhat = (b1*x2 - x3/b5)./(1+b2*x1+b3*x2+b4*x3);
```

To fit the `reaction` data, call the function `nlinfit`:

```
load reaction
betahat = nlinfit(reactants, rate, 'hougen', beta)

betahat =

    1.2526
    0.0628
    0.0400
    0.1124
    1.1914
```

`nlinfit` has two optional outputs. They are the residuals and Jacobian matrix at the solution. The residuals are the differences between the observed and fitted responses. The Jacobian matrix is the direct analog of the matrix, X, in the standard linear regression model.

These outputs are useful for obtaining confidence intervals on the parameter estimates and predicted responses.

Confidence Intervals on the Parameter Estimates

Using `nlparci`, form 95% confidence intervals on the parameter estimates, `betahat`, from the reaction kinetics example.

```
[betahat, f, J] = nlinfit(reactants, rate, 'hougen', beta);
betaci = nlparci(betahat, f, J)

betaci =

   -0.7467    3.2519
   -0.0377    0.1632
   -0.0312    0.1113
   -0.0609    0.2857
   -0.7381    3.1208
```

Confidence Intervals on the Predicted Responses

Using nlpredci, form 95% confidence intervals on the predicted responses from the reaction kinetics example.

```
[yhat, delta] = nlpredci('hougen', reactants, betahat, f, J);
opd = [rate yhat delta]

opd =

     8.5500     8.2937    0.9178
     3.7900     3.8584    0.7244
     4.8200     4.7950    0.8267
     0.0200    -0.0725    0.4775
     2.7500     2.5687    0.4987
    14.3900    14.2227    0.9666
     2.5400     2.4393    0.9247
     4.3500     3.9360    0.7327
    13.0000    12.9440    0.7210
     8.5000     8.2670    0.9459
     0.0500    -0.1437    0.9537
    11.3200    11.3484    0.9228
     3.1300     3.3145    0.8418
```

The matrix, opd, has the observed rates in column 1 and the predictions in column 2. The 95% confidence interval is column 2 ± column 3. Note that the confidence interval contains the observations in each case.

An Interactive GUI for Nonlinear Fitting and Prediction

The function nlintool for nonlinear models is a direct analog of rstool for polynomial models. nlintool requires the same inputs as nlinfit. nlintool calls nlinfit.

The purpose of nlintool is larger than just fitting and prediction for nonlinear models. This GUI provides an enviroment for exploration of the graph of a multidimensional nonlinear function.

If you have already loaded reaction.mat, you can start nlintool:

```
nlintool(reactants, rate, 'hougen', beta, 0.01, xn, yn)
```

You will see a "vector" of three plots. The dependent variable of all three plots is the reaction rate. The first plot has hydrogen as the independent variable. The second and third plots have n-pentane and isopentane respectively.

Each plot shows the fitted relationship of the reaction rate to the independent variable at a fixed value of the other two independent variables. The fixed value of each independent variable is in an editable text box below each axis. You can change the fixed value of any independent variable by either typing a new value in the box or by dragging any of the 3 vertical lines to a new position.

When you change the value of an independent variable, all the plots update to show the current picture at the new point in the space of the independent variables.

Note that while this example only uses three reactants, nlintool, can accommodate an arbitrary number of independent variables. Interpretability may be limited by the size of the monitor for large numbers of inputs.

Hypothesis Tests

A hypothesis test is a procedure for determining if an assertion about a characteristic of a population is reasonable.

For example, suppose that someone says that the average price of a gallon of regular unleaded gas in Massachusetts is $1.15. How would you decide whether this statement is true? You could try to find out what every gas station in the state was charging and how many gallons they were selling at that price. That approach might be definitive, but it could end up costing more than the information is worth.

A simpler approach is to find out the price of gas at a small number of randomly chosen stations around the state and compare the average price to $1.15.

Of course, the average price you get will probably not be exactly $1.15 due to variability in price from one station to the next. Suppose your average price was $1.18. Is this three cent difference a result of chance variability, or is the original assertion incorrect? A hypothesis test can provide an answer.

Terminology

To get started, there are some terms to define and assumptions to make.

Terms
Null hypothesis
Alternative hypothesis
Significance level
p-value
Confidence interval

The *null hypothesis* is the original assertion. In this case the null hypothesis is that the average price of a gallon of gas is $1.15. The notation is $H_0: \mu = 1.15$.

There are three possibilities for the *alternative hypothesis*. You might only be interested in the result if gas prices were actually higher. In this case, the

alternative hypothesis is H_1: $\mu > 1.15$. The other possibilities are H_1: $\mu < 1.15$ and H_1: $\mu \neq 1.15$.

The *significance level* is related to the degree of certainty you require in order to reject the null hypothesis in favor of the alternative. By taking a small sample you cannot be certain about your conclusion. So you decide in advance to reject the null hypothesis if the probability of observing your sampled result is less than the significance level. For a typical significance level of 5% the notation is $\alpha = 0.05$. For this significance level, the probability of incorrectly rejecting the null hypothesis when it is actually true is 5%. If you need more protection from this error, then choose a lower value of α.

The *p-value* is the probability of observing the given sample result under the assumption that the null hypothesis is true. If the p-value is less than α, then you reject the null hypothesis. For example, if $\alpha = 0.05$ and the p-value is 0.03, then you reject the null hypothesis.

The converse is not true. If the p-value is greater than α, you do not accept the null hypothesis. You just have insufficient evidence to reject the null hypothesis (which is the same for practical purposes).

The outputs for the hypothesis test functions also include *confidence intervals*. Loosely speaking, a confidence interval is a range of values that have a chosen probability of containing the true hypothesized quantity. Suppose, in our example, 1.15 is inside a 95% confidence interval for the mean, μ. That is equivalent to being unable to reject the null hypothesis at a significance level of 0.05. Conversely if the $100(1 - \alpha)$ confidence interval does not contain 1.15, then you reject the null hypothesis at the α level of significance.

Assumptions

The difference between hypothesis test procedures often arises from differences in the assumptions that the researcher is willing to make about the data sample. The Z-test assumes that the data represents independent samples from the same normal distribution and that you know the standard deviation, σ. The t-test has the same assumptions except that you estimate the standard deviation using the data instead of specifying it as a known quantity.

Both tests have an associated signal-to-noise ratio:

$$z = \frac{\bar{x} - \mu}{\sigma} \quad or \quad T = \frac{\bar{x} - \mu}{s}$$

$$where \quad \bar{x} = \sum_{i=1}^{n} \frac{x_i}{n}$$

The signal is the difference between the average and the hypothesized mean. The noise is the standard deviation posited or estimated.

If the null hypothesis is true, then Z has a standard normal distribution, N(0,1). T has a Student's t distribution with the degrees of freedom, ν, equal to one less than the number of data values.

Given the observed result for Z or T, and knowing their distribution assuming the null hypothesis is true, it is possible to compute the probability (p-value) of observing this result. If the p-value is very small, then that casts doubt on the truth of the null hypothesis. For example, suppose that the p-value was 0.001, meaning that the probability of observing the given Z (or T) was one in a thousand. That should make you skeptical enough about the null hypothesis that you reject it rather than believe that your result was just a lucky 999 to 1 shot.

Example

This example uses the gasoline price data in gas.mat. There are two samples of 20 observed gas prices for the months of January and February 1993.

```
load gas
prices = [price1 price2]

prices =

     119    118
     117    115
     115    115
     116    122
     112    118
     121    121
     115    120
     122    122
     116    120
```

118	113
109	120
112	123
119	121
112	109
117	117
113	117
114	120
109	116
109	118
118	125

Suppose it is historically true that the standard deviation of gas prices at gas stations around Massachusetts is four cents a gallon. The Z-test is a procedure for testing the null hypothesis that the average price of a gallon of gas in January (price1) is $1.15.

```
[h, pvalue, ci] = ztest(price1/100, 1.15, 0.04)

h =

     0

pvalue =

    0.8668

ci =

    1.1340    1.1690
```

The result of the hypothesis test is the boolean variable, h. When h = 0, you do not reject the null hypothesis.

The result suggests that $1.15 is reasonable. The 95% confidence interval [1.1340 1.1690] neatly brackets $1.15.

What about February? Try a t-test with price2. Now you are not assuming that you know the standard deviation in price.

```
[h, pvalue, ci] = ttest(price2/100, 1.15)
```

```
h =

     1

pvalue =

   4.9517e-04

ci =

     1.1675     1.2025
```

With the boolean result, h = 1, you can reject the null hypothesis at the default significance level, 0.05.

It looks like $1.15 is not a reasonable estimate of the gasoline price in February. The low end of the 95% confidence interval is greater than 1.15.

The function ttest2 allows you to compare the means of the two data samples.

```
[h, sig, ci] = ttest2(price1, price2)

h =

     1


sig =

   0.0083


ci =

   -5.7845    -0.9155
```

The confidence interval (ci above) indicates that gasoline prices were between one and six cents lower in January than February.

The box plot gives the same conclusion graphically. Note that the notches have little, if any, overlap. Refer back to the "Statistical Plots" section for more on box plots.

```
boxplot(prices, 1)
set(gca,'XtickLabels',str2mat('January','February'))
xlabel('Month')
ylabel('Prices ($0.01)')
```
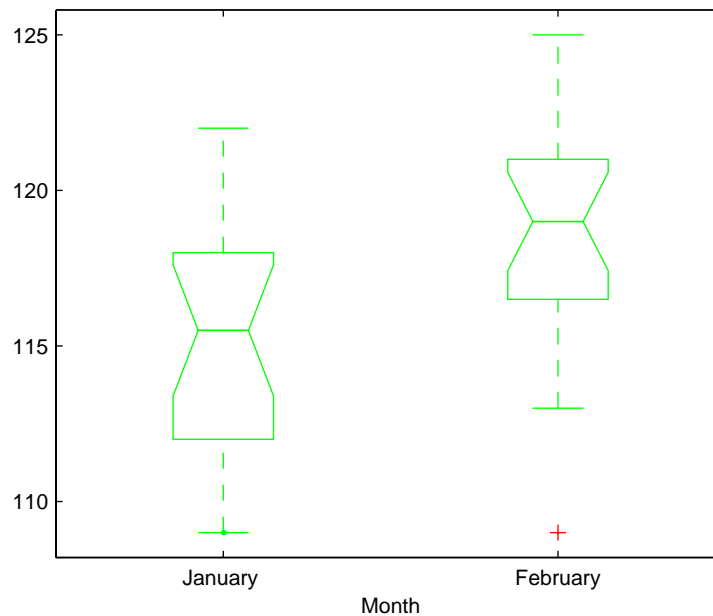
Multivariate Statistics

Multivariate statistics is an omnibus term for a number of different statistical methods. The defining characteristic of these methods is that they all aim to understand a data set by considering a group of variables together rather than focusing on only one variable at a time.

Principal Components Analysis

One of the difficulties inherent in multivariate statistics is the problem of visualizing multi-dimensionality. In MATLAB the `plot` command displays a graph of the relationship between two variables. The `plot3` and `surf` commands display different three-dimensional views. When there are more than three variables, it stretches the imagination to visualize their relationships.

Fortunately in data sets with many variables, groups of variables often move together. One reason for this is that more than one variable may be measuring the same driving principle governing the behavior of the system. In many systems there are only a few such driving forces. But an abundance of instrumentation allows us to measure dozens of system variables. When this happens, we can take advantage of this redundancy of information. We can simplify our problem by replacing a group of variables with a single new variable.

Principal Components Analysis is a quantitatively rigorous method for achieving this simplification. The method generates a new set of variables, called principal components. Each principal component is a linear combination of the original variables. All the principal components are orthogonal to each other so there is no redundant information. The principal components as a whole form an orthogonal basis for the space of the data.

There are an infinite number of ways to construct an orthogonal basis for several columns of data. What is so special about the principal component basis?

The first principal component is a single axis in space. When you project each observation on that axis, the resulting values form a new variable. And the variance of this variable is the maximum among all possible choices of the first axis.

The second principal component is another axis in space, perpendicular to the first. Projecting the observations on this axis generates another new variable. The variance of this variable is the maximum among all possible choices of this second axis.

The full set of principal components is as large as the original set of variables. But, it is commonplace for the sum of the variances of the first few principal components to exceed 80% of the total variance of the original data. By examining plots of these few new variables, researchers often develop a deeper understanding of the driving forces that generated the original data.

Example

Let us look at a sample application that uses 9 different indices of the quality of life in 329 U.S. cities. These are climate, housing, health, crime, transportation, education, arts, recreation, and economics. For each index, higher is better; so, for example, a higher index for crime means a lower crime rate.

We start by loading the data in `cities.mat`.

```
load cities
whos
            Name          Size

        categories        9 by 14
             names      329 by 43
           ratings      329 by 9
```

The `whos` command generates a table of information about all the variables in the workspace. The cities data set contains three variables:

- `categories`, a string matrix containing the names of the indices.
- `names`, a string matrix containing the 329 city names.
- `ratings`, the data matrix with 329 rows and 9 columns.

Here are the `categories`:

```
categories

categories =

climate
housing
health
crime
transportation
education
```

```
arts
recreation
economics
```

Let's look at the first several rows of city names, too.

```
first5 = names(1:5,:)

first5 =

Abilene, TX
Akron, OH
Albany, GA
Albany-Troy, NY
Albuquerque, NM
```

To get a quick impression of the ratings data, make a boxplot.

```
boxplot(ratings, 0, '+', 0)
set(gca, 'YTicklabels', categories)
```

These commands generate the plot below. Note that there is substantially more variability in the ratings of the arts and housing than in the ratings of crime and climate.
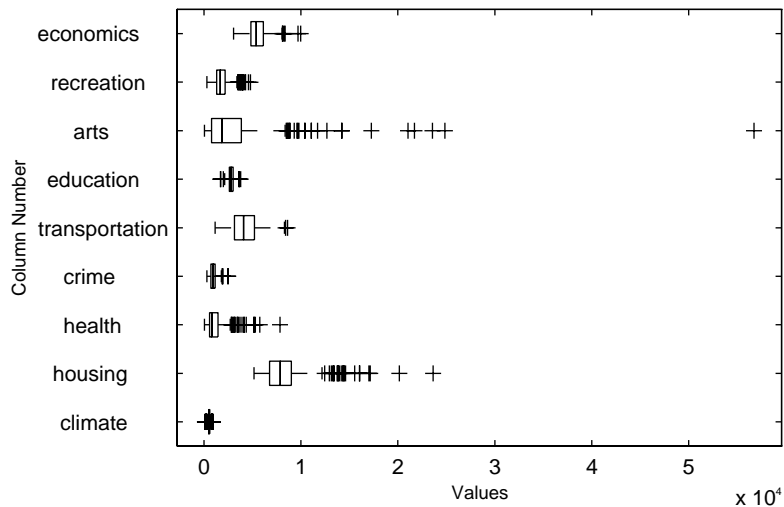
Ordinarily you might also graph pairs of the original variables, but there are 36 two-variable plots. Maybe Principal Components Analysis can reduce the number of variables we need to consider.

Sometimes it makes sense to compute principal components for raw data. This is appropriate when all the variables are in the same units. Standardizing the data is reasonable when the variables are in different units or when the variance of the different columns is substantial (as in this case).

You can standardize the data by dividing each column by its standard deviation.

```
stdr = std(ratings);
sr = ratings./stdr(ones(329,1),:);
```

Now we are ready to find the principal components.

```
[pcs, newdata, variances, t2] = princomp(sr);
```

The Principal Components (First Output)

The first output of princomp, pcs, is the nine principal components. These are the linear combinations of the original variables that generate the new variables.

Let's look at the first three principal component vectors.

```
p3 = pcs(:,1:3)

p3 =

    0.2064   -0.2178    0.6900
    0.3565   -0.2506    0.2082
    0.4602    0.2995    0.0073
    0.2813   -0.3553   -0.1851
    0.3512    0.1796   -0.1464
    0.2753    0.4834   -0.2297
    0.4631    0.1948    0.0265
    0.3279   -0.3845    0.0509
    0.1354   -0.4713   -0.6073
```

The largest weights in the first column (1st principal component) are the 3rd and 7th elements corresponding to the variables, arts and health. All the ele-

ments of the first principal component are the same sign, making it a weighted average of all the variables.

To show the orthogonality of the principal components note that pre-multiplying them by their transpose yields the identity matrix.

```
I = p3' *p3

I =

     1.0000     0.0000    -0.0000
     0.0000     1.0000    -0.0000
    -0.0000    -0.0000     1.0000
```

The Component Scores (Second Output)

The second output, newdata, is the data in the new coordinate system defined by the principal components. This output is the same size as the input data matrix.

A plot of the first two columns of newdata shows the ratings data projected onto the first two principal components.

```
plot(newdata(:, 1), newdata(:, 2), '+')
xlabel('1st Principal Component');
ylabel('2nd Principal Component');
```
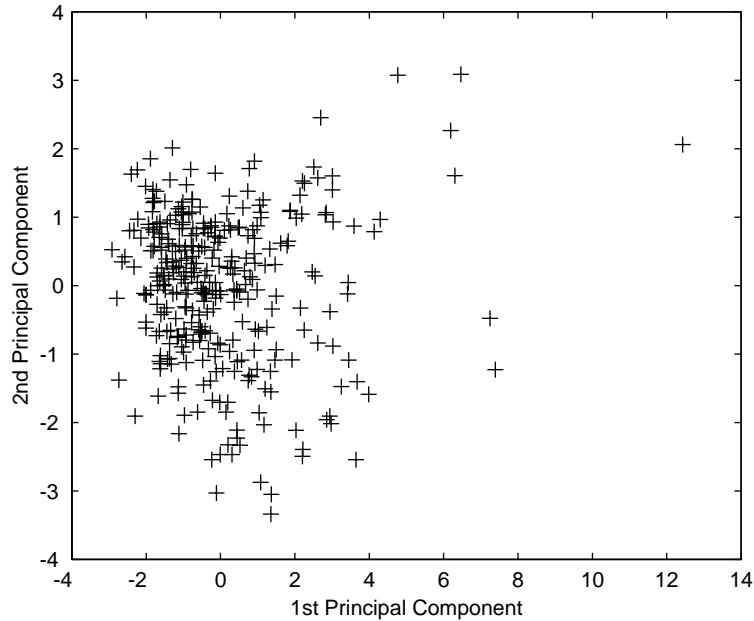

Note the outlying points in the upper right corner.

The function gname is useful for graphically identifying a few points in a plot like this. You can call gname with a string matrix containing as many case labels as points in the plot. The string matrix names works for labeling points with the city names.

```
gname(names)
```

Move your cursor over the plot and click once near each point at the top right. When you finish press the return key. Here is the resulting plot.
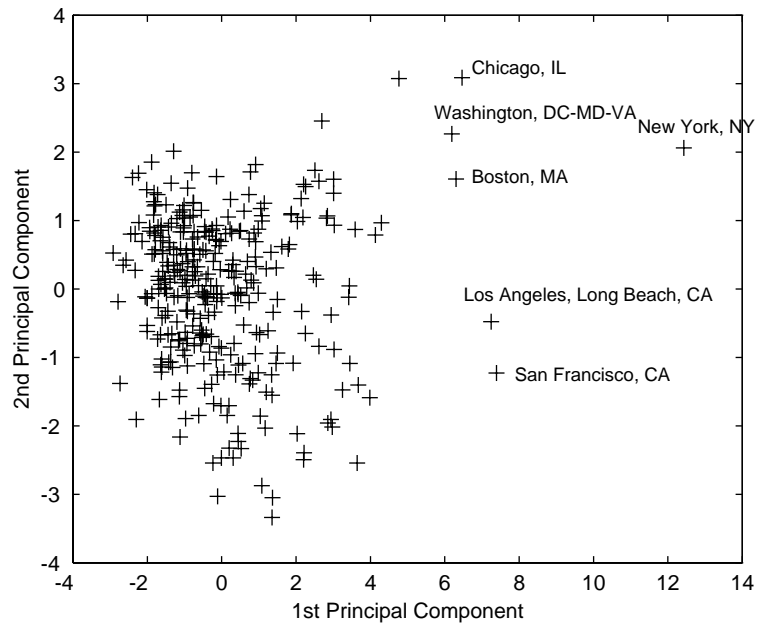
The labeled cities are the biggest population centers in the U.S. Perhaps we should consider them as a completely separate group. If we call gname without arguments, it labels each point with its row number.
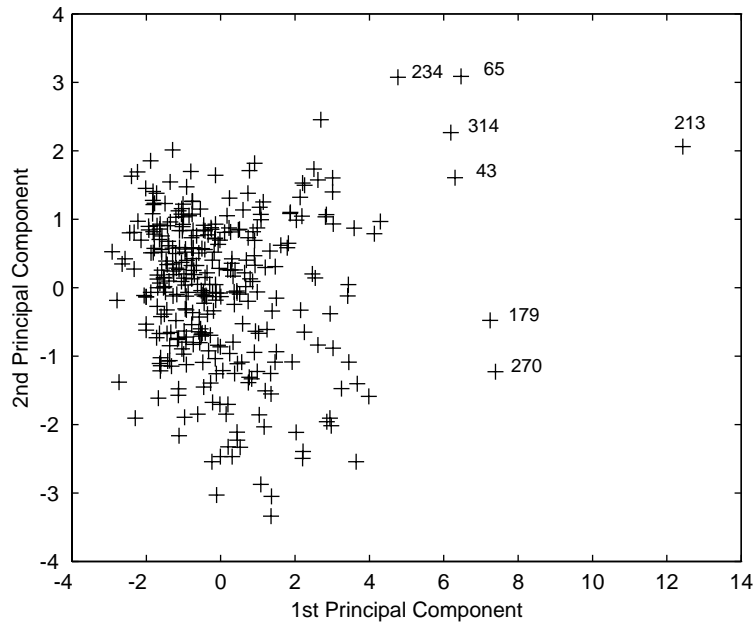
We can create an index variable containing the row numbers of all the metro-politan areas we chose.

```
metro = [43 65 179 213 234 270 314];
names(metro,:)
ans =

Boston, MA
Chicago, IL
Los Angeles, Long Beach, CA
New York, NY
Philadelphia, PA-NJ
San Francisco, CA
Washington, DC-MD-VA
```

To remove these rows from the ratings matrix:

```
rsubset = ratings;
nsubset = names;
nsubset(metro,:) = [];
rsubset(metro,:) = [];
size(rsubset)

ans =

   322     9
```

To practice, repeat the analysis using the variable rsubset as the new data matrix and nsubset as the string matrix of labels.

The Component Variances (Third Output)

The third output (variances) is a vector containing the variance explained by the corresponding column of newdata.

```
variances

variances =

   3.4083
   1.2140
   1.1415
   0.9209
   0.7533
   0.6306
   0.4930
   0.3180
   0.1204
```

You can easily calculate the percent of the total variability explained by each principal component.

```
percent_explained = 100*variances/sum(variances)
percent_explained =

    37.8699
    13.4886
    12.6831
    10.2324
     8.3698
     7.0062
     5.4783
     3.5338
     1.3378
```

A "Scree" plot is a pareto plot of the percent variability explained by each principal component.

```
pareto(percent_explained)
xlabel('Principal Component')
ylabel('Variance Explained (%)')
```
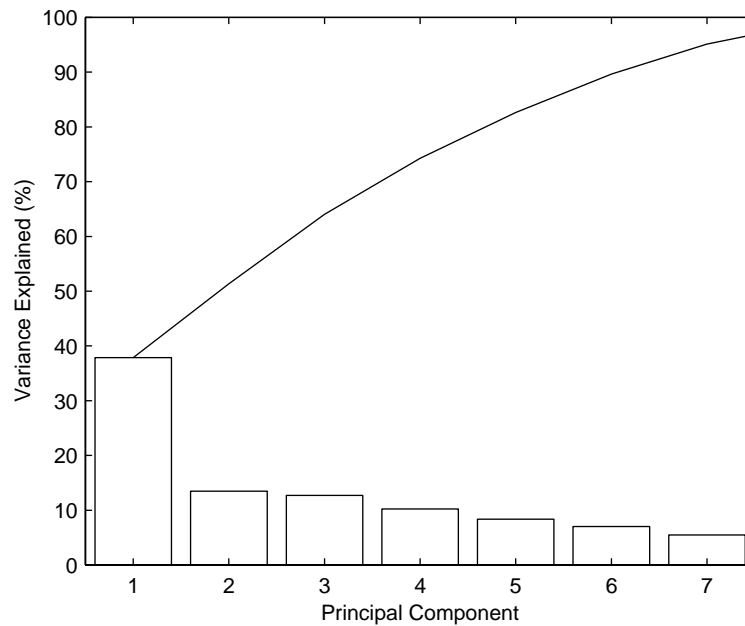
We can see that the first three principal components explain roughly two thirds of the total variability in the standardized ratings.

Hotelling's T^2 (Fourth Output)

The last output of the function `princomp`, Hotelling's T^2, is a statistical measure of the multivariate distance of each observation from the center of the data set. This is an analytical way to find the most extreme points in the data.

```
[st2, index] = sort(t2); % Sort in ascending order.
st2 = flipud(st2); % Values in descending order.
index = flipud(index); % Indices in descending order.
extreme = index(1)

extreme =

   213
names(extreme,:)

ans =

New York, NY
```

It is not surprising that the ratings for New York are the furthest from the average U.S. town.

Statistical Plots

The Statistics Toolbox adds specialized plots to the extensive graphics capabilities of MATLAB.

Box plots are graphs for data sample description. They are also useful for graphic comparison of the means of many samples (see the discussion of one-way ANOVA on page 1-51).

Normal probability plots are graphs for determining whether a data sample has normal distribution.

Quantile-quantile plots graphically compare the distributions of two samples.

Box Plots

The graph shows an example of a notched box plot.
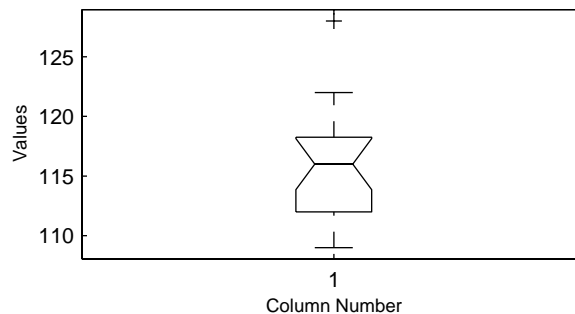
This plot has several graphic elements:

- The lower and upper lines of the "box" are the 25th and 75th percentiles of the sample. The distance between the top and bottom of the box is the interquartile range.

- The line in the middle of the box is the sample median. If the median is not centered in the box, that is an indication of skewness.

- The "whiskers" are lines extending above and below the box. They show the extent of the rest of the sample (unless there are outliers). Assuming no outliers, the maximum of the sample is the top of the upper whisker. The minimum of the sample is the bottom of the lower whisker. By default, an outlier

is a value that is more than 1.5 times the interquartile range away from the top or bottom of the box.

- The plus sign at the top of the plot is an indication of an outlier in the data. This point may be the result of a data entry error, a poor measurement or a change in the system that generated the data.

- The "notches" in the box are a graphic confidence interval about the median of a sample. Box plots do not have notches by default.

A side-by-side comparison of two notched box plots is the graphical equivalent of a t-test. See the section "Hypothesis Tests" on page 1-71.

Normal Probability Plots

A normal probability plot is a useful graph for assessing whether data comes from a normal distribution. Many statistical procedures make the assumption that the underlying distribution of the data is normal, so this plot can provide some assurance that the assumption of normality is not being violated or provide an early warning of a problem with your assumptions.

This example shows a typical normal probability plot.

```
x = normrnd(10, 1, 25, 1);
normplot(x)
```
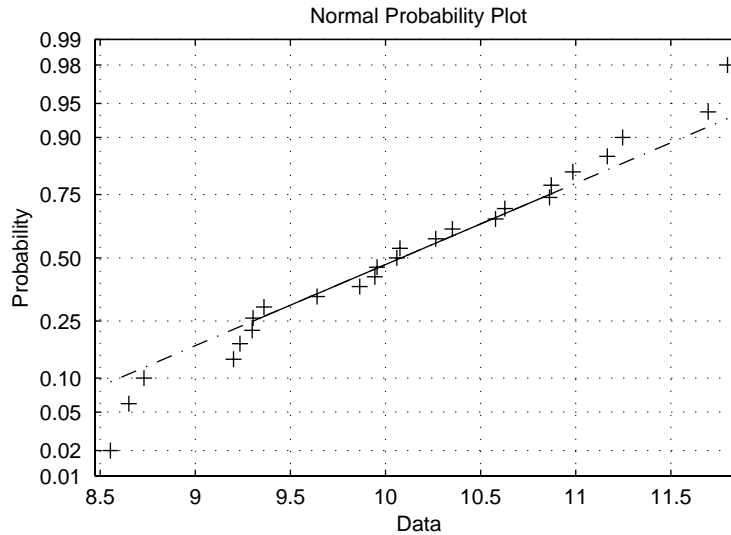

The plot has three graphic elements. The plus signs show the empirical proba-
bility versus the data value for each point in the sample. The solid line connects
the 25th and 75th percentiles of the data and represents a robust linear fit (i.e.,
insensitive to the extremes of the sample). The dashed line extends the solid
line to the ends of the sample.

The scale of the *y*-axis is not uniform. The *y*-axis values are probabilities and,
as such, go from zero to one. The distance between the tick marks on the *y*-axis
matches the distance between the quantiles of a normal distribution. The
quantiles are close together near the median (probability = 0.5) and stretch out
symmetrically moving away from the median. Compare the vertical distance
from the bottom of the plot to the probability 0.25 with the distance from 0.25
to 0.50. Similarly, compare the distance from the top of the plot to the proba-
bility 0.75 with the distance from 0.75 to 0.50.

If all the data points fall near the line, the assumption of normality is reasonable. But, if the data is nonnormal, the plus signs may follow a curve, as in the example using exponential data below.

```
x = exprnd(10, 100, 1);
normplot(x)
```


Normal Probability Plot
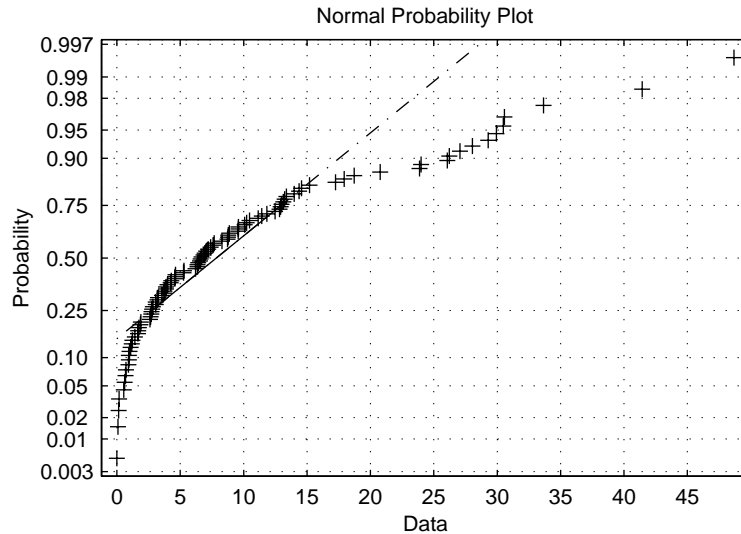
This plot is clear evidence that the underlying distribution is not normal.

Quantile-Quantile Plots

A quantile-quantile plot is useful for determining whether two samples come from the same distribution (whether normally distributed or not).

The example shows a quantile-quantile plot of two samples from a Poisson distribution.

```
x = poissrnd(10, 50, 1);
y = poissrnd(5, 100, 1);
qqplot(x, y);
```
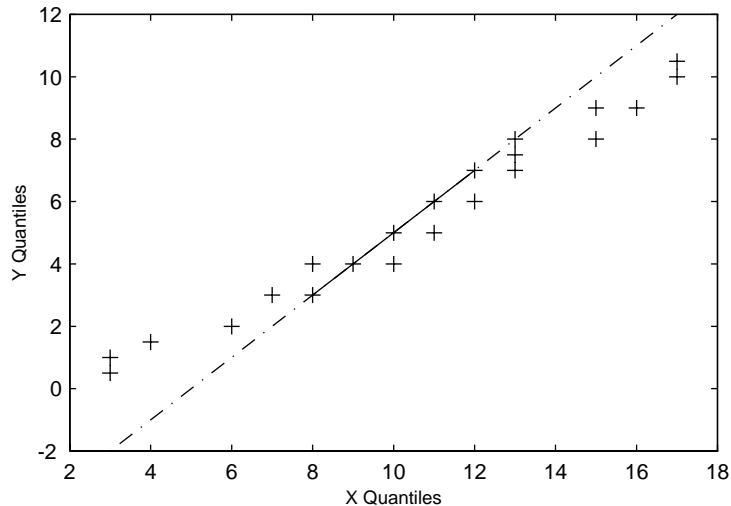

Even though the parameters and sample sizes are different, the straight line relationship shows that the two samples come from the same distribution.

Like the normal probability plot, the quantile-quantile plot has three graphic elements. The pluses are the quantiles of each sample. By default the number of pluses is the number of data values in the smaller sample. The solid line joins the 25th and 75th percentiles of the samples. The dashed line extends the solid line to the extent of the sample.

The example below shows what happens when the underlying distributions are not the same.

```
x = normrnd(5, 1, 100, 1);
y = weibrnd(2, 0.5, 100, 1);
qqplot(x, y);
```
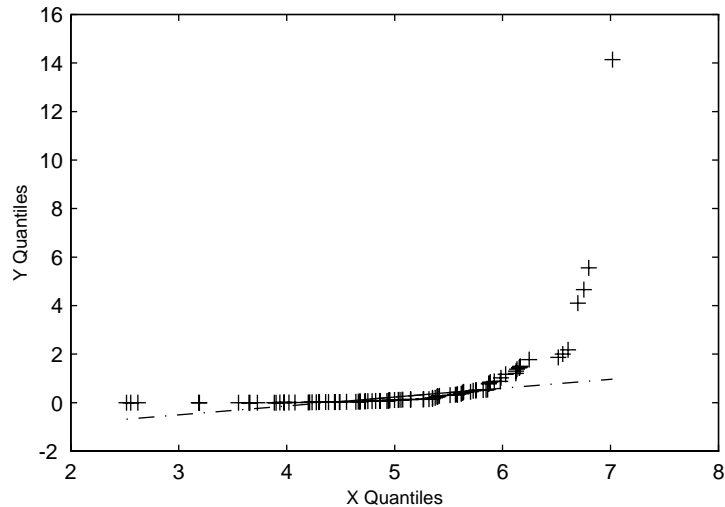

These samples clearly are not from the same distribution.

It is incorrect to interpret a linear plot as a guarantee that the two samples come from the same distribution. But, for assessing the validity of a statistical procedure that depends on the two samples coming from the same distribution, a linear quantile-quantile plot should be sufficient.

Weibull Probability Plots

A Weibull probability plot is a useful graph for assessing whether data comes from a Weibull distribution. Many reliability analyses make the assumption that the underlying distribution of the life times is Weibull, so this plot can provide some assurance that this assumption is not being violated or provide an early warning of a problem with your assumptions.

The scale of the *y*-axis is not uniform. The *y*-axis values are probabilities and, as such, go from zero to one. The distance between the tick marks on the *y*-axis matches the distance between the quantiles of a Weibull distribution.

If the data points (pluses) fall near the line, the assumption that the data come from a Weibull distribution is reasonable.

This example shows a typical Weibull probability plot.

```
y = weibrnd(2, 0.5, 100, 1);
weibplot(y)
```


Weibull Probability Plot
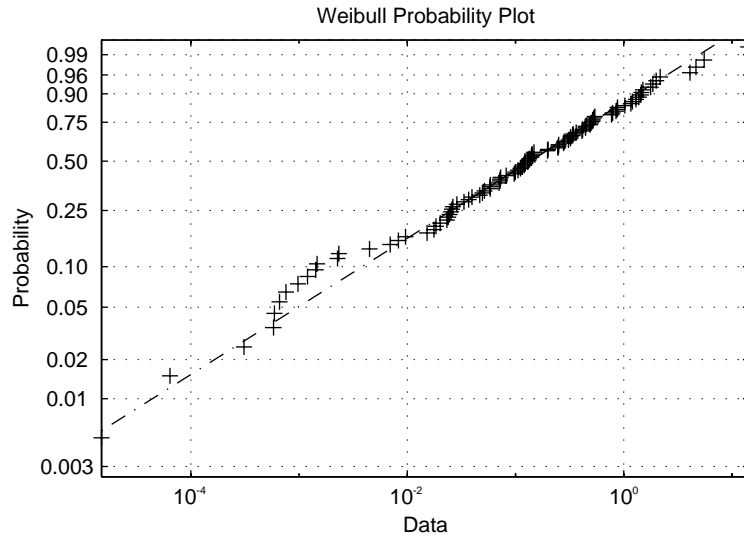
Statistical Process Control (SPC)

SPC is an omnibus term for a number of methods for assessing and monitoring the quality of manufactured goods. These methods are simple which makes them easy to implement even in a production environment.

Control Charts

These graphs were popularized by Walter Shewhart in his work in the 1920s at Western Electric. A control chart is a plot of a measurements over time with statistical limits applied. Actually *control* chart is a slight misnomer. The chart itself is actually a monitoring tool. The control activity may occur if the chart indicates that the process is changing in an undesirable systematic direction.

The Statistics Toolbox supports three common control charts:

- Xbar charts
- S charts
- Exponentially weighted moving average (EWMA) charts.

Xbar Charts

Xbar charts are a plot of the average of a sample of a process taken at regular intervals. Suppose we are manufacturing pistons to a tolerance of 0.5 thou-

sandths of an inch. We measure the runout (deviation from circularity in thousandths of an inch) at 4 points on each piston.

```
load parts
conf = 0.99;
spec = [-0.5 0.5];
xbarplot(runout,conf,spec)
```
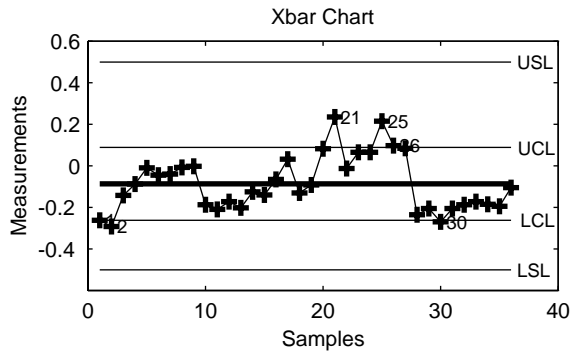

The lines at the bottom and the top of the plot show the process specifications. The central line is the average runout over all the pistons. The two lines flanking the center line are the 99% statistical control limits. By chance only one measurement in 100 should fall outside these lines. We can see that even in this small run of 36 parts, there are several points outside the boundaries (labeled by their observation numbers.) This is an indication that the process mean is not in statistical control. This might not be of much concern in practice, since all the parts are well within specification.

S Charts

The S chart is a plot of the standard deviation of a process taken at regular intervals. The standard deviation is a measure of the variability of a process. So, the plot indicates whether there is any systematic change in the process

variability. Continuing with the piston manufacturing example, we can look at the standard deviation of each set of 4 measurements of runout.

`schart(runout)`
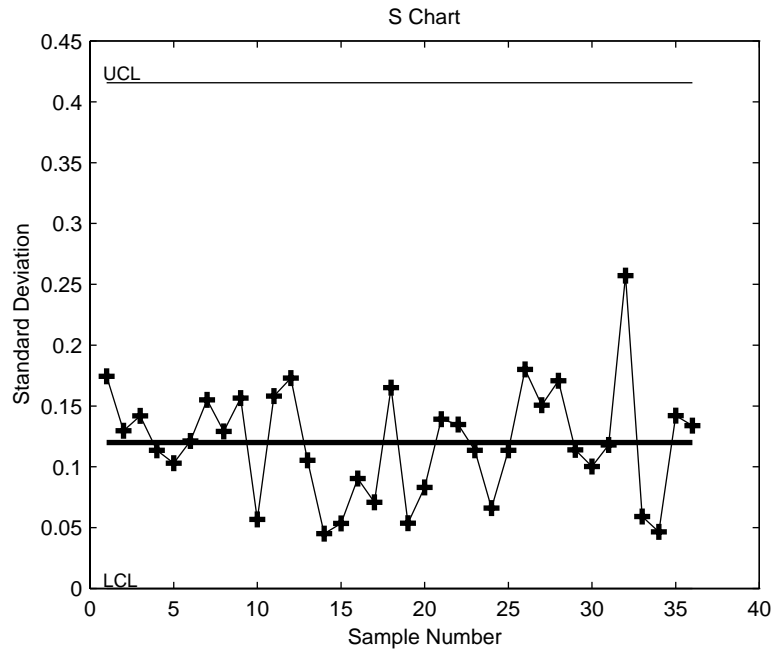
S Chart

The average runout is about one ten-thousandth of an inch. There is no indication of nonrandom variability.

EWMA Charts

The EWMA chart is another chart for monitoring the process average. It operates on slightly different assumptions than the Xbar chart. The mathematical model behind the Xbar chart posits that the process mean is actually constant over time and any variation in individual measurements is due entirely to chance.

The EWMA model is a little looser. Here we assume that the mean may be varying in time. Here is an EWMA chart of our runout example. Compare this with the plot on page 1-96.

```
ewmaplot(runout, 0.5, 0.01, spec)
```

Exponentially Weighted Moving Average (EWMA) Chart
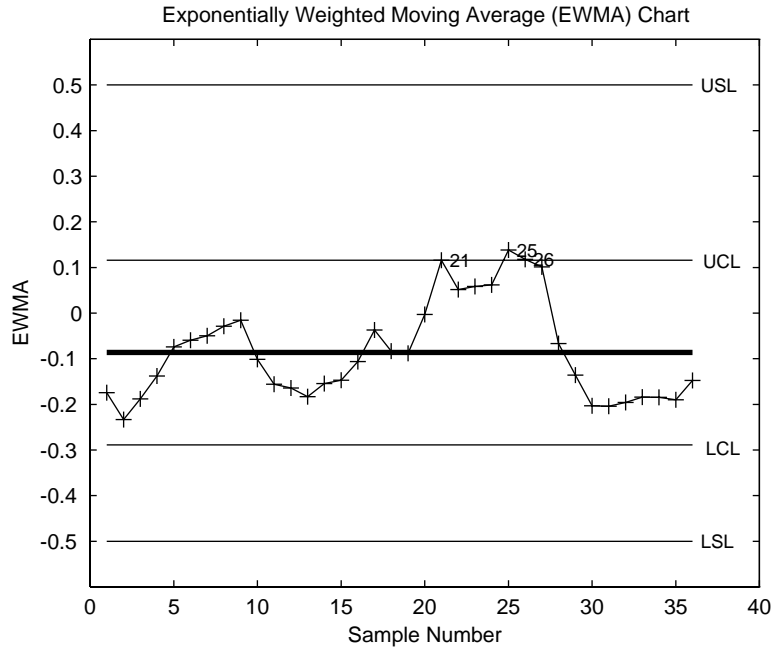
Capability Studies

Before going into full-scale production, many manufacturers run a pilot study to determine whether their process can actually build parts to the specifications demanded by the engineering drawing.

Using the data from these capability studies with a statistical model allows us to get a preliminary estimate of the percentage of parts that will fall outside the specifications.

```
[p, Cp, Cpk] = capable(mean(runout), spec)

p =

    1.3940e-09
```

Cp =

2. 3950

Cpk =

1. 9812

The result above shows that the probability (p = 1.3940e−09) of observing an unacceptable runout is extremely low. Cp and Cpk are two popular capability indices.

Cp is the ratio of the range of the specifications to six times the estimate of the process standard deviation.

$$C_p = \frac{USL - LSL}{6\sigma}$$

For a process that has its average value on target, a *Cp* of one translates to a little more than one defect per thousand. Recently many industries have set a quality goal of one part per million. This would correspond to a *Cp* = 1.6. The higher the value of *Cp* the more capable the process.

For processes that do not maintain their average on target, *Cpk*, is a more descriptive index of process capability. *Cpk* is the ratio of difference between the process mean and the closer specification limit to three times the estimate of the process standard deviation.

$$C_{pk} = min\left(\frac{USL - \mu}{3\sigma}, \frac{\mu - LSL}{3\sigma}\right)$$

where the process mean is μ.

Design of Experiments (DOE)

There is a world of difference between data and information. To extract information from data you have to make assumptions about the system that generated the data. Using these assumptions and physical theory you may be able to develop a mathematical model of the system.

Generally, even rigorously formulated models have some unknown constants. The goal of experimentation is to acquire data that allow us to estimate these constants.

But why do we need to experiment at all? We could instrument the system we want to study and just let it run. Sooner or later we would have all the data we could use.

In fact, this is a fairly common approach. There are three characteristics of historical data that pose problems for statistical modeling.

• Suppose we observe a change in the operating variables of a system followed by a change in the outputs of the system. That does *not* necessarily mean that the change in the system *caused* the change in the outputs.

• A common assumption in statistical modeling is that the observations are independent of each other. This is not the way a system in normal operation works.

• Controlling a system in operation often means changing system variables in tandem. But if two variables change together, it is impossible to separate their effects mathematically.

Designed experiments directly address these problems. The overwhelming advantage of a designed experiment is that you actively manipulate the system you are studying.

With DOE you may generate fewer data points than by using passive instrumentation, but the quality of the information you get will be higher.

The Statistics Toolbox provides several functions for generating experimental designs appropriate to various situations.

Full Factorial Designs

Suppose you wish to determine whether the variability of a machining process is due to the difference in the lathes that cut the parts or the operators who run the lathes.

If the same operator always runs a given lathe then you cannot tell whether the machine or the operator is the cause of the variation in the output. By allowing every operator to run every lathe you can separate their effects.

This is a factorial approach. fullfact is the function that generates the design. Suppose we have four operators and three machines. What is the factorial design?

```
d = fullfact([4 3])

d =
```

```
        1       1
        2       1
        3       1
        4       1
        1       2
        2       2
        3       2
        4       2
        1       3
        2       3
        3       3
        4       3
```

Each row of d represents one operator/machine combination. Note that there are 4*3 = 12 rows.

One special subclass of factorial designs is when all the variables take only two values. Suppose you want to quickly determine the sensitivity of a process to high and low values of 3 variables.

```
d2 = ff2n(3)

d2 =
        0       0       0
        0       0       1
```

0	1	0
0	1	1
1	0	0
1	0	1
1	1	0
1	1	1

There are $2^3 = 8$ combinations to check.

Fractional Factorial Designs

One difficulty with factorial designs is that the number of combinations increases exponentially with the number of variables you want to manipulate.

For example the sensitivity study discussed above might be impractical if there were 7 variables to study instead of just 3. A full factorial design would require $2^7 = 128$ runs!

If we assume that the variables do not act synergistically in the system, we can assess the sensitivity with far fewer runs. The theoretical minimum number is 8. To see the design (X) matrix we use the hadamard function.

```
X = hadamard(8)

X =
```

1	1	1	1	1	1	1	1
1	−1	1	−1	1	−1	1	−1
1	1	−1	−1	1	1	−1	−1
1	−1	−1	1	1	−1	−1	1
1	1	1	1	−1	−1	−1	−1
1	−1	1	−1	−1	1	−1	1
1	1	−1	−1	−1	−1	1	1
1	−1	−1	1	−1	1	1	−1

The last seven columns of d are the actual variable settings (–1 for low, 1 for high.) The first column (all ones) allows us to measure the mean effect in the linear equation, $y = X\beta + \varepsilon$.

D-optimal Designs

All the designs above were in use by early in the 20th century. In the 1970s statisticians started to use the computer in experimental design by recasting DOE in terms of optimization. A D-optimal design is one that maximizes the determinant of Fisher's information matrix, $X'X$. This matrix is proportional to the inverse of the covariance matrix of the parameters. So maximizing $det(X'X)$ is equivalent to minimizing the determinant of the covariance of the parameters.

A D-optimal design minimizes the volume of the confidence ellipsoid of the regression estimates of the linear model parameters, β.

There are several functions in the Statistics Toolbox that generate D-optimal designs. These are cordexch, daugment, dcovary, and rowexch.

Generating D-optimal Designs

cordexch and rowexch are two competing optimization algorithms for computing a D-optimal design given a model specification.

Both cordexch and rowexch are iterative algorithms. They operate by improving a starting design by making incremental changes to its elements. In the coordinate exchange algorithm, the increments are the individual elements of the design matrix. In row exchange, the elements are the rows of the design matrix. Atkinson and Donev (1992) is a reference.

To generate a D-optimal design you must specify the number of inputs, the number of runs, and the order of the model you wish to fit.

Both cordexch and rowexch take the following strings to specify the model.

- 'linear' ('l') – the default model with constant and first order terms.
- 'interaction' ('i') – includes constant, linear, and cross product terms.
- 'quadratic' ('q') – interactions plus squared terms.
- 'purequadratic' ('p') – includes constant, linear and squared terms.

Alternatively, you can use a matrix of integers to specify the terms. Details are in the help for the utility function x2fx.

For a simple example using the coordinate-exchange algorithm consider the problem of quadratic modeling with two inputs. The model form is:

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_{12} x_1 x_2 + \beta_{11} x_1^2 + \beta_{22} x_2^2 + \varepsilon$$

Suppose we want the D-optimal design for fitting this model with nine runs.

```
settings = cordexch(2, 9, 'q')

settings =
```

$$
\begin{array}{rr}
-1 & 1 \\
1 & 1 \\
0 & 1 \\
1 & -1 \\
-1 & -1 \\
0 & -1 \\
1 & 0 \\
0 & 0 \\
-1 & 0
\end{array}
$$

We can plot the columns of settings against each other to get a better picture of the design.

```
h = plot(settings(:,1),settings(:,2),'.');
set(gca,'Xtick',[-1 0 1])
set(gca,'Ytick',[-1 0 1])
set(h,'Markersize',20)
```
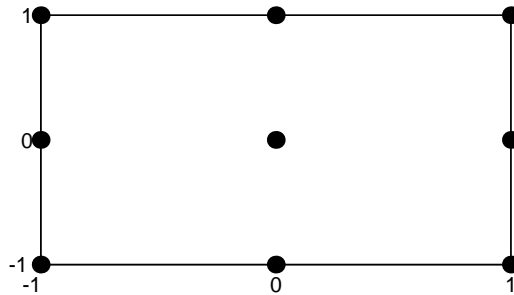

For a simple example using the row-exchange algorithm, consider the interaction model with two inputs. The model form is:

$$ y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_{12} x_1 x_2 + \varepsilon $$

Suppose we want the D-optimal design for fitting this model with four runs.

```
[settings, X] = rowexch(2, 4, 'i')

settings =

    -1     1
    -1    -1
     1    -1
     1     1


X =

     1    -1     1    -1
     1    -1    -1     1
     1     1    -1    -1
     1     1     1     1
```

The settings matrix shows how to vary the inputs from run to run. The X matrix is the design matrix for fitting the above regression model. The first column of X is for fitting the constant term, The last column is the element-wise product of the 2nd and 3rd columns.

The associated plot is simple but elegant.

```
h = plot(settings(:, 1), settings(:, 2), '.');
set(gca, 'Xtick', [-1 0 1])
set(gca, 'Ytick', [-1 0 1])
set(h, 'Markersize', 20)
```
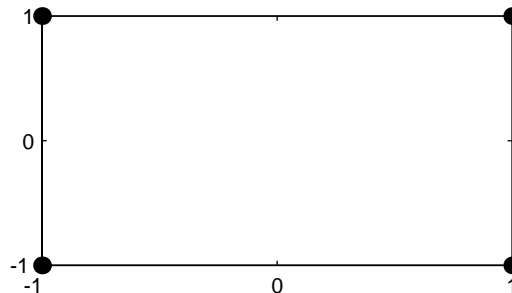
Augmenting D-Optimal Designs

In practice, experimentation is an iterative process. We often want to add runs to a completed experiment to learn more about our system. The function daugment allows you choose these extra runs optimally.

Suppose we have run the 8 run design below for fitting a linear model to 4 input variables.

```
settings = cordexch(4, 8)

settings =

        1     -1      1      1
       -1     -1      1     -1
       -1      1      1      1
        1      1      1     -1
       -1      1     -1      1
        1     -1     -1      1
       -1     -1     -1     -1
        1      1     -1     -1
```

This design is adequate to fit the linear model for four inputs, but cannot fit the six cross-product (interaction) terms. Suppose we are willing to do 8 more runs to fit these extra terms. Here's how.

```
[augmented, X] = daugment(settings, 8, 'i');
augmented

augmented =

     1    -1     1     1
    -1    -1     1    -1
    -1     1     1     1
     1     1     1    -1
    -1     1    -1     1
     1    -1    -1     1
    -1    -1    -1    -1
     1     1    -1    -1
    -1    -1    -1     1
     1     1     1     1
    -1    -1     1     1
    -1     1     1    -1
     1    -1     1    -1
     1    -1    -1    -1
    -1     1    -1    -1
     1     1    -1     1
info = X' *X

info =

    16     0     0     0     0     0     0     0     0     0     0
     0    16     0     0     0     0     0     0     0     0     0
     0     0    16     0     0     0     0     0     0     0     0
     0     0     0    16     0     0     0     0     0     0     0
     0     0     0     0    16     0     0     0     0     0     0
     0     0     0     0     0    16     0     0     0     0     0
     0     0     0     0     0     0    16     0     0     0     0
     0     0     0     0     0     0     0    16     0     0     0
     0     0     0     0     0     0     0     0    16     0     0
     0     0     0     0     0     0     0     0     0    16     0
     0     0     0     0     0     0     0     0     0     0    16
```

The augmented design is orthogonal, since X' *X is a multiple of the identity matrix. In fact, this design is the same as a 2^4 factorial design.

Design of Experiments with Known but Uncontrolled Inputs

Sometimes it is impossible to control every experimental input. But you may know the values of some inputs in advance. An example is the time each run takes place. If a process is experiencing linear drift, you may want to include the time of each test run as a variable in the model.

The function dcovary allows you to choose the settings for each run in order to maximize your information despite a linear drift in the process.

Suppose we wish to run an 8 run experiment with 3 factors that is optimal with respect to a linear drift in the response over time. First we create our drift input variable. Note, that drift is normalized to have mean zero. Its minimum is –1 and its maximum is +1.

```
drift = (linspace(-1, 1, 8))'
drift =

   -1.0000
   -0.7143
   -0.4286
   -0.1429
    0.1429
    0.4286
    0.7143
    1.0000

settings = dcovary(3, drift, 'linear')
settings =

    1.0000    1.0000   -1.0000   -1.0000
   -1.0000   -1.0000   -1.0000   -0.7143
   -1.0000    1.0000    1.0000   -0.4286
    1.0000   -1.0000    1.0000   -0.1429
   -1.0000    1.0000   -1.0000    0.1429
    1.0000    1.0000    1.0000    0.4286
   -1.0000   -1.0000    1.0000    0.7143
    1.0000   -1.0000   -1.0000    1.0000
```

Demos

The Statistics Toolbox has demonstration programs that create an interactive environment for exploring the probability distribution, random number generation, curve fitting, and design of experiments functions.

Demo	Purpose
disttool	Graphic interaction with probability distributions.
randtool	Interactive control of random number generation.
polytool	Interactive graphic prediction of polynomial fits.
rsmdemo	Design of Experiments and regression modeling.

The disttool Demo

disttool is a graphic environment for developing an intuitive understanding of probability distributions.

The disttool demo has the following features:

- A graph of the cdf (pdf) for the given parameters of a distribution.
- A pop-up menu for changing the distribution function.
- A pop-up menu for changing the function type (cdf <–> pdf).
- Sliders to change the parameter settings.
- Data entry boxes to choose specific parameter values.
- Data entry boxes to change the limits of the parameter sliders.
- Draggable horizontal and vertical reference lines to do interactive evaluation of the function at varying values.
- A data entry box to evaluate the function at a specific *x*-value.
- For cdf plots, a data entry box on the probability axis (*y*-axis) to find critical values corresponding to a specific probability.
- A **Close** button to end the demonstration.

The figure shows the randtool graphical interface with the following labels:
- distributions pop-up
- Normal (pop-up menu)
- CDF (pop-up menu)
- function type pop-up
- cdf function
- cdf value
- Probability 0.5
- draggable horizontal reference line
- draggable vertical reference line
- x value — 0
- Mu — 2, 0, -2
- Sigma — 2, 1, 0.5
- upper and lower parameter bounds
- Close
- parameter value
- parameter control
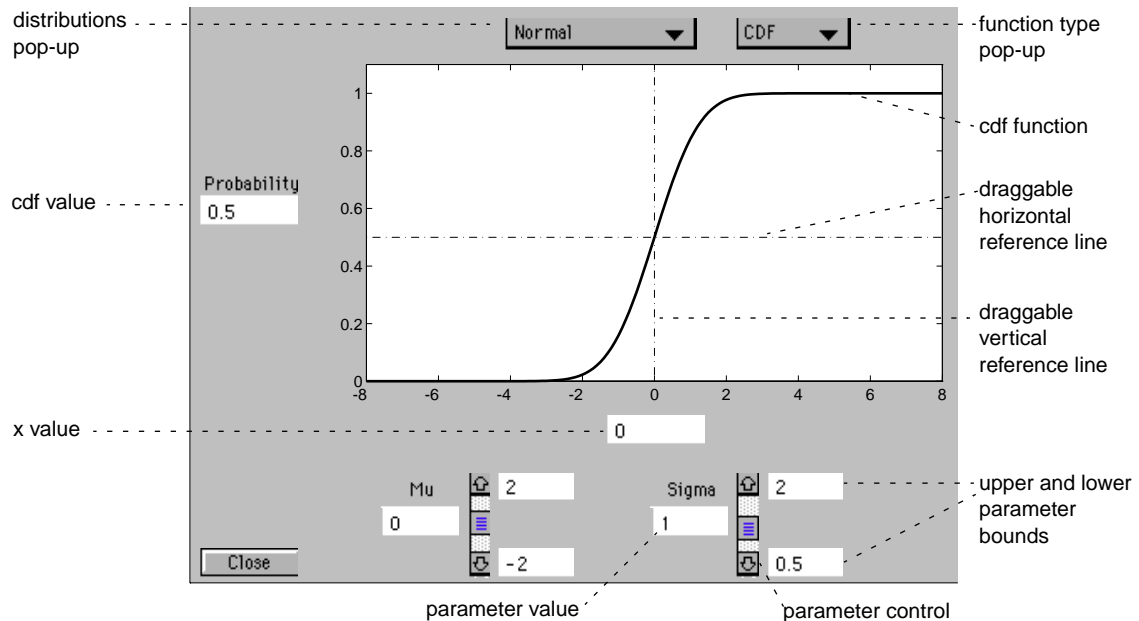
The randtool Demo

randtool is a graphic environment for generating random samples from various probability distributions and displaying the sample histogram.

The randtool demo has the following features:

- A histogram of the sample.
- A pop-up menu for changing the distribution function.
- Sliders to change the parameter settings.
- A data entry box to choose the sample size.
- Data entry boxes to choose specific parameter values.
- Data entry boxes to change the limits of the parameter sliders.
- An **Output** button to output the current sample to the variable ans.
- A **Resample** button to allow repetitive sampling with constant sample size and fixed parameters.
- A **Close** button to end the demonstration

distributions pop-up

histogram

upper and lower parameter bounds

draw again from the same distribution

output to variable ans

sample size

Counts

Normal

Values

Resample

Output

Close

Mu 2 0 -2

Sigma 2 1 0.5

Samples 100

parameter value

parameter control
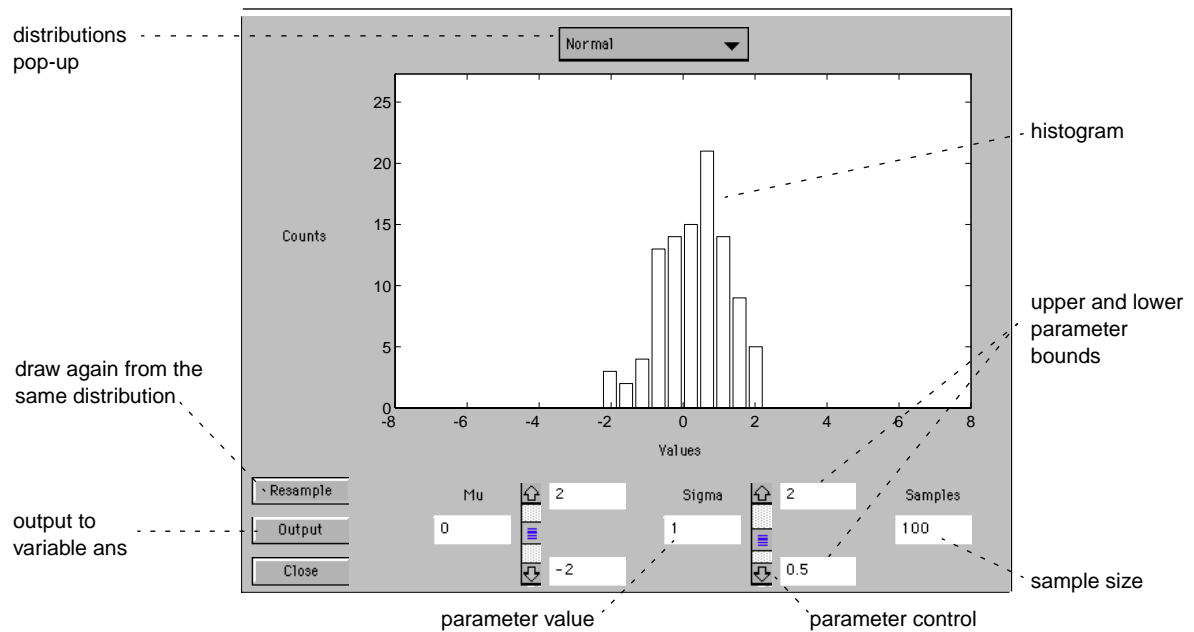
The polytool Demo

The polytool demo is an interactive graphic environment for polynomial curve fitting and prediction.

The `polytool` demo has the following features:

- A graph of the data, the fitted polynomial, and global confidence bounds on a new predicted value.
- *y*-axis text to display the predicted *y*-value and its uncertainty at the current *x*-value.
- A data entry box to change the degree of the polynomial fit.
- A data entry box to evaluate the polynomial at a specific *x*-value.
- A draggable vertical reference line to do interactive evaluation of the polynomial at varying *x*-values.
- A **Close** button to end the demonstration.

You can use `polytool` to do curve fitting and prediction for any set of *x-y* data, but, for the sake of demonstration, the Statistics Toolbox provides a dataset (`polydata.mat`) to teach some basic concepts.

To start the demonstration you must first load the dataset.

```
load polydata
who
Your variables are:

x          x1          y          y1
```

The variables x and y are observations made with error from a cubic polynomial. The variables x1 and y1 are data points from the "true" function without error.

If you do not specify the degree of the polynomial, `polytool` does a linear fit to the data.

```
polytool(x, y)
```
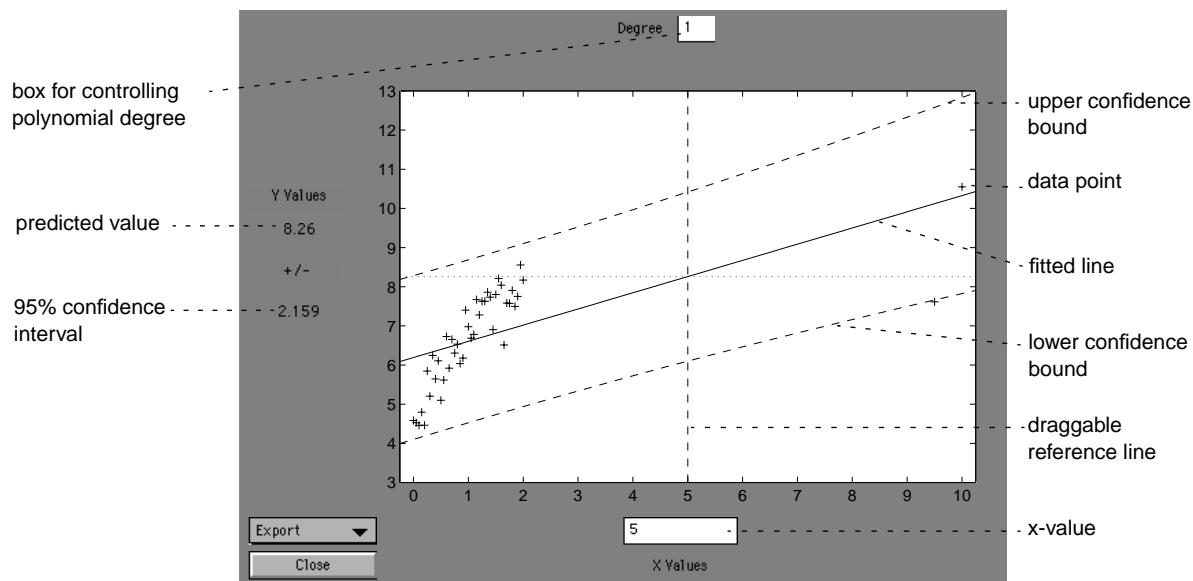
The linear fit is not very good. The bulk of the data with *x*-values between zero and two has a steeper slope than the fitted line. The two points to the right are dragging down the estimate of the slope.

Go to the data entry box at the top and type 3 for a cubic model. Then, drag the vertical reference line to the x-value of two (or type 2 in the x-axis data entry box).
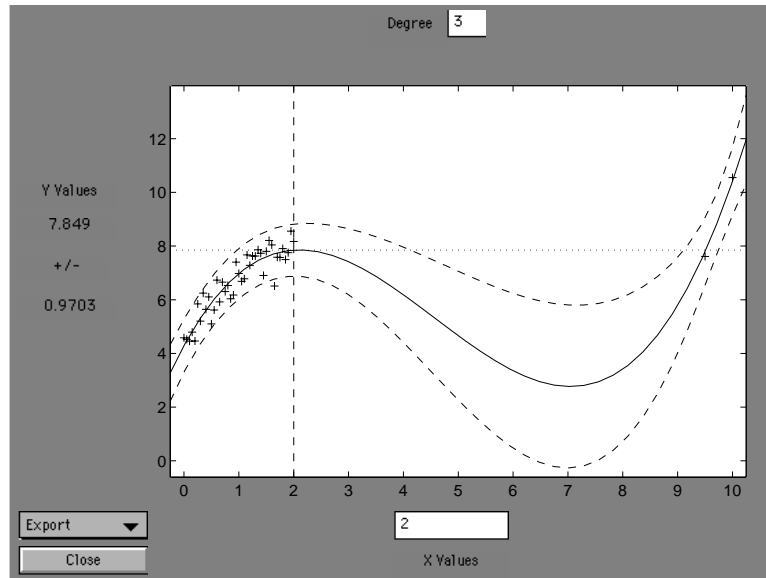
This graph shows a much better fit to the data. The confidence bounds are closer together indicating that there is less uncertainty in prediction. The data at both ends of the plot tracks the fitted curve.

The true function in this case is cubic.

$$y = 4 + 4.3444\,x - 1.4533\,x^2 + 0.1089\,x^3 + \varepsilon$$
$$\varepsilon \sim N(0, 0.1\,I)$$

To superimpose the "true" function on the plot use the command:

plot(x1, y1)
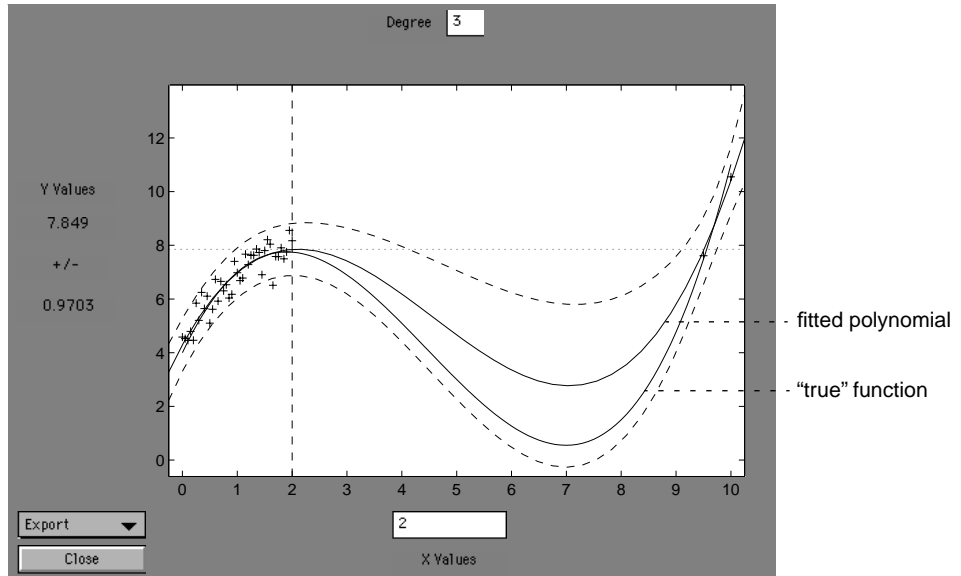
The true function is quite close to the fitted polynomial in the region of the data. Between the two groups of data points the two functions separate, but both fall inside the 95% confidence bounds.

If the cubic polynomial is a good fit, it is tempting to try a higher order polynomial to see if even more precise predictions are possible.

Since the true function is cubic, this amounts to overfitting the data. Use the data entry box for degree and type 5 for a quintic model.
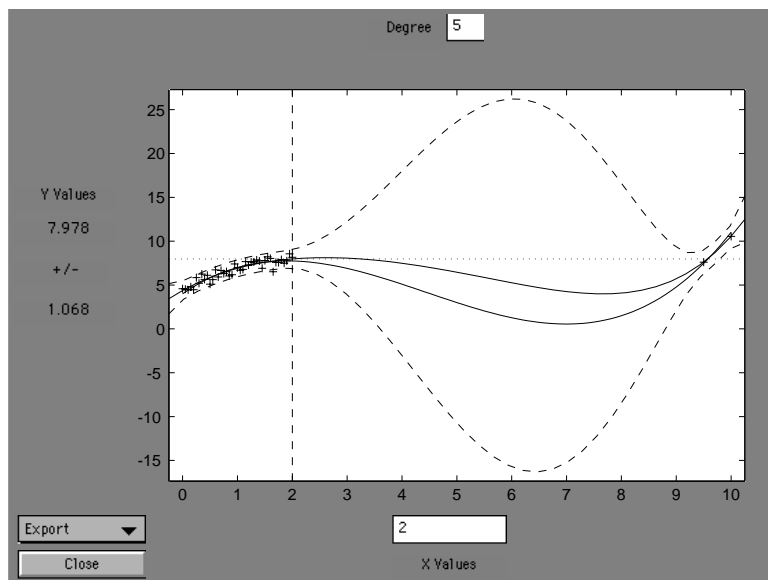
The resulting fit again does well predicting the function near the data points. But, in the region between the data groups, the uncertainty of prediction rises dramatically.

This bulge in the confidence bounds happens because the data really do not contain enough information to estimate the higher order polynomial terms precisely, so even interpolation using polynomials can be risky in some cases.

The rsmdemo Demo

rsmdemo is an interactive graphic environment that demonstrates design of experiments and surface fitting through the simulation of a chemical reaction. The goal of the demo is to find the levels of the reactants needed to maximize the reaction rate.

There are two parts to the demo:

1 Compare data gathered through trial and error with data from a designed experiment.

2 Compare response surface (polynomial) modeling with nonlinear modeling.

Part 1

Begin the demo by using the sliders in the Reaction Simulator to control the partial pressures of three reactants: Hydrogen, n-Pentane, and Isopentane. Each time you click the **Run** button, the levels for the reactants and results of the run are entered in the Trial and Error Data window.

Based on the results of previous runs, you can change the levels of the reactants to increase the reaction rate. (The results are determined using an underlying model that takes into account the noise in the process, so even if you keep all of the levels the same, the results will vary from run to run.) You are allotted a budget of 13 runs. When you have completed the runs, you can use the **Plot** menu on the Trial and Error Data window to plot the relationships between the reactants and the reaction rate, or click the **Analyze** button. When you click **Analyze**, rsmdemo calls the rstool function, which you can then use to try to optimize the results.)

Next, perform another set of 13 runs, this time from a designed experiment. In the Experimental Design Data window, click the **Do Experiment** button. rsmdemo calls the cordexch function to generate a D-optimal design, and then, for each run, computes the reaction rate.

Now use the **Plot** menu on the Experimental Design Data window to plot the relationships between the levels of the reactants and the reaction rate, or click the **Response Surface** button to call rstool to find the optimal levels of the reactants.

Compare the analysis results for the two sets of data. It is likely (though not certain) that you'll find some or all of these differences:

- You can fit a full quadratic model with the data from the designed experiment, but the trial and error data may be insufficient for fitting a quadratic model or interactions model.
- Using the data from the designed experiment, you are more likely to be able to find levels for the reactants that result in the maximum reaction rate.

Even if you find the best settings using the trial and error data, the confidence bounds are likely to be wider than those from the designed experiment.

Part 2

Now analyze the experimental design data with a polynomial model and a nonlinear model, and comparing the results. The true model for the process, which is used to generate the data, is actually a nonlinear model. However, within the range of the data, a quadratic model approximates the true model quite well.

To see the polynomial model, click the **Response Surface** button on the Experimental Design Data window. `rsmdemo` calls `rstool`, which fits a full quadratic model to the data. Drag the reference lines to change the levels of the reactants, and find the optimal reaction rate. Observe the width of the confidence intervals.

Now click the **Nonlinear Model** button on the Experimental Design Data window. `rsmdemo` calls `nlintool`, which fits a Hougen-Watson model to the data. As with the quadratic model, you can drag the reference lines to change the reactant levels. Observe the reaction rate and the confidence intervals.

Compare the analysis results for the two models. Even though the true model is nonlinear, you may find that the polynomial model provides a good fit. Because polynomial models are much easier to fit and work with than nonlinear models, a polynomial model is often preferable even when modeling a nonlinear process. Keep in mind, however, that such models are unlikely to be reliable for extrapolating outside the range of the data.

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Reference

The Statistics Toolbox provides several categories of functions. These categories appear in the table below.

The Statistics Toolbox's Main Categories of Functions	
probability	Probability distribution functions.
descriptive	Descriptive statistics for data samples.
plots	Statistical plots.
SPC	Statistical Process Control.
linear	Fitting linear models to data.
nonlinear	Fitting nonlinear regression models.
DOE	Design of Experiments.
PCA	Principal Components Analysis.
hypotheses	Statistical tests of hypotheses.
file I/O	Reads data from/writes data to operating-system files.
demos	Demonstrations.
data	Data for examples.

The following pages contain tables of functions from each of these specific areas. The first seven tables contain probability distribution functions. The remaining tables describe the other categories of functions.

	Parameter Estimation
betafit	Parameter estimation for the beta distribution.
betalike	Beta log-likelihood function.
binofit	Parameter estimation for the binomial distribution.
expfit	Parameter estimation for the exponential distribution.
gamfit	Parameter estimation for the gamma distribution.
gamlike	Gamma log-likelihood function.
mle	Maximum likelihood estimation.
normlike	Normal log-likelihood function.
normfit	Parameter estimation for the normal distribution.
poissfit	Parameter estimation for the Poisson distribution.
unifit	Parameter estimation for the uniform distribution.

	Cumulative Distribution Functions (cdf)
betacdf	Beta cdf.
binocdf	Binomial cdf.
cdf	Parameterized cdf routine.
chi2cdf	Chi-square cdf.
expcdf	Exponential cdf.
fcdf	F cdf.
gamcdf	Gamma cdf.
geocdf	Geometric cdf.
hygecdf	Hypergeometric cdf.

Cumulative Distribution Functions (cdf)	
logncdf	Lognormal cdf.
nbincdf	Negative binomial cdf.
ncfcdf	Noncentral F cdf.
nctcdf	Noncentral t cdf.
ncx2cdf	Noncentral Chi-square cdf.
normcdf	Normal (Gaussian) cdf.
poisscdf	Poisson cdf.
raylcdf	Rayleigh cdf.
tcdf	Student's t cdf.
unidcdf	Discrete uniform cdf.
unifcdf	Continuous uniform cdf.
weibcdf	Weibull cdf.

Probability Density Functions (pdf)	
betapdf	Beta pdf.
binopdf	Binomial pdf.
chi2pdf	Chi-square pdf.
exppdf	Exponential pdf.
fpdf	F pdf.
gampdf	Gamma pdf.
geopdf	Geometric pdf.
hygepdf	Hypergeometric pdf.

Probability Density Functions (pdf)	
normpdf	Normal (Gaussian) pdf.
lognpdf	Lognormal pdf.
nbinpdf	Negative binomial pdf.
ncfpdf	Noncentral F pdf.
nctpdf	Noncentral t pdf.
ncx2pdf	Noncentral Chi-square pdf.
pdf	Parameterized pdf routine.
poisspdf	Poisson pdf.
raylpdf	Rayleigh pdf.
tpdf	Student's t pdf.
unidpdf	Discrete uniform pdf.
unifpdf	Continuous uniform pdf.
weibpdf	Weibull pdf.

Inverse Cumulative Distribution Functions	
betainv	Beta critical values.
binoinv	Binomial critical values.
chi2inv	Chi-square critical values.
expinv	Exponential critical values.
finv	F critical values.
gaminv	Gamma critical values.
geoinv	Geometric critical values.

Inverse Cumulative Distribution Functions	
hygeinv	Hypergeometric critical values.
logninv	Lognormal critical values.
nbininv	Negative binomial critical values
ncfinv	Noncentral F critical values.
nctinv	Noncentral t critical values.
ncx2inv	Noncentral Chi-square critical values.
icdf	Parameterized inverse distribution routine.
norminv	Normal (Gaussian) critical values.
poissinv	Poisson critical values.
raylinv	Rayleigh critical values.
tinv	Student's t critical values.
unidinv	Discrete uniform critical values.
unifinv	Continuous uniform critical values.
weibinv	Weibull critical values.

Random Number Generators	
betarnd	Beta random numbers.
binornd	Binomial random numbers.
chi2rnd	Chi-square random numbers.
exprnd	Exponential random numbers.
frnd	F random numbers.
gamrnd	Gamma random numbers.

	Random Number Generators
geornd	Geometric random numbers.
hygernd	Hypergeometric random numbers.
lognrnd	Lognormal random numbers.
nbinrnd	Negative binomial random numbers.
ncfrnd	Noncentral F random numbers.
nctrnd	Noncentral t random numbers.
ncx2rnd	Noncentral Chi-square random numbers.
normrnd	Normal (Gaussian) random numbers.
poissrnd	Poisson random numbers.
raylrnd	Rayleigh random numbers.
random	Parameterized random number routine.
trnd	Student's t random numbers.
unidrnd	Discrete uniform random numbers.
unifrnd	Continuous uniform random numbers.
weibrnd	Weibull random numbers.

	Moments of Distribution Functions
`betastat`	Beta mean and variance.
`binostat`	Binomial mean and variance.
`chi2stat`	Chi-square mean and variance.
`expstat`	Exponential mean and variance.
`fstat`	F mean and variance.
`gamstat`	Gamma mean and variance.
`geostat`	Geometric mean and variance.
`hygestat`	Hypergeometric mean and variance.
`lognstat`	Lognormal mean and variance.
`nbinstat`	Negative binomial mean and variance.
`ncfstat`	Noncentral F mean and variance.
`nctstat`	Noncentral t mean and variance.
`ncx2stat`	Noncentral Chi-square mean and variance.
`normstat`	Normal (Gaussian) mean and variance.
`poisstat`	Poisson mean and variance.
`raylstat`	Rayleigh mean and variance.
`tstat`	Student's t mean and variance.
`unidstat`	Discrete uniform mean and variance.
`unifstat`	Continuous uniform mean and variance.
`weibstat`	Weibull mean and variance.

	Descriptive Statistics
corrcoef	Correlation coefficients (in MATLAB).
cov	Covariance matrix (in MATLAB).
geomean	Geometric mean.
harmmean	Harmonic mean.
iqr	Interquartile range.
kurtosis	Sample kurtosis.
mad	Mean absolute deviation.
mean	Arithmetic average (in MATLAB).
median	50th percentile (in MATLAB).
moment	Central moments of all orders.
nanmax	Maximum ignoring missing data.
nanmean	Average ignoring missing data.
nanmedian	Median ignoring missing data.
nanmin	Minimum ignoring missing data.
nanstd	Standard deviation ignoring missing data.
nansum	Sum ignoring missing data.
prctile	Empirical percentiles of a sample.
range	Sample range.
skewness	Sample skewness.
std	Standard deviation (in MATLAB).
trimmean	Trimmed mean.
var	Variance.

	Statistical Plotting
boxplot	Box plots.
errorbar	Error bar plot.
fsurfht	Interactive contour plot of a function.
gline	Interactive line drawing.
gname	Interactive point labeling.
lsline	Add least-squares fit line to plotted data.
normplot	Normal probability plots.
pareto	Pareto charts.
qqplot	Quantile-Quantile plots.
rcoplot	Regression case order plot.
refcurve	Reference polynomial.
refline	Reference line.
surfht	Interactive interpolating contour plot.
weibplot	Weibull plotting.

Statistical Process Control	
capable	Quality capability indices.
capaplot	Plot of process capability
ewmaplot	Exponentially weighted moving average plot
histfit	Histogram and normal density curve.
normspec	Plots normal density between limits.
schart	Time plot of standard deviation.
xbarplot	Time plot of means.

Linear Models	
anova1	One-way Analysis of Variance (ANOVA).
anova2	Two-way Analysis of Variance.
lscov	Regression given a covariance matrix (in MATLAB).
polyconf	Polynomial prediction with confidence intervals.
polyfit	Polynomial fitting (in MATLAB).
polyval	Polynomial prediction (in MATLAB).
regress	Multiple linear regression.
ridge	Ridge regression.
rstool	Response surface tool.
stepwise	Stepwise regression GUI.

	Nonlinear Regression
nlinfit	Nonlinear least-squares fitting.
nlintool	Prediction graph for nonlinear fits.
nlparci	Confidence intervals on parameters.
nlpredci	Confidence intervals for prediction.
nnls	Non-negative Least Squares (in MATLAB).

	Design of Experiments
cordexch	D-optimal design using coordinate exchange.
daugment	D-optimal augmentation of designs.
dcovary	D-optimal design with fixed covariates.
ff2n	Two-level full factorial designs.
fullfact	Mixed level full factorial designs.
hadamard	Hadamard designs (in MATLAB).
rowexch	D-optimal design using row exchange.

	Principal Components Analysis
barttest	Bartlett's test.
pcacov	PCA from covariance matrix.
pcares	Residuals from PCA.
princomp	PCA from raw data matrix.

Hypothesis Tests	
ranksum	Wilcoxon rank sum test.
signrank	Wilcoxon signed rank test.
signtest	Sign test for paired samples.
ttest	One sample t-test.
ttest2	Two sample t-test.
ztest	Z-test.

File I/O	
caseread	Read casenames from a file.
casewrite	Write casenames from a string matrix to a file.
tblread	Retrieve tabular data from the file system.
tblwrite	Write data in tabular form to the file system.

Demonstrations	
disttool	Interactive exploration of distribution functions.
randtool	Interactive random number generation.
polytool	Interactive fitting of polynomial models.
rsmdemo	Interactive process experimentation and analysis.
statdemo	Demonstrates capabilities of the Statistics Toolbox.

	Data
census.mat	U. S. Population 1790 to 1980.
cities.mat	Names of US metropolitan areas.
discrim.mat	Classification data.
gas.mat	Gasoline prices.
hald.mat	Hald data.
hogg.mat	Bacteria counts from milk shipments.
lawdata.mat	GPA versus LSAT for 15 law schools.
mileage.mat	Mileage data for three car models from two factories.
moore.mat	Five factor – one response regression data.
parts.mat	Dimensional runout on 36 circular parts.
popcorn.mat	Data for popcorn example.
polydata.mat	Data for polytool demo.
reaction.mat	Reaction kinetics data.
sat.dat	ASCII data for tblread example.

Purpose   One-way Analysis of Variance (ANOVA).

Syntax   p = anova1(X)
                   p = anova1(x, group)

Description   anova1(X) performs a balanced one-way ANOVA for comparing the means of
                   two or more columns of data on the sample in X. It returns the p-value for the
                   null hypothesis that the means of the columns of X are equal. If the p-value is
                   near zero, this casts doubt on the null hypothesis and suggests that the means
                   of the columns are, in fact, different.

                   anova1(x, group) performs a one-way ANOVA for comparing the means of two
                   or more samples of data in x indexed by the vector, group. The input, group,
                   identifies the group of the corresponding element of the vector x.

                   The values of group are integers with minimum equal to one and maximum
                   equal to the number of different groups to compare. There must be at least one
                   element in each group. This two-input form of anova1 does not require equal
                   numbers of elements in each group, so it is appropriate for unbalanced data.

                   The choice of a limit for the p-value to determine whether the result is "statis-
                   tically significant" is left to the researcher. It is common to declare a result
                   significant if the p-value is less than 0.05 or 0.01.

                   anova1 also displays two figures.

                   The first figure is the standard ANOVA table, which divides the variability of
                   the data in X into two parts:

                   • The variability due to the differences among the column means.
                   • The variability due to the differences between the data in each column and
                     the column mean.

                   The ANOVA table has five columns.

                   • The first shows the source of the variability.
                   • The second shows the Sum of Squares (SS) due to each source.
                   • The third shows the degrees of freedom (df) associated with each source.
                   • The fourth shows the Mean Squares (MS), which is the ratio SS/df.
                   • The fifth shows the F statistic, which is the ratio of the MS's.

The p-value is a function (fcdf) of F. As F increases the p-value decreases.

The second figure displays box plots of each column of X. Large differences in the center lines of the box plots correspond to large values of F and correspondingly small p-values.

Examples   The five columns of x are the constants one through five plus a random normal disturbance with mean zero and standard deviation one. The ANOVA procedure detects the difference in the column means with great assurance. The probability (p) of observing the sample x by chance given that there is no difference in the column means is less than 6 in 100,000.

```
x = meshgrid(1:5)

x =

1      2      3      4      5
1      2      3      4      5
1      2      3      4      5
1      2      3      4      5

x = x + normrnd(0, 1, 5, 5)

x =

2.1650     3.6961     1.5538     3.6400     4.9551
1.6268     2.0591     2.2988     3.8644     4.2011
1.0751     3.7971     4.2460     2.6507     4.2348
1.3516     2.2641     2.3610     2.7296     5.8617
0.3035     2.8717     3.5774     4.9846     4.9438

p = anova1(x)

p =

    5.9952e-05
```

ANOVA Table

Source	SS	df	MS	F
Columns	32.93	4	8.232	11.26
Error	14.62	20	0.7312	
Total	47.55	24		
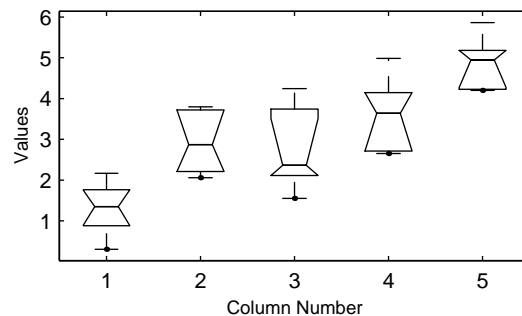
The following example comes from a study of material strength in structural beams Hogg (1987). The vector, strength, measures the deflection of a beam in thousandths of an inch under 3,000 pounds of force. Stronger beams deflect less. The civil engineer performing the study wanted to determine whether the strength of steel beams was equal to the strength of two more expensive alloys. Steel is coded 1 in the vector, alloy. The other materials are coded 2 and 3.

```
strength = [82 86 79 83 84 85 86 87 74 82 78 75 76 77 79 ...
79 77 78 82 79];
alloy =[1 1 1 1 1 1 1 1 2 2 2 2 2 2 3 3 3 3 3 3];
```

Though alloy is sorted in this example, you do not need to sort the grouping variable.

```
p = anova1(strength, alloy)
p =

1.5264e-04
```

ANOVA Table

Source	SS	df	MS	F
Columns	184.8	2	92.4	15.4
Error	102	17	6	
Total	286.8	19		
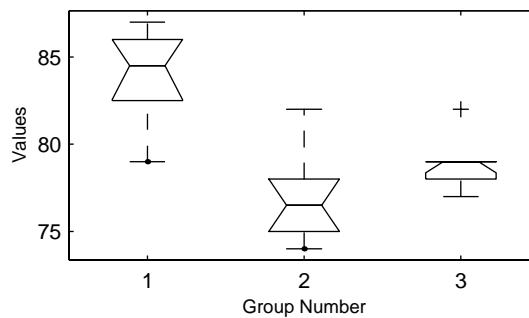
The p-value indicates that the three alloys are significantly different. The box plot confirms this graphically and shows that the steel beams deflect more than the more expensive alloys.

Reference   Hogg, R. V. and J. Ledolter. *Engineering Statistics.* MacMillan Publishing Company, 1987.

Purpose   Two-way Analysis of Variance (ANOVA).

Syntax   p = anova2(X, reps)

Description   anova2(X, reps) performs a balanced two-way ANOVA for comparing the means of two or more columns and two or more rows of the sample in X. The data in different columns represent changes in one factor. The data in different rows represent changes in the other factor. If there is more than one observation per row-column pair, then the argument, reps, indicates the number of observations per "cell."

The matrix below shows the format for a set-up where the column factor has two levels, the row factor has three levels, and there are two replications. The subscripts indicate row, column and replicate, respectively.

$$\begin{bmatrix} x_{111} & x_{121} \\ x_{112} & x_{122} \\ x_{211} & x_{221} \\ x_{212} & x_{222} \\ x_{311} & x_{321} \\ x_{312} & x_{322} \end{bmatrix}$$

anova2 returns the p-values for the null hypotheses that the means of the columns and the means of the rows of X are equal. If any p-value is near zero, this casts doubt on the null hypothesis and suggests that the means of the source of variability associated with that p-value are, in fact, different.

The choice of a limit for the p-value to determine whether the result is "statistically significant" is left to the researcher. It is common to declare a result significant if the p-value is less than 0.05 or 0.01.

anova2 also displays a figure showing the standard ANOVA table, which divides the variability of the data in X into three or four parts depending on the value of reps:

• The variability due to the differences among the column means.
• The variability due to the differences among the row means.
• The variability due to the interaction between rows and columns (if reps is greater than its default value of one.)
• The remaining variability not explained by any systematic source.

The ANOVA table has five columns.

• The first shows the source of the variability.
• The second shows the Sum of Squares (SS) due to each source.
• The third shows the degrees of freedom (df) associated with each source.
• The fourth shows the Mean Squares (MS), which is the ratio SS/df.
• The fifth shows the F statistics, which is the ratio of the mean squares.

The p-value is a function (fcdf) of F. As F increases the p-value decreases.

Examples   The data below comes from a study of popcorn brands and popper type (Hogg 1987). The columns of the matrix popcorn are brands (Gourmet, National, and Generic). The rows are popper type (Oil and Air.) The study popped a batch of

each brand three times with each popper. The values are the yield in cups of popped popcorn.

```
load popcorn
popcorn

popcorn =

    5.5000    4.5000    3.5000
    5.5000    4.5000    4.0000
    6.0000    4.0000    3.0000
    6.5000    5.0000    4.0000
    7.0000    5.5000    5.0000
    7.0000    5.0000    4.5000


p = anova2(popcorn, 3)

p =

    0.0000    0.0001    0.7462
```

ANOVA Table

Source	SS	df	MS	F
Columns	15.75	2	7.875	56.7
Rows	4.5	1	4.5	32.4
Interaction	0.08333	2	0.04167	0.3
Error	1.667	12	0.1389	
Total	22	17		

The vector, p, shows the p-values for the three brands of popcorn 0.0000, the two popper types 0.0001, and the interaction between brand and popper type 0.7462. These values indicate that both popcorn brand and popper type affect the yield of popcorn, but there is no evidence of a synergistic (interaction) effect of the two.

The conclusion is that you can get the greatest yield using the Gourmet brand and an Air popper (the three values located in popcorn(4:6, 1)).

Reference   Hogg, R. V. and J. Ledolter. *Engineering Statistics.* MacMillan Publishing Company, 1987.

barttest

Purpose   Bartlett's test for dimensionality.

Syntax   ndim = barttest(x, alpha)
                    [ndim, prob, chisquare] = barttest(x, alpha)

Description   ndim = barttest(x, alpha) returns the number of dimensions necessary to
                    explain the nonrandom variation in the the data matrix x, using the signifi-
                    cance probability alpha. The dimension is determined by a series of hypothesis
                    tests. The test for ndim = 1 tests the hypothesis that the variances of the data
                    values along each principal component are equal; the test for ndim = 2 tests
                    the hypothesis that the variances along the second through last components
                    are equal; and so on.

                    [ndim, prob, chisquare] = barttest(x, alpha) returns the number of dimen-
                    sions, the significance values for the hypothesis tests, and the χ^2 values asso-
                    ciated with the tests.

Example   x = mvnrnd([0 0], [1 0.99; 0.99 1], 20);
                    x(:, 3:4) = mvnrnd([0 0], [1 0.99; 0.99 1], 20);
                    x(:, 5:6) = mvnrnd([0 0], [1 0.99; 0.99 1], 20);
                    [ndim, prob] = barttest(x, 0.05)

                    ndim =

                            3

                    prob =

                                0
                                0
                                0
                           0.5081
                           0.6618
                           1.0000

See Also   princomp, pcacov, pcares

Purpose   Beta cumulative distribution function (cdf).

Syntax   P = betacdf(X, A, B)

Description betacdf(X, A, B) computes the beta cdf with parameters A and B at the values
in X. The arguments X, A, and B must all be the same size except that scalar
arguments function as constant matrices of the common size of the other argu-
ments.

The parameters A and B must both be positive and x must lie on the interval
[0 1].

The beta cdf is:

$$p = F(x|a, b) = \frac{1}{B(a, b)} \int_0^x t^{a-1}(1-t)^{b-1} dt$$

The result, p, is the probability that a single observation from a beta distribu-
tion with parameters a and b will fall in the interval [0 x].

Examples
```
x = 0.1:0.2:0.9;
a = 2;
b = 2;
p = betacdf(x, a, b)

p =

    0.0280    0.2160    0.5000    0.7840    0.9720

a = [1 2 3];
p = betacdf(0.5, a, a)

p =

    0.5000    0.5000    0.5000
```

betafit

Purpose   Parameter estimates and confidence intervals for beta distributed data.

Syntax   phat = betafit(x)
                [phat, pci] = betafit(x, alpha)

Description betafit computes the maximum likelihood estimates of the parameters of the
                beta distribution from the data in the vector, x. With two output parameters,
                betafit also returns confidence intervals on the parameters, in the form of a
                2-by-2 matrix. The first column of the matrix contains the lower and upper
                confidence bounds for parameter A, and the second column contains the confi-
                dence bounds for parameter B.

                The optional input argument, alpha, controls the width of the confidence
                interval. By default, alpha is 0.05 which corresponds to 95% confidence inter-
                vals.

Example   This example generates 100 beta distributed observations. The "true" parame-
                ters are 4 and 3 respectively. Compare these to the values in p. Note that the
                columns of ci both bracket the true parameters.

```
r = betarnd(4, 3, 100, 1);
[p, ci] = betafit(r, 0.01)

p =

    3.9010    2.6193

ci =

    2.5244    1.7488
    5.2777    3.4899
```

Reference   Hahn, Gerald J., & Shapiro, Samuel, S. *"Statistical Models in Engineering"*,
                Wiley Classics Library John Wiley & Sons, New York. 1994. p. 95.

See Also   betalike, mle

Purpose   Inverse of the beta cumulative distribution function.

Syntax   X = betainv(P, A, B)

Description   betainv(P, A, B) computes the inverse of the beta cdf with parameters A and B for the probabilities in P. The arguments P, A, and B must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The parameters A and B must both be positive and P must lie on the interval [0 1].

The beta inverse function in terms of the beta cdf is:

$$x = F^{-1}(p|a, b) = \{x : F(x|a, b) = p\}$$

$$where \quad p = F(x|a, b) = \frac{1}{B(a, b)}\int_0^x t^{a-1}(1-t)^{b-1}dt$$

The result, x, is the solution of the integral equation of the beta cdf with parameters a and b where you supply the desired probability p.

Algorithm   We use Newton's Method with modifications to constrain steps to the allowable range for x, i.e., [0 1].

Examples
```
p = [0.01 0.5 0.99];
x = betainv(p, 10, 5)

x =

    0.3726    0.6742    0.8981
```

betalike

Purpose   Negative beta log-likelihood function.

Syntax   logL = betalike(params, data)
                  [logL, info] = betalike(params, data)

Description   logL = betalike(params, data) returns the negative of the beta log-likelihood function for the two beta parameters, params, given the column vector, data. The length of logL is the length of data.

[logL, info] = betalike(params, data) also returns Fisher's information matrix, info. The diagonal elements of info are the asymptotic variances of their respective parameters.

betalike is a utility function for maximum likelihood estimation of the beta distribution. The likelihood assumes that all the elements in the data sample are mutually independent. Since betalike returns the negative gamma log-likelihood function, minimizing betalike using fmins is the same as maximizing the likelihood.

Example   This continues the example for betafit where we calculated estimates of the beta parameters for some randomly generated beta distributed data.

```
r = betarnd(4, 3, 100, 1);
[logl, info] = betalike([3.9010 2.6193], r)

logl =

  -33.0514


info =

    0.2856    0.1528
    0.1528    0.1142
```

See Also   betafit, fmins, gamlike, mle, weiblike

Purpose   Beta probability density function (pdf).

Syntax   Y = betapdf(X, A, B)

Description betapdf(X, A, B) computes the beta pdf with parameters A and B at the values
in X. The arguments X, A, and B must all be the same size except that scalar
arguments function as constant matrices of the common size of the other argu-
ments.

The parameters A and B must both be positive and X must lie on the interval
[0 1].

The probability density function for the beta distribution is:

$$y = f(x|a, b) = \frac{1}{B(a, b)} x^{a-1} (1-x)^{b-1} I_{(0, 1)}(x)$$

A *likelihood function* is the pdf viewed as a function of the parameters.
Maximum likelihood estimators (MLEs) are the values of the parameters that
maximize the likelihood function for a fixed value of *x*.

The uniform distribution on [0 1] is a degenerate case of the beta where
a = 1 and *b* = 1.

Examples   a = [0.5 1; 2 4]

                    a =

                        0.5000   1.0000
                        2.0000   4.0000

                    y = betapdf(0.5, a, a)

                    y =
                        0.6366   1.0000
                        1.5000   2.1875

betarnd

Purpose   Random numbers from the beta distribution.

Syntax   R = betarnd(A, B)
                 R = betarnd(A, B, m)
                 R = betarnd(A, B, m, n)

Description R = betarnd(A, B) generates beta random numbers with parameters A and B. The size of R is the common size of A and B if both are matrices. If either parameter is a scalar, the size of R is the size of the other.

R = betarnd(A, B, m) generates beta random numbers with parameters A and B. m is a 1-by-2 vector that contains the row and column dimensions of r.

R = betarnd(A, B, m, n) generates an m by n matrix of beta random numbers with parameters A and B.

Examples
```
a = [1 1; 2 2];
b = [1 2; 1 2];
r = betarnd(a, b)

r =

    0.6987    0.6139
    0.9102    0.8067

r = betarnd(10, 10, [1 5])

r =

    0.5974    0.4777    0.5538    0.5465    0.6327

r = betarnd(4, 2, 2, 3)

r =

    0.3943    0.6101    0.5768
    0.5990    0.2760    0.5474
```

Purpose   Mean and variance for the beta distribution.

Syntax   [M, V] = betastat(A, B)

Description   For the beta distribution,

- The mean is $\dfrac{a}{a+b}$

- The variance is $\dfrac{ab}{(a+b+1)(a+b)^2}$

Examples   If the parameters are equal, the mean is 1/2.

    a = 1: 6;
    [m, v] = betastat(a, a)

    m =

        0. 5000   0. 5000   0. 5000   0. 5000   0. 5000   0. 5000

    v =

        0. 0833   0. 0500   0. 0357   0. 0278   0. 0227   0. 0192

binocdf

Purpose   Binomial cumulative distribution function (cdf).

Syntax   Y = binocdf(X, N, P)

Description   binocdf(X, N, P) computes the binomial cdf with parameters N and P at the values in X. The arguments X, N, and P must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The parameter N must be a positive integer and P must lie on the interval [0 1].

The binomial cdf is:

$$y = F(x|n, p) = \sum_{i=0}^{x} \binom{n}{i} p^i q^{(1-i)} I_{(0, 1, \ldots, n)}(i)$$

The result, y, is the probability of observing up to x successes in n independent trials of where the probability of success in any given trial is p.

Examples   If a baseball team plays 162 games in a season and has a 50-50 chance of winning any game, then the probability of that team winning more than 100 games in a season is

    1 – binocdf(100, 162, 0.5)

The result is 0.001 (i.e., 1 – 0.999). If a team wins 100 or more games in a season, this result suggests that it is likely that the team's true probability of winning any game is greater than 0.5.

Purpose   Parameter estimates and confidence intervals for binomial data.

Syntax   phat = binofit(x, n)
                   [phat, pci] = binofit(x, n)
                   [phat, pci] = binofit(x, n, alpha)

Description   binofit(x, n) returns the estimate of the probability of success for the bino-
                   mial distribution given the data in the vector, x.

                   [phat, pci] = binofit(x, n) gives maximum likelihood estimate, phat, and
                   95% confidence intervals, pci.

                   [phat, pci] = binofit(x, n, alpha) gives 100(1–alpha) percent confidence
                   intervals. For example, alpha = 0.01 yields 99% confidence intervals.

Example   First we generate one binomial sample of 100 elements with a probability of
                   success of 0.6. Then, we estimate this probability given the results from the
                   sample. The 95% confidence interval, pci, contains the true value, 0.6.

                       r = binornd(100, 0.6);
                       [phat, pci] = binofit(r, 100)

                       phat =

                           0.5800

                       pci =

                           0.4771   0.6780

Reference   Johnson, Norman L., Kotz, Samuel, & Kemp, Adrienne W., *"Univariate
                   Discrete Distributions, Second Edition,"* Wiley 1992. pp. 124–130.

See Also   mle

binoinv

Purpose   Inverse of the binomial cumulative distribution function (cdf).

Syntax   X = binoinv(Y, N, P)

Description binoinv(Y, N, P) returns the smallest integer X such that the binomial cdf evaluated at X is equal to or exceeds Y. You can think of Y as the probability of observing X successes in N independent trials where P is the probability of success in each trial.

The parameter n must be a positive integer and both P and Y must lie on the interval [0 1]. Each X is a positive integer less than or equal to N.

Examples   If a baseball team has a 50-50 chance of winning any game, what is a reasonable range of games this team might win over a season of 162 games? We assume that a surprising result is one that occurs by chance once in a decade.

    binoinv([0.05 0.95], 162, 0.5)

    ans =

        71   91

This result means that in 90% of baseball seasons, a .500 team should win between 71 and 91 games.

Purpose   Binomial probability density function (pdf).

Syntax   Y = binopdf(X, N, P)

Description   binopdf(X, N, P) computes the binomial pdf with parameters N and P at the values in X. The arguments X, N and P must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

N must be a positive integer and P must lie on the interval [0 1].

The binomial pdf is

$$y = f(x|n, p) = \binom{n}{x} p^x q^{(1-x)} I_{(0, 1, \dots, n)}(x)$$

The result, y, is the probability of observing x successes in n independent trials of where the probability of success in any given trial is p.

Examples   A Quality Assurance inspector tests 200 circuit boards a day. If 2% of the boards have defects, what is the probability that the inspector will find no defective boards on any given day?

    binopdf(0, 200, 0.02)
    ans =

        0.0176

What is the most likely number of defective boards the inspector will find?

    y = binopdf([0:200], 200, 0.02);
    [x, i] = max(y);
    i

    i =

        5

binornd

Purpose	Random numbers from the binomial distribution.
Syntax	R = binornd(N, P) R = binornd(N, P, mm) R = binornd(N, P, mm, nn)
Description	R = binornd(N, P) generates binomial random numbers with parameters N and P. The size of R is the common size of N and P if both are matrices . If either parameter is a scalar, the size of R is the size of the other. R = binornd(N, P, mm) generates binomial random numbers with parameters N and P. mm is a 1-by-2 vector that contains the row and column dimensions of R. R = binornd(N, p, mm, nn) generates binomial random numbers with parameters N and P. The scalars mm and nn are the row and column dimensions of R.
Algorithm	The binornd function uses the direct method using the definition of the binomial distribution as a sum of Bernoulli random variables.

Examples

```
n = 10: 10: 60;
r1 = binornd(n, 1./n)

r1 =

        2       1       0       1       1       2

r2 = binornd(n, 1./n, [1 6])

r2 =

        0       1       2       1       3       1

r3 = binornd(n, 1./n, 1, 6)

r3 =

        0       1       1       1       0       3
```

Purpose   Mean and variance for the binomial distribution.

Syntax   [M, V] = binostat(N, P)

Description   For the binomial distribution

• The mean is *np*.

• The variance is *npq*.

Examples   n = logspace(1, 5, 5)

n =

                10   100   1000   10000   100000

[m, v] = binostat(n, 1./n)

m =

        1   1   1   1   1

v =

    0.9000   0.9900   0.9990   0.9999   1.0000

[m, v] = binostat(n, 1/2)

m =

             5   50   500   5000   50000

v =

    1.0e+04 *

    0.0003   0.0025   0.0250   0.2500   2.5000

bootstrp

Purpose   Bootstrap statistics through resampling of data.

Syntax   bootstat = bootstrp(nboot, '*bootfun*', d1, ...)
                [bootstat, bootsam] = bootstrp(...)

Description bootstrp(nboot, '*bootfun*', d1, ...) draws nboot bootstrap data samples
                and analyzes them using the function bootfun. nboot must be a positive
                integer. bootstrp passes the data d1, d2, etc., to bootfun.

                [bootstat, bootsam] = bootstrap(...) returns the bootstrap statistics in
                bootstat. Each row of bootstat contains the results of applying '*bootfun*' to
                one bootstrap sample. If '*bootfun*' returns a matrix, then this output is
                converted to a long vector for storage in bootstat. bootsam is a matrix of
                indices into the rows of the data matrix.

Example   Correlate the LSAT scores and and law-school GPA for 15 students. These 15
                data points are resampled to create 1000 different datasets, and the correlation
                between the two variables is computed for each dataset.

```
load lawdata
[bootstat, bootsam] = bootstrp(1000, 'corrcoef', lsat, gpa);
bootstat(1:5,:)

ans =

        1.0000      0.3021      0.3021      1.0000
        1.0000      0.6869      0.6869      1.0000
        1.0000      0.8346      0.8346      1.0000
        1.0000      0.8711      0.8711      1.0000
        1.0000      0.8043      0.8043      1.0000
```

```
bootsam(:, 1: 5)

ans =
```

4	7	5	12	8
1	11	10	8	4
11	9	12	4	2
11	14	15	5	15
15	13	6	6	2
6	8	4	3	8
8	2	15	8	6
13	10	11	14	5
1	7	12	14	14
1	11	10	1	8
8	14	2	14	7
11	12	10	8	15
1	4	14	8	1
6	1	5	5	12
2	12	7	15	12

```
hist(bootstat(:, 2))
```
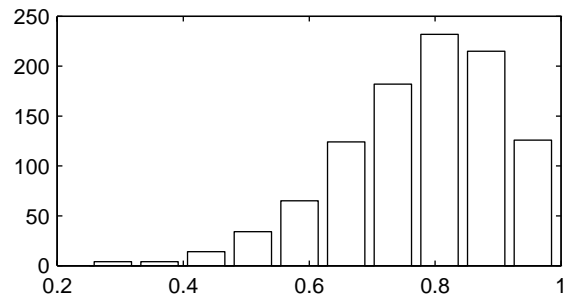

The histogram shows the variation of the correlation coefficient across all the bootstrap samples. The sample minimum is positive indicating that the relationship between LSAT and GPA is not accidental.

boxplot

Purpose   Box plots of a data sample.

Syntax   boxplot(X)
                  boxplot(X, notch)
                  boxplot(X, notch, '*sym*')
                  boxplot(X, notch, '*sym*', vert)
                  boxplot(X, notch, '*sym*', vert, whis)

Description   boxplot(X) produces a box and whisker plot for each column of X. The box has
                  lines at the lower quartile, median, and upper quartile values. The whiskers
                  are lines extending from each end of the box to show the extent of the rest of
                  the data. Outliers are data with values beyond the ends of the whiskers.

                  boxplot(X, notch) with notch = 1 produces a notched-box plot. Notches graph
                  a robust estimate of the uncertainty about the means for box to box compar-
                  ison. The default, notch = 0 produces a rectangular box plot.

                  boxplot(X, notch, '*sym*') where '*sym*' is a plotting symbol allows control of
                  the symbol for outliers if any (default = '+').

                  boxplot(X, notch, '*sym*', vert) with vert = 0 makes the boxes horizontal
                  (default: vert = 1, for vertical)

                  boxplot(X, notch, '*sym*', vert, whis) enables you to specify the length of the
                  "whiskers". whis defines the length of the whiskers as a function of the
                  inter-quartile range (default = 1.5 * IQR.) If whis = 0, then boxplot displays all
                  data values outside the box using the plotting symbol, '*sym*'.

Examples

```
x1 = normrnd(5, 1, 100, 1);
x2 = normrnd(6, 1, 100, 1);
x = [x1 x2];
boxplot(x, 1)
```
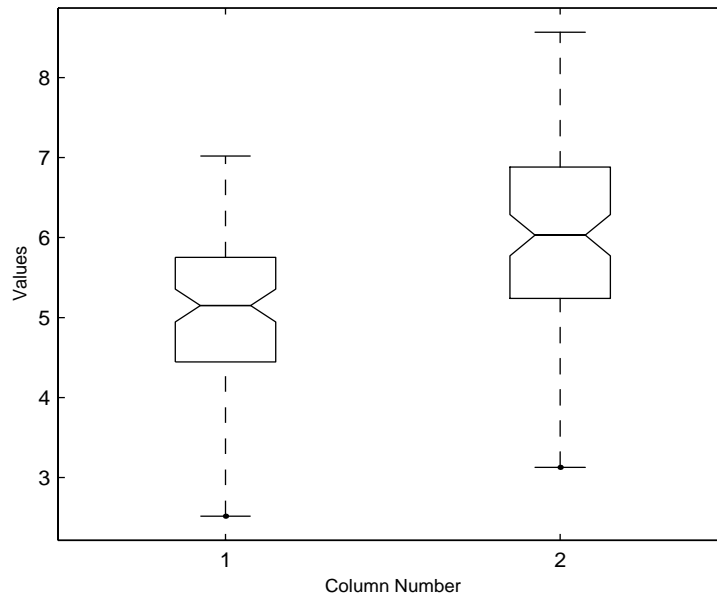

The difference between the means of the two columns of x is 1. We can detect this difference graphically since the notches do not overlap.

capable

Purpose   Process capability indices.

Syntax   p = capable(data, lower, upper)
                   [p, Cp, Cpk] = capable(data, lower, upper)

Description   capable(data, lower, upper) computes the probability that a sample, data, from some process falls outside the bounds specified in lower and upper.

The assumptions are that the measured values in the vector, data, are normally distributed with constant mean and variance and the the measurements are statistically independent.

[p, Cp, Cpk] = capable(data, lower, upper) also returns the capability indices Cp and Cpk.

Cp is the ratio of the range of the specifications to six times the estimate of the process standard deviation.

$$C_p = \frac{USL - LSL}{6\sigma}$$

For a process that has its average value on target, a *Cp* of one translates to a little more than one defect per thousand. Recently many industries have set a quality goal of one part per million. This would correspond to a *Cp* = 1.6. The higher the value of *Cp* the more capable the process.

For processes that do not maintain their average on target, *Cpk*, is a more descriptive index of process capability. *Cpk* is the ratio of difference between the process mean and the closer specification limit to three times the estimate of the process standard deviation.

$$C_{pk} = min\left(\frac{USL - \mu}{3\sigma}, \frac{\mu - LSL}{3\sigma}\right)$$

where the process mean is μ.

Example   Imagine a machined part with specifications requiring a dimension to be within 3 thousandths of an inch of nominal. Suppose that the machining process cuts too thick by one thousandth of an inch on average and also has a

standard deviation of one thousandth of an inch. What are the capability indices of this process?

```
data = normrnd(1, 1, 30, 1);
[p, Cp, Cpk] = capable(data, [-3 3]);
indices = [p Cp Cpk]

indices =

    0.0172    1.1144    0.7053
```

We expect 17 parts out of a thousand to be out-of-specification. Cpk is less than Cp because the process is not centered.

Reference   Montgomery, Douglas, *"Introduction to Statistical Quality Control,"* John Wiley & Sons 1991. pp. 369–374.

See Also   capaplot, histfit

capaplot

Purpose	Process capability plot.

Syntax

p = capaplot(data, specs)
[p, h] = capaplot(data, specs)

Description   capaplot(data, specs) fits the observations in the vector data assuming a normal distribution with unknown mean and variance and plots the distribution of a new observation (T distribution.) The part of the distribution between the lower and upper bounds contained in the two element vector, specs, is shaded in the plot.

[p, h] = capaplot(data, specs) returns the probability of the new observation being within specification in p and handles to the plot elements in h.

Example   Imagine a machined part with specifications requiring a dimension to be within 3 thousandths of an inch of nominal. Suppose that the machining process cuts too thick by one thousandth of an inch on average and also has a standard deviation of one thousandth of an inch.

```
data = normrnd(1, 1, 30, 1);
p = capaplot(data, [-3 3])
p =

    0.9784
```

The probability of a new observation being within specs is 97.84%.

Probability Between Limits is 0.9784
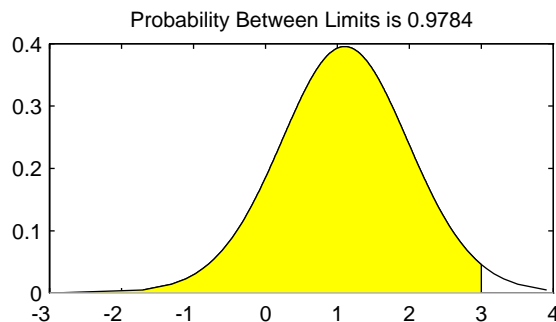
See Also   capable, histfit

Purpose   Read casenames from a file.

Syntax   names = caseread(filename)
                   names = caseread

Description   names = caseread(filename) reads the contents of filename and returns a
                   string matrix of names. filename is the name of a file in the current directory,
                   or the complete pathname of any file elsewhere. caseread treats each line as a
                   separate case.

                   names = caseread displays the File Open dialog box for interactive selection of
                   the input file.

Example   Use the file months.dat created using the function casewrite on the next page.

```
type months.dat

January
February
March
April
May

names = caseread('months.dat')

names =

January
February
March
April
May
```

See Also   tblread, gname, casewrite

casewrite

Purpose	Write casenames from a string matrix to a file.
Syntax	casewrite(strmat, filename) casewrite(strmat)
Description	casewrite(strmat, filename) writes the contents of strmat to filename. Each row of strmat represents one casename. filename is the name of a file in the current directory, or the complete pathname of any file elsewhere. casewrite writes each name to a separate line in filename. casewrite(strmat) displays the File Open dialog box for interactive specification of the output file.
Example	strmat = str2mat('January','February','March','April','May') strmat = January February March April May casewrite(strmat,'months.dat') type months.dat January February March April May
See Also	gname, caseread, tblwrite

Purpose   Computes a chosen cumulative distribution function (cdf).

Syntax   P = cdf(' *name*', X, A1, A2, A3)

Description   cdf is a utility routine allowing you to access all the cdfs in the Statistics Toolbox using the name of the distribution as a parameter.

P = cdf(' name', X, A1, A2, A3) returns a matrix of probabilities. name is a string containing the name of the distribution. X is a matrix of values, and A, A2, and A3 are matrices of distribution parameters. Depending on the distribution, some of the parameters may not be necessary.

The arguments X, A1, A2, and A3 must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

Examples   p = cdf('Normal', –2:2, 0, 1)

p =

        0.0228   0.1587   0.5000   0.8413   0.9772

p = cdf('Poisson', 0:5, 1:6)

p =

        0.3679   0.4060   0.4232   0.4335   0.4405   0.4457

See Also   icdf, mle, pdf, random

chi2cdf

Purpose   Chi-square (χ^2) cumulative distribution function (cdf).

Syntax   P = chi2cdf(X, V)

Description chi2cdf(X, V) computes the χ^2 cdf with parameter V at the values in X. The arguments X and V must be the same size except that a scalar argument functions as a constant matrix of the same size as the other argument.

The degrees of freedom,V, must be a positive integer.

The χ^2 cdf is:

$$p = F(x|\nu) = \int_0^x \frac{t^{(\nu-2)/2}e^{-t/2}}{2^{\frac{\nu}{2}}\Gamma(\nu/2)}dt$$

The result, p, is the probability that a single observation from the χ^2 distribution with degrees of freedom, ν, will fall in the interval [0 x].

The χ^2 density function with n degrees of freedom is the same as the gamma density function with parameters n/2 and 2.

Examples
```
probability = chi2cdf(5, 1:5)

probability =

    0.9747    0.9179    0.8282    0.7127    0.5841

probability = chi2cdf(1:5, 1:5)

probability =

    0.6827    0.6321    0.6084    0.5940    0.5841
```

Purpose   Inverse of the chi-square (χ^2) cumulative distribution function (cdf).

Syntax   X = chi2inv(P, V)

Description   chi2inv(P, V) computes the inverse of the χ^2 cdf with parameter V for the probabilities in P. The arguments P and V must be the same size except that a scalar argument functions as a constant matrix of the size of the other argument.

The degrees of freedom, V, must be a positive integer and P must lie in the interval [0 1].

We define the χ^2 inverse function in terms of the χ^2 cdf.

$$x = F^{-1}(p|\nu) = \{x : F(x|\nu) = p\}$$

$$where \quad p = F(x|\nu) = \int_0^x \frac{t^{(\nu-2)/2} e^{-t/2}}{2^{\frac{\nu}{2}} \Gamma(\nu/2)} dt$$

The result, x, is the solution of the integral equation of the χ^2 cdf with parameter ν where you supply the desired probability p.

Examples   Find a value that exceeds 95% of the samples from a χ^2 distribution with 10 degrees of freedom.

    x = chi2inv(0.95, 10)

    x =

       18.3070

You would observe values greater than 18.3 only 5% of the time by chance.

chi2pdf

Purpose Chi-square (χ^2) probability density function (pdf).

Syntax Y = chi2pdf(X, V)

Description chi2pdf(X, V) computes the χ^2 pdf with parameter V at the values in X. The arguments X and V must be the same size except that a scalar argument functions as a constant matrix of the same size of the other argument.

The degrees of freedom, V, must be a positive integer.

The chi-square pdf is:

$$y = f(x \mid \nu) = \frac{x^{(\nu-2)/2} e^{-x/2}}{2^{\frac{\nu}{2}} \Gamma(\nu/2)}$$

The χ^2 density function with n degrees of freedom is the same as the gamma density function with parameters $n/2$ and 2.

If x is standard normal, then x^2 is distributed χ^2 with one degree of freedom. If x_1, x_2, ..., x_n are n independent standard normal observations, then the sum of the squares of the x's is distributed χ^2 with n degrees of freedom.

Examples
```
nu = 1: 6;
x = nu;
y = chi2pdf(x, nu)

y =

    0.2420    0.1839    0.1542    0.1353    0.1220    0.1120
```

The mean of the χ^2 distribution is the value of the parameter, nu. The above example shows that the probability density of the mean falls as nu increases.

Purpose   Random numbers from the chi-square (χ^2) distribution.

Syntax   R = chi2rnd(V)
                    R = chi2rnd(V, m)
                    R = chi2rnd(V, m, n)

Description   R = chi2rnd(V) generates χ^2 random numbers with V degrees of freedom. The size of R is the size of V.

                    R = chi2rnd(V, m) generates χ^2 random numbers with V degrees of freedom. m is a 1-by-2 vector that contains the row and column dimensions of R.

                    R = chi2rnd(V, m, n) generates χ^2 random numbers with V degrees of freedom. The scalars m and n are the row and column dimensions of R.

Examples   Note that the first and third commands are the same but are different from the second command.

                    r = chi2rnd(1:6)

                    r =

                        0.0037   3.0377   7.8142   0.9021   3.2019   9.0729

                    r = chi2rnd(6, [1 6])

                    r =

                        6.5249   2.6226   12.2497   3.0388   6.3133   5.0388

                    r = chi2rnd(1:6, 1, 6)

                    r =

                        0.7638   6.0955   0.8273   3.2506   1.5469   10.9197

chi2stat

Purpose   Mean and variance for the chi-square (χ^2) distribution.

Syntax   [M, V] = chi2stat(NU)

Description For the χ^2 distribution,

- The mean is *n*
- The variance is *2n*.

Example
```
nu = 1: 10;
nu = nu' *nu;
[m, v] = chi2stat(nu)

m =
```

1	2	3	4	5	6	7	8	9	10
2	4	6	8	10	12	14	16	18	20
3	6	9	12	15	18	21	24	27	30
4	8	12	16	20	24	28	32	36	40
5	10	15	20	25	30	35	40	45	50
6	12	18	24	30	36	42	48	54	60
7	14	21	28	35	42	49	56	63	70
8	16	24	32	40	48	56	64	72	80
9	18	27	36	45	54	63	72	81	90
10	20	30	40	50	60	70	80	90	100

```
v =
```

2	4	6	8	10	12	14	16	18	20
4	8	12	16	20	24	28	32	36	40
6	12	18	24	30	36	42	48	54	60
8	16	24	32	40	48	56	64	72	80
10	20	30	40	50	60	70	80	90	100
12	24	36	48	60	72	84	96	108	120
14	28	42	56	70	84	98	112	126	140
16	32	48	64	80	96	112	128	144	160
18	36	54	72	90	108	126	144	162	180
20	40	60	80	100	120	140	160	180	200

Purpose　　　　Linear discriminant analysis.

Syntax　　　　`class = classify(sample, training, group)`

Description　　`class = classify(sample, training, group)` assigns each row of the data in
`sample` into one of the values of the vector `group`. `group` contains integers from
one to the number of groups. The training set is the matrix, `training`.

sample and `training` must have the same number of columns. `training` and
`group` must have the same number of rows. `class` is a vector with the same
number of rows as `sample`.

Example
```
load discrim
sample = ratings(idx,:);
training = ratings(1:200,:);
g = group(1:200);
class = classify(sample, training, g);
first5 = class(1:5)

first5 =

    2
    2
    2
    2
    2
```

See Also　　　mahal

combnk

Purpose	Enumeration of all combinations of *n* objects *k* at a time.
Syntax	C = combnk(v, k)
Description	C = combnk(v, k) returns all combinations of the *n* elements in v taken k at a time.
	C = combnk(v, k) produces a matrix, with k columns. Each row of C has k of the elements in the vector v. C has *n!/k!(n-k)!* rows.
	It is not feasible to use this function if v has more than about 10 elements.
Example	Combinations of characters from a string.

```
C = combnk('bradley', 4);
last5 = c(31:35, :)

last5 =

brdl
bray
brae
bral
brad
```

Combinations of elements from a numeric vector.

```
c = combnk(1:4, 2)

c =

    3    4
    2    4
    2    3
    1    4
    1    3
    1    2
```

Purpose   D-Optimal design of experiments – coordinate exchange algorithm.

Syntax   settings = cordexch(nfactors, nruns)
                   [settings, X] = cordexch(nfactors, nruns)
                   [settings, X] = cordexch(nfactors, nruns, 'model')

Description   settings = cordexch(nfactors, nruns) generates the factor settings matrix,
                   settings, for a D-Optimal design using a linear additive model with a constant
                   term. settings has nruns rows and nfactors columns.

                   [settings, X] = cordexch(nfactors, nruns) also generates the associated
                   design matrix, X.

                   [settings, X] = cordexch(nfactors, nruns, 'model') produces a design for
                   fitting a specified regression model. The input, 'model', can be one of these
                   strings:

                   • 'interaction' – includes constant, linear, and cross product terms.
                   • 'quadratic' – interactions plus squared terms.
                   • 'purequadratic' – includes constant, linear and squared terms.

Example   The D-optimal design for two factors in nine runs using a quadratic model is
                   the 3^2 factorial as shown below:

                       settings = cordexch(2, 9, 'quadratic')

                       settings =

                           −1   1
                            1   1
                            0   1
                            1   −1
                           −1   −1
                            0   −1
                            1   0
                            0   0
                           −1   0

See Also   rowexch, daugment, dcovary, hadamard, fullfact, ff2n

corrcoef

Purpose   Correlation coefficients.

Syntax   R = corrcoef(X)

Description R = corrcoef(X) returns a matrix of correlation coefficients calculated from
an input matrix whose rows are observations and whose columns are variables.
The element (i,j) of the matrix R is related to the corresponding element of
the covariance matrix C = cov(X) by

$$rR(i, j) = \frac{C(i, j))}{\sqrt{C(i, i)C(j, j)}}$$

See Also   cov, mean, std, var

corrcoef is a function in MATLAB.

Purpose Covariance matrix.

Syntax C = cov(X)
C = cov(x, y)

Description cov computes the covariance matrix. For a single vector, cov(x) returns a scalar containing the variance. For matrices, where each row is an observation, and each column a variable, cov(X) is the covariance matrix.

The variance function, var(X) is the same as diag(cov(X)).

The standard deviation function, std(X) is equivalent to sqrt(diag(cov(X))).

cov(x, y), where x and y are column vectors of equal length, gives the same result as cov([x y]).

Algorithm The algorithm for cov is

    [n, p] = size(X);
    X = X - ones(n, 1) * mean(X);
    Y = X'*X/(n-1);

See Also corrcoef, mean, std, var
xcov, xcorr in the Signal Processing Toolbox

cov is a function in MATLAB.

crosstab

Purpose   Cross-tabulation of two vectors.

Syntax   table = crosstab(col1, col2)
                   [table, chi2, p] = crosstab(col1, col2)

Description   table = crosstab(col1, col2) takes two vectors of positive integers and
                   returns a matrix, table, of cross-tabulations. The *ij*th element of table
                   contains the count of all instances where col1 = *i* and col2 = *j*.

                   [table, chi2, p] = crosstab(col1, col2) also returns the chisquare statistic,
                   chi2, for testing the independence of the rows and columns table. The scalar,
                   p, is the significance level of the test. Values of p near zero cast doubt on the
                   assumption of independence of the rows and columns of table.

Example   We generate 2 columns of 50 discrete uniform random numbers. The first
                   column has numbers from one to three. The second has only ones and twos. The
                   two columns are independent so we would be surprised if p were near zero.

```
r1 = unidrnd(3, 50, 1); r2 = unidrnd(2, 50, 1);
[table, chi2, p] = crosstab(r1, r2)

table =

    10      5
     8      8
     6     13

chi2 =

    4.1723

p =

    0.1242
```

                   The result, 0.1242, is not a surprise. A very small value of p would make us
                   suspect the "randomness" of the random number generator.

See Also   tabulate

Purpose   D-optimal augmentation of an experimental design.

Syntax   settings = daugment(startdes, nruns)
                 [settings, X] = daugment(startdes, nruns, '*model*')

Description settings = daugment(startdes, nruns) augments an initial experimental
                 design, startdes, with nruns new tests.

                 [settings, X] = daugment(startdes, nruns, '*model*') also supplies the
                 design matrix, X. The input, 'model', controls the order of the regression
                 model. By default, daugment assumes a linear additive model. Alternatively,
                 'model' can be any of these:

                 • 'interaction' – includes constant, linear, and cross product terms.
                 • 'quadratic' – interactions plus squared terms.
                 • 'purequadratic' – includes constant, linear and squared terms.

                 daugment uses the coordinate exchange algorithm.

Example   We add 5 runs to a 2^2 factorial design to allow us to fit a quadratic model.

                     startdes = [−1 −1; 1 −1; −1 1; 1 1];
                     settings = daugment(startdes, 5, 'quadratic')

                     settings =

                         −1   −1
                          1   −1
                         −1   1
                          1   1
                          1   0
                         −1   0
                          0   1
                          0   0
                          0   −1

                 The result is a 3^2 factorial design.

See Also   cordexch, dcovary, rowexch

dcovary

Purpose   D-Optimal design with specified fixed covariates.

Syntax   settings = dcovary(factors, covariates)
                   [settings, X] = dcovary(factors, covariates, '*model*')

Description   settings = dcovary(factors, covariates, '*model*') creates a D-Optimal
                   design subject to the constraint of fixed covariates for each run. factors is
                   the number of experimental variables you wish to control.

                   [settings, X] = dcovary(factors, covariates, '*model*') also creates the
                   associated design matrix, X. The input, 'model', controls the order of the
                   regression model. By default, dcovary assumes a linear additive model. Alter-
                   natively, 'model' can be any of these:

                   • 'interaction' – includes constant, linear, and cross product terms.
                   • 'quadratic' – interactions plus squared terms.
                   • 'purequadratic' – includes constant, linear and squared terms.

Example   Suppose we wish to block an 8 run experiment into 4 blocks of size 2 to fit a
                   linear model on two factors.

```
covariates = dummyvar([1 1 2 2 3 3 4 4]);
settings = dcovary(2, covariates(:, 1:3), 'linear')
settings =
```

1	1	1	0	0
–1	–1	1	0	0
–1	1	0	1	0
1	–1	0	1	0
1	1	0	0	1
–1	–1	0	0	1
–1	1	0	0	0
1	–1	0	0	0

The first two columns of the output matrix contain the settings for the two
factors. The last 3 columns are *dummy variable* codings for the 4 blocks.

See Also   daugment, cordexch

Purpose   Interactive graph of cdf (or pdf) for many probability distributions.

Syntax   disttool

Description   The disttool command sets up a graphic user interface for exploring the effects of changing parameters on the plot of a cdf or pdf. Clicking and dragging a vertical line on the plot allows you to evaluate the function over its entire domain interactively.

Evaluate the plotted function by typing a value in the x-axis edit box or dragging the vertical reference line on the plot. For cdfs, you can evaluate the inverse function by typing a value in the y-axis edit box or dragging the horizontal reference line on the plot. The shape of the pointer changes from an arrow to a crosshair when you are over the vertical or horizontal line to indicate that the reference line is draggable.

To change the distribution function choose from the pop-up menu of functions at the top left of the figure. To change from cdfs to pdfs, choose from the pop-up menu at the top right of the figure.

To change the parameter settings move the sliders or type a value in the edit box under the name of the parameter. To change the limits of a parameter, type a value in the edit box at the top or bottom of the parameter slider.

When you are done, press the **Close** button.

See Also   randtool

dummyvar

Purpose   Matrix of 0-1 "dummy" variables.

Syntax   D = dummyvar(group)

Description   D = dummyvar(group) generates a matrix, D, of 0-1 columns. D has one column
                     for each unique value in each column of the matrix group. Each column of
                     group contains positive integers that indicate the group membership of an indi-
                     vidual row.

Example   Suppose we are studying the effects of two machines and three operators on a
                     process. The first column of group would have the values one or two depending
                     on which machine was used. The second column of group would have the values
                     one, two, or three depending on which operator ran the machine.

```
group = [1 1; 1 2; 1 3; 2 1; 2 2; 2 3];
D = dummyvar(group)

D =

    1    0    1    0    0
    1    0    0    1    0
    1    0    0    0    1
    0    1    1    0    0
    0    1    0    1    0
    0    1    0    0    1
```

See Also   pinv, regress

Purpose   Plot error bars along a curve.

Syntax   errorbar(X, Y, L, U, symbol)
                 errorbar(X, Y, L)
                 errorbar(Y, L)

Description errorbar(X, Y, L, U, symbol) plots X versus Y with error bars specified by L and U. X, Y, L, and U must be the same length. If X, Y, L, and U are matrices, then each column produces a separate line. The error bars are each drawn a distance of U(i) above and L(i) below the points in (X, Y). symbol is a string that controls the line type, plotting symbol, and color of the error bars.

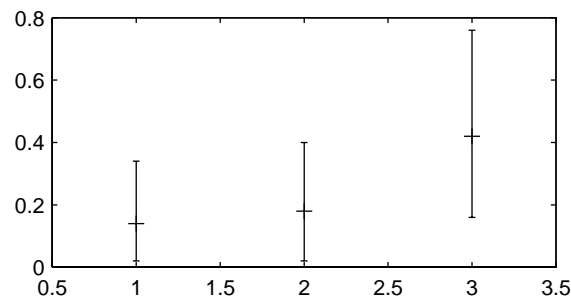errorbar(X, Y, L) plots X versus Y with symmetric error bars about Y.

errorbar(Y, L) plots Y with error bars [Y–L Y+L].

Example
```
lambda = (0.1:0.2:0.5);
r = poissrnd(lambda(ones(50, 1), :));
[p, pci] = poissfit(r, 0.001);
L = p - pci(1, :)
U = pci(2, :) - p
errorbar(1:3, p, L, U, '+')

L =
    0.1200    0.1600    0.2600

U =
    0.2000    0.2200    0.3400
```
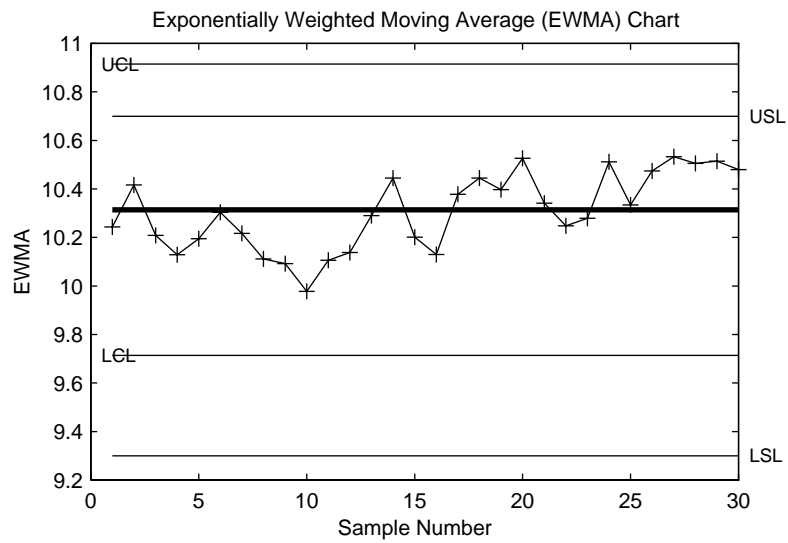

See Also   errorbar is a function in MATLAB.

ewmaplot

Purpose	Exponentially weighted moving average chart for SPC.
Syntax	ewmaplot(data)
	ewmaplot(data, lambda)
	ewmaplot(data, lambda, alpha)
	ewmaplot(data, lambda, alpha, specs)
	h = ewmaplot(...)

Description ewmaplot(data) produces an EWMA chart of the grouped responses in data. The rows of data contain replicate observations taken at a given time. The rows should be in time order.

ewmaplot(data, lambda) produces an EWMA chart of the grouped responses in data, and specifes how much the current prediction is influenced by past observations. Higher values of lambda give more weight to past observations. By default, lambda = 0.4;lambda must be between 0 and 1.

ewmaplot(data, lambda, alpha) produces an EWMA chart of the grouped responses in data, and specifies the significance level of the upper and lower plotted confidence limits. alpha is 0.01 by default. This means that roughly 99% of the plotted points should fall between the control limits.

ewmaplot(data, lambda, alpha, specs) produces an EWMA chart of the grouped responses in data, and specifies a two element vector, specs, for the lower and upper specification limits of the response. Note

h = ewmaplot(...) returns a vector of handles to the plotted lines.

Example Consider a process with a slowly drifting mean over time. An EWMA chart is preferable to an x-bar chart for monitoring this kind of process. This simulation demonstrates an EWMA chart for a slow linear drift.

```
t = (1:30)';
r = normrnd(10+0.02*t(:,ones(4,1)),0.5);
ewmaplot(r,0.4,0.01,[9.3 10.7])
```

Exponentially Weighted Moving Average (EWMA) Chart

Reference   Montgomery, Douglas, *Introduction to Statistical Quality Control,* John Wiley & Sons 1991. p. 299.

See Also   xbarplot, schart

expcdf

Purpose   Exponential cumulative distribution function (cdf).

Syntax   P = expcdf(X, MU)

Description   expcdf(X, MU) computes the exponential cdf with parameter settings MU at the values in X. The arguments X and MU must be the same size except that a scalar argument functions as a constant matrix of the same size of the other argument.

The parameter MU must be positive.

The exponential cdf is:

$$p = F(x|\mu) = \int_0^x \frac{1}{\mu} e^{-\frac{t}{\mu}} dt = 1 - e^{-\frac{x}{\mu}}$$

The result, p, is the probability that a single observation from an exponential distribution will fall in the interval [0 x].

Examples   The median of the exponential distribution is $\mu*\log(2)$. Demonstrate this fact.

    mu = 10: 10: 60;
    p = expcdf(log(2)*mu, mu)

    p =

        0.5000   0.5000   0.5000   0.5000   0.5000   0.5000

What is the probability that an exponential random variable will be less than or equal to the mean, μ?

    mu = 1: 6;
    x = mu;
    p = expcdf(x, mu)

    p =

        0.6321   0.6321   0.6321   0.6321   0.6321   0.6321

Purpose   Parameter estimates and confidence intervals for exponential data.

Syntax   muhat = expfit(x)
                     muhat = expfit(x)
                     [muhat, muci] = expfit(x, alpha)

Description   muhat = expfit(x) returns the estimate of the parameter, μ, of the exponential distribution given the data, x.

                     [muhat, muci] = expfit(x) also returns the 95% confidence interval in muci.

                     [muhat, muci] = expfit(x, alpha) gives 100(1–alpha) percent confidence intervals. For example, alpha = 0.01 yields 99% confidence intervals.

Example   We generate 100 independent samples of exponential data with $\mu = 3$. muhat is an estimate of true_mu and muci is a 99% confidence interval around muhat. Notice that muci contains true_mu.

```
true_mu = 3;
[muhat, muci] = expfit(r, 0.01)

muhat =

    2.8835

muci =

    2.1949
    3.6803
```

See Also   betafit, binofit, gamfit, normfit, poissfit, unifit, weibfit

expinv

Purpose   Inverse of the exponential cumulative distribution function (cdf).

Syntax   X = expinv(P, MU)

Description   expinv(P, MU) computes the inverse of the exponential cdf with parameter MU
for the probabilities in P. The arguments P and MU must be the same size except
that a scalar argument functions as a constant matrix of the size of the other
argument.

The parameter MU must be positive and P must lie on the interval [0 1].

The inverse of the exponential cdf is:

$$x = F(p|\mu) = -\mu \ln(1 - p)$$

The result, x, is the value such that the probability is p that an observation
from an exponential distribution with parameter μ will fall in the range [0 x].

Examples   Let the lifetime of light bulbs be exponentially distributed with mu equal to 700
hours. What is the median lifetime of a bulb?

    expinv(0.50, 700)

    ans =

      485.2030

So, suppose you buy a box of "700 hour" light bulbs. If 700 hours is mean life of
the bulbs, then half them will burn out in less than 500 hours.

Purpose   Exponential probability density function (pdf).

Syntax   Y = exppdf(X, MU)

Description exppdf(X, MU) computes the exponential pdf with parameter settings MU at the values in X. The arguments X and MU must be the same size except that a scalar argument functions as a constant matrix of the same size of the other argument.

The parameter MU must be positive.

The exponential pdf is:

$$y = f(x|\mu) = \frac{1}{\mu} e^{-\frac{x}{\mu}}$$

The exponential pdf is the gamma pdf with its first parameter (a) equal to 1.

The exponential distribution is appropriate for modeling waiting times when you think the probability of waiting an additional period of time is independent of how long you've already waited. For example, the probability that a light bulb will burn out in its next minute of use is relatively independent of how many minutes it has already burned.

Examples   y = exppdf(5, 1: 5)

y =

    0. 0067   0. 0410   0. 0630   0. 0716   0. 0736

y = exppdf(1: 5, 1: 5)

y =

    0. 3679   0. 1839   0. 1226   0. 0920   0. 0736

exprnd

Purpose	Random numbers from the exponential distribution.
Syntax	R = exprnd(MU) R = exprnd(MU, m) R = exprnd(MU, m, n)

Description R = exprnd(MU) generates exponential random numbers with mean MU. The size of R is the size of MU.

R = exprnd(MU, m) generates exponential random numbers with mean MU. m is a 1-by-2 vector that contains the row and column dimensions of R.

R = exprnd(MU, m, n) generates exponential random numbers with mean MU. The scalars m and n are the row and column dimensions of R.

Examples

```
n1 = exprnd(5: 10)

n1 =

    7. 5943    18. 3400     2. 7113     3. 0936     0. 6078     9. 5841

n2 = exprnd(5: 10, [1  6])

n2 =

    3. 2752     1. 1110    23. 5530    23. 4303     5. 7190     3. 9876

n3 = exprnd(5, 2, 3)

n3 =

   24. 3339    13. 5271     1. 8788
    4. 7932     4. 3675     2. 6468
```

Purpose   Mean and variance for the exponential distribution.

Syntax   [M, V] = expstat(MU)

Description   For the exponential distribution,

- The mean is μ.

- The variance is μ^2.

Examples   [m, v] = expstat([1 10 100 1000])

m =

              1   10   100   1000

v =

              1   100   10000   1000000

fcdf

Purpose   F cumulative distribution function (cdf).

Syntax   P = fcdf(X, V1, V2)

Description fcdf(X, V1, V2) computes the F cdf with parameters V1 and V2 at the values in
X. The arguments X, V1 and V2 must all be the same size except that scalar
arguments function as constant matrices of the common size of the other argu-
ments.

Parameters V1 and V2 must contain positive integers.

The F cdf is:

$$F(x|\nu_1,\nu_2) = \int_0^x \frac{\Gamma\left[\frac{(\nu_1+\nu_2)}{2}\right]}{\Gamma\left(\frac{\nu_1}{2}\right)\Gamma\left(\frac{\nu_2}{2}\right)}\left(\frac{\nu_1}{\nu_2}\right)^{\frac{\nu_1}{2}}\frac{t^{\frac{\nu_1-2}{2}}}{\left[1+\left(\frac{\nu_1}{\nu_2}\right)t\right]^{\frac{\nu_1+\nu_2}{2}}}dt$$

The result, p, is the probability that a single observation from an F distribution
with parameters $v1$ and $v2$ will fall in the interval [0 x].

Examples   This example illustrates an important and useful mathematical identity for the
F distribution.

```
nu1 = 1:5;
nu2 = 6:10;
x = 2:6;
F1 = fcdf(x, nu1, nu2)

F1 =

    0.7930    0.8854    0.9481    0.9788    0.9919

F2 = 1 - fcdf(1./x, nu2, nu1)

F2 =

    0.7930    0.8854    0.9481    0.9788    0.9919
```

Purpose   Two-level full-factorial designs.

Syntax   X = ff2n(n)

Description   X = ff2n(n) creates a two-level full-factorial design, X. n is the number of columns of X. The number of rows is 2^n.

Example   X = ff2n(3)

X =

0	0	0
0	0	1
0	1	0
0	1	1
1	0	0
1	0	1
1	1	0
1	1	1

X is the binary representation of the numbers from 0 to 2^n-1.

See Also   fullfact

finv

Purpose   Inverse of the F cumulative distribution function (cdf).

Syntax   X = finv(P, V1, V2)

Description   finv(P, V1, V2) computes the inverse of the F cdf with numerator degrees of freedom, V1, and denominator degrees of freedom, V2, for the probabilities in P. The arguments P, V1 and V2 must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The parameters V1 and V2 must both be positive integers and P must lie on the interval [0 1].

The F inverse function is defined in terms of the F cdf:

$$x = F^{-1}(p|v_1,v_2) = \{x{:}F(x|v_1,v_2) = p\}$$

$$where \quad p = F(x|v_1,v_2) = \int_0^x \frac{\Gamma\left[\frac{(v_1 + v_2)}{2}\right]}{\Gamma\left(\frac{v_1}{2}\right)\Gamma\left(\frac{v_2}{2}\right)}\left(\frac{v_1}{v_2}\right)^{\frac{v_1}{2}} \frac{t^{\frac{v_1-2}{2}}}{\left[1+\left(\frac{v_1}{v_2}\right)t\right]^{\frac{v_1+v_2}{2}}}dt$$

Examples   Find a value that should exceed 95% of the samples from an F distribution with 5 degrees of freedom in the numerator and 10 degrees of freedom in the denominator.

    x = finv(0.95, 5, 10)

    x =

       3.3258

You would observe values greater than 3.3258 only 5% of the time by chance.

Purpose   F probability density function (pdf).

Syntax   Y = fpdf(X, V1, V2)

Description   fpdf(X, V1, V2) computes the F pdf with parameters V1 and V2 at the values in
X. The arguments X, V1 and V2 must all be the same size except that scalar
arguments function as constant matrices of the common size of the other argu-
ments.

The parameters V1 and V2 must both be positive integers and X must lie on the
interval [0 ∞).

The probability density function for the F distribution is:

$$y = f(x|\nu_1, \nu_2) = \frac{\Gamma\left[\dfrac{(\nu_1 + \nu_2)}{2}\right]}{\Gamma\left(\dfrac{\nu_1}{2}\right)\Gamma\left(\dfrac{\nu_2}{2}\right)}\left(\dfrac{\nu_1}{\nu_2}\right)^{\frac{\nu_1}{2}} \frac{x^{\frac{\nu_1 - 2}{2}}}{\left[1 + \left(\dfrac{\nu_1}{\nu_2}\right)x\right]^{\frac{\nu_1 + \nu_2}{2}}}$$

Examples   y = fpdf(1: 6, 2, 2)

y =

    0. 2500   0. 1111   0. 0625   0. 0400   0. 0278   0. 0204

z = fpdf(3, 5: 10, 5: 10)

z =

    0. 0689   0. 0659   0. 0620   0. 0577   0. 0532   0. 0487

frnd

Purpose	Random numbers from the F distribution.
Syntax	R = frnd(V1, V2) R = frnd(V1, V2, m) R = frnd(V1, V2, m, n)

Description   R = frnd(V1, V2) generates random numbers from the F distribution with numerator degrees of freedom, V1, and denominator degrees of freedom, V2. The size of R is the common size of V1 and V2 if both are matrices. If either parameter is a scalar, the size of R is the size of the other parameter.

R = frnd(V1, V2, m) generates random numbers from the F distribution with parameters V1 and V2. m is a 1-by-2 vector that contains the row and column dimensions of R.

R = frnd(V1, V2, m, n) generates random numbers from the F distribution with parameters V1 and V2. The scalars m and n are the row and column dimensions of R.

Examples

```
n1 = frnd(1: 6, 1: 6)

n1 =

    0. 0022    0. 3121    3. 0528    0. 3189    0. 2715    0. 9539

n2 = frnd(2, 2, [2 3])

n2 =

    0. 3186    0. 9727    3. 0268
    0. 2052  148. 5816    0. 2191

n3 = frnd([1 2 3; 4 5 6], 1, 2, 3)

n3 =

    0. 6233    0. 2322   31. 5458
    2. 5848    0. 2121    4. 4955
```

Purpose   Mean and variance for the F distribution.

Syntax $[M, V] = fstat(V1, V2)$

Description   For the F distribution,

- The mean, for values of n_2 greater than 2, is:

$$\frac{v_2}{v_2 - 2}$$

- The variance, for values of n greater than 4, is:

$$\frac{2v_2^2(v_1 + v_2 - 2)}{v_1(v_2 - 2)^2(v_2 - 4)}$$

The mean of the F distribution is undefined if $v2$ is less than 3. The variance is undefined for $v2$ less than 5.

Examples   fstat returns NaN when the mean and variance are undefined.

    [m, v] = fstat(1: 5, 1: 5)

    m =

        NaN   NaN   3. 0000   2. 0000   1. 6667

    v =

        NaN   NaN   NaN   NaN   8. 8889

fsurfht

Purpose   Interactive contour plot of a function.

Syntax   fsurfht('*fun*', xlims, ylims)
                 fsurfht('*fun*', xlims, ylims, p1, p2, p3, p4, p5)

Description fsurfht('*fun*', xlims, ylims) is an interactive contour plot of the function
                 specified by the text variable fun. The *x*-axis limits are specified by xlims =
                 [xmin xmax] and the *y*-axis limits specified by ylims.

                 fsurfht('*fun*', xlims, ylims, p1, p2, p3, p4, p5) allows for five optional
                 parameters that you can supply to the function '*fun*'. The first two arguments
                 of fun are the *x*-axis variable and *y*-axis variable, respectively.

                 There are vertical and horizontal reference lines on the plot whose intersection
                 defines the current *x*-value and *y*-value. You can drag these dotted white refer-
                 ence lines and watch the calculated *z*-values (at the top of the plot) update
                 simultaneously. Alternatively, you can get a specific *z*-value by typing the
                 x-value and *y*-value into editable text fields on the *x*-axis and *y*-axis respec-
                 tively.

Example   Plot the Gaussian likelihood function for the gas.mat data.
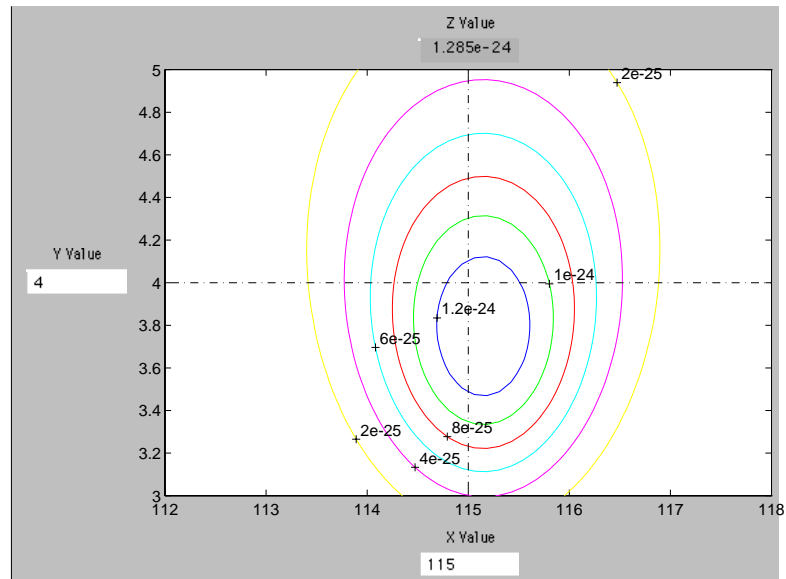
                     load gas

                 Write the M-file, gauslike.m.

```
function z = gauslike(mu, sigma, p1)
n = length(p1);
z = ones(size(mu));
for i = 1:n
z = z .* (normpdf(p1(i), mu, sigma));
end
```

gausl i ke calls normpdf treating the data sample as fixed and the parameters μ and σ as variables. Assume that the gas prices are normally distributed and plot the likelihood surface of the sample.

```
fsurfht('gauslike', [112 118], [3 5], price1)
```


The sample mean is the *x*-value at the maximum, but the sample standard deviation is not the *y*-value at the maximum.

```
mumax = mean(price1)

mumax =

   115.1500

sigmamax = std(price1)*sqrt(19/20)

sigmamax =

   3.7719
```

fullfact

Purpose   Full-factorial experimental design.

Syntax   design = fullfact(levels)

Description   design = fullfact(levels) give the factor settings for a full factorial design.
                   Each element in the vector levels specifies the number of unique values in the
                   corresponding column of design.

                   For example, if the first element of levels is 3, then the first column of design
                   contains only integers from 1 to 3.

Example   If levels = [2 4], fullfact generates an 8 run design with 2 levels in the first
                   column and 4 in the second column.

                       d = fullfact([2 4])

                       d =

                           1   1
                           2   1
                           1   2
                           2   2
                           1   3
                           2   3
                           1   4
                           2   4

See Also   ff2n, dcovary, daugment, cordexch

Purpose   Gamma cumulative distribution function (cdf).

Syntax   P = gamcdf(X, A, B)

Description gamcdf(X, A, B) computes the gamma cdf with parameters A and B at the values
in X. The arguments X, A, and B must all be the same size except that scalar
arguments function as constant matrices of the common size of the other argu-
ments.

Parameters A and B are positive.

The gamma cdf is:

$$p = F(x|a, b) = \frac{1}{b^a \Gamma(a)} \int_0^x t^{a-1} e^{-\frac{t}{b}} dt$$

The result, p, is the probability that a single observation from a gamma distri-
bution with parameters a and b will fall in the interval [0 x].

gammainc is the gamma distribution with a single parameter, a, with b at its
default value of 1.

Examples
```
a = 1: 6;
b = 5: 10;
prob = gamcdf(a. *b, a, b)

prob =

    0. 6321    0. 5940    0. 5768    0. 5665    0. 5595    0. 5543
```

The mean of the gamma distribution is the product of the parameters, $a*b$. In
this example as the mean increases, it approaches the median (i.e., the distri-
bution gets more symmetric).

gamfit

Purpose   Parameter estimates and confidence intervals for gamma distributed data.

Syntax   phat = gamfit(x)
                 [phat, pci] = gamfit(x)
                 [phat, pci] = gamfit(x, alpha)

Description   phat = gamfit(x) returns the maximum likelihood estimates of the parameters of the gamma distribution given the data in the vector, x.

                 [phat, pci] = gamfit(x) gives MLEs and 95% percent confidence intervals. The first row of pci is the lower bound of the confidence intervals; the last row is the upper bound.

                 [phat, pci] = gamfit(x, alpha) returns 100(1–alpha) percent confidence intervals. For example, alpha = 0.01 yields 99% confidence intervals.

Example   Note the 95% confidence intervals in the example bracket the "true" parameter values, 2 and 4, respectively.

```
a = 2;  b = 4;
r = gamrnd(a, b, 100, 1);
[p, ci] = gamfit(r)

p =

    2.1990    3.7426

ci =

    1.6840    2.8298
    2.7141    4.6554
```

Reference   Hahn, Gerald J., & Shapiro, Samuel, S. *"Statistical Models in Engineering,"* Wiley Classics Library John Wiley & Sons, New York. 1994. p. 88.

See Also   betafit, binofit, expfit, normfit, poissfit, unifit, weibfit

Purpose   Inverse of the gamma cumulative distribution function (cdf).

Syntax   X = gaminv(P, A, B)

Description   gaminv(P, A, B) computes the inverse of the gamma cdf with parameters A and
                  B for the probabilities in P. The arguments P, A and B must all be the same size
                  except that scalar arguments function as constant matrices of the common size
                  of the other arguments.

                  The parameters A and B must both be positive and P must lie on the interval
                  [0 1].

                  The gamma inverse function in terms of the gamma cdf is:

$$x = F^{-1}(p|a,b) = \{x : F(x|a,b) = p\}$$

$$where \quad p = F(x|a, b) = \frac{1}{b^a\Gamma(a)}\int_0^x t^{a-1}e^{-\frac{t}{b}}dt$$

Algorithm   There is no known analytic solution to the integral equation above. gaminv uses
                 an iterative approach (Newton's method) to converge to the solution.

Examples   This example shows the relationship between the gamma cdf and its inverse
                 function.

```
a = 1:5;
b = 6:10;
x = gaminv(gamcdf(1:5, a, b), a, b)

x =

    1.0000    2.0000    3.0000    4.0000    5.0000
```

gamlike

Purpose   Negative gamma log-likelihood function.

Syntax   logL = gamlike(params, data)
                [logL, info] = gamlike(params, data)

Description logL = gamlike(params, data) returns the negative of the gamma log-likeli-
                hood function for the parameters, params, given data. The length of the vector,
                logL, is the length of the vector, data.

                [logL, info] = gamlike(params, data) adds Fisher's information matrix,
                info. The diagonal elements of info are the asymptotic variances of their
                respective parameters.

                gamlike is a utility function for maximum likelihood estimation of the gamma
                distribution. Since gamlike returns the negative gamma log-likelihood func-
                tion, minimizing gamlike using fmins is the same as maximizing the likeli-
                hood.

Example   Continuing the example for gamfit:

                    a = 2; b = 3;
                    r = gamrnd(a, b, 100, 1);
                    [logL, info] = gamlike([2.1990 2.8069], r)

                    logL =

                      267.5585

                    info =

                        0.0690   –0.0790
                       –0.0790   0.1220

See Also   betalike, fmins, gamfit, mle, weiblike

Purpose   Gamma probability density function (pdf).

Syntax   Y = gampdf (X, A, B)

Description gampdf (X, A, B) computes the gamma pdf with parameters A and B at the values in X. The arguments X, A and B must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The parameters A and B must both be positive and X must lie on the interval $[0 \; \infty)$.

The gamma pdf is:

$$y = f(x|a, b) = \frac{1}{b^a \Gamma(a)} x^{a-1} e^{-\frac{x}{b}}$$

Gamma probability density function is useful in reliability models of lifetimes. The gamma distribution is more flexible than the exponential in that the probability of surviving an additional period may depend on age. Special cases of the gamma function are the exponential and χ^2 functions.

Examples   The exponential distribution is a special case of the gamma distribution.

```
mu = 1: 5;
y = gampdf (1, 1, mu)

y =

    0. 3679    0. 3033    0. 2388    0. 1947    0. 1637

y1 = exppdf (1, mu)

y1 =

    0. 3679    0. 3033    0. 2388    0. 1947    0. 1637
```

gamrnd

Purpose   Random numbers from the gamma distribution.

Syntax   R = gamrnd(A, B)
                   R = gamrnd(A, B, m)
                   R = gamrnd(A, B, m, n)

Description   R = gamrnd(A, B) generates gamma random numbers with parameters A and
                   B. The size of R is the common size of A and B if both are matrices. If either
                   parameter is a scalar, the size of R is the size of the other parameter.

                   R = gamrnd(A, B, m) generates gamma random numbers with parameters A and
                   B. m is a 1-by-2 vector that contains the row and column dimensions of R.

                   R = gamrnd(A, B, m, n) generates gamma random numbers with parameters A
                   and B. The scalars m and n are the row and column dimensions of R.

Examples   n1 = gamrnd(1: 5, 6: 10)

                     n1 =

                         9. 1132   12. 8431   24. 8025   38. 5960   106. 4164

                     n2 = gamrnd(5, 10, [1 5])

                     n2 =

                       30. 9486   33. 5667   33. 6837   55. 2014   46. 8265

                     n3 = gamrnd(2: 6, 3, 1, 5)

                     n3 =

                       12. 8715   11. 3068   3. 0982   15. 6012   21. 6739

Purpose   Mean and variance for the gamma distribution.

Syntax   [M, V] = gamstat(A, B)

Description   For the gamma distribution,

- the mean is ab

- the variance is ab^2.

Examples   [m, v] = gamstat(1:5, 1:5)

m =

        1   4   9   16   25

v =

        1   8   27   64   125

[m, v] = gamstat(1:5, 1./(1:5))

m =

        1   1   1   1   1

v =

        1.0000   0.5000   0.3333   0.2500   0.2000

geocdf

Purpose	Geometric cumulative distribution function (cdf).
Syntax	Y = geocdf (X, P)
Description	geocdf (X, P) computes the geometric cdf with probabilities, P, at the values in X. The arguments X and P must be the same size except that a scalar argument functions as a constant matrix of the same size as the other argument.

The parameter, P, is on the interval [0 1].

The geometric cdf is:

$$y = F(x|p) = \sum_{i=0}^{floor(x)} pq^i$$

$$where \quad q = 1 - p$$

The result, y, is the probability of observing up to x trials before a success when the probability of success in any given trial is p.

Examples	Suppose you toss a fair coin repeatedly. If the coin lands face up (heads), that is a success. What is the probability of observing three or fewer tails before getting a heads?

```
p = geocdf (3, 0. 5)

p =

    0. 9375
```

Purpose   Inverse of the geometric cumulative distribution function (cdf).

Syntax   X = geoinv(Y, P)

Description   geoinv(Y, P) returns the smallest integer X such that the geometric cdf evalu-
ated at X is equal to or exceeds Y. You can think of Y as the probability of
observing X successes in a row in independent trials where P is the probability
of success in each trial.

The arguments P and Y must lie on the interval [0 1]. Each X is a positive
integer.

Examples   The probability of correctly guessing the result of 10 coin tosses in a row is less
than 0.001 (unless the coin is not fair.)

    psychic = geoinv(0. 999, 0. 5)

    psychic =

        9

The example below shows the inverse method for generating random numbers
from the geometric distribution.

    rndgeo = geoinv(rand(2, 5), 0. 5)

    rndgeo =

        0   1   3   1   0
        0   1   0   2   0

geomean

Purpose   Geometric mean of a sample.

Syntax   m = geomean(X)

Description geomean calculates the geometric mean of a sample. For vectors, geomean(x) is the geometric mean of the elements in x. For matrices, geomean(X) is a row vector containing the geometric means of each column.

The geometric mean is:

$$m = \left[\prod_{i=1}^{n} x_i \right]^{\frac{1}{n}}$$

Examples   The sample average is greater than or equal to the geometric mean.

```
x = exprnd(1, 10, 6);
geometric = geomean(x)

geometric =

    0.7466    0.6061    0.6038    0.2569    0.7539    0.3478

average = mean(x)

average =

    1.3509    1.1583    0.9741    0.5319    1.0088    0.8122
```

See Also   mean, median, harmmean, trimmean

Purpose   Geometric probability density function (pdf).

Syntax   Y = geopdf (X, P)

Description   geocdf (X, P) computes the geometric pdf with probabilities, P, at the values in
                     X. The arguments X and P must be the same size except that a scalar argument
                     functions as a constant matrix of the same size as the other argument.

                     The parameter, P, is on the interval [0 1].

                     The geometric pdf is:

$$y = f(x|p) = pq^x I_{(0, 1, K)}(x)$$
$$where \quad q = 1 - p$$

Examples   Suppose you toss a fair coin repeatedly. If the coin lands face up (heads), that
                     is a success. What is the probability of observing exactly three tails before
                     getting a heads?

                         p = geopdf (3, 0. 5)

                         p =

                             0. 0625

geornd

Purpose	Random numbers from the geometric distribution.
Syntax	R = geornd(P)
	R = geornd(P, m)
	R = geornd(P, m, n)

Description The geometric distribution is useful when you wish to model the number of failed trials in a row before a success where the probability of success in any given trial is the constant P.

R = geornd(P) generates geometric random numbers with probability parameter, P . The size of R is the size of P.

R = geornd(P, m) generates geometric random numbers with probability parameter, P. m is a 1-by-2 vector that contains the row and column dimensions of R.

R = geornd(P, m, n) generates geometric random numbers with probability parameter, P. The scalars m and n are the row and column dimensions of R.

The parameter P must lie on the interval [0 1].

Examples

```
r1 = geornd(1 ./ 2.^(1:6))
r1 =

      2    10     2     5     2    60

r2 = geornd(0.01, [1 5])

r2 =

     65    18   334   291    63

r3 = geornd(0.5, 1, 6)

r3 =

      0     7     1     3     1     0
```

Purpose   Mean and variance for the geometric distribution.

Syntax   [M, V] = geostat(P)

Description   For the geometric distribution,

- The mean is $\dfrac{q}{p}$

- The variance is $\dfrac{q}{p^2}$

where $q = 1 - p$.

Examples
```
[m, v] = geostat(1. /(1: 6))

m =

     0    1. 0000    2. 0000    3. 0000    4. 0000    5. 0000

v =

     0    2. 0000    6. 0000    12. 0000    20. 0000    30. 0000
```

gline

Purpose   Interactively draw a line in a figure.

Syntax   gline(fig)
                     h = gline(fig)
                     gline

Description   gline(fig) draws a line segment by clicking the mouse at the two end-points
                     of the line segment in the figure, fig. A rubber band line tracks the mouse
                     movement.

                     h = gline(fig) returns the handle to the line in h.

                     gline with no input arguments draws in the current figure.

See Also   refline, gname

Purpose   Label plotted points with their case names or case number.

Syntax   gname('*cases*')
gname
h = gname('*cases*', line_handle)

Description   gname('*cases*') displays the graph window, puts up a cross-hair, and waits for
a mouse button or keyboard key to be pressed. Position the cross-hair with the
mouse and click once near each point that you want to label. When you are
done, press the **Return** or **Enter** key and the labels will appear at each point
that you clicked. '*cases*' is a string matrix. Each row is the case name of a data
point.

gname with no arguments labels each case with its case number.

h = gname(cases, line_handle) returns a vector of handles to the text objects
on the plot. Use the scalar, line_handle, to identify the correct line if there is
more than one line object on the plot.

Example   Let's use the city ratings datasets to find out which cities are the best and worst
for education and the arts.

```
load cities
education = ratings(:,6); arts = ratings(:,7);
plot(education,arts,'+')
gname(names)
```
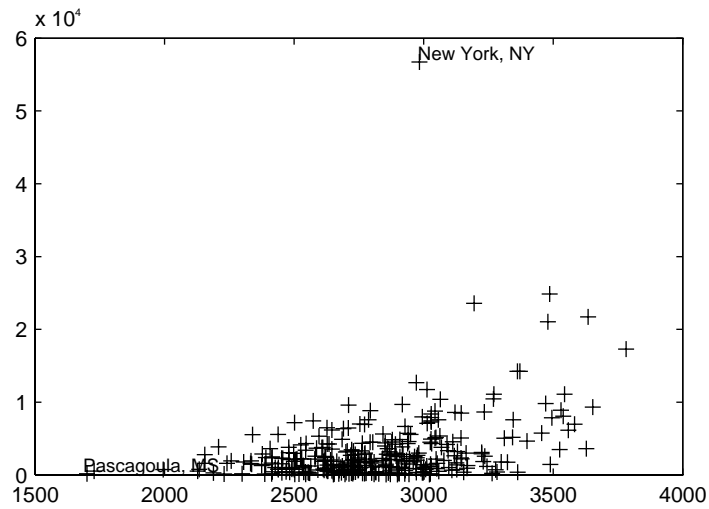

See Also   gtext

Purpose   Summary statistics by group.

Syntax   means = grpstats(X, group)
                     [means, sem, counts] = grpstats(X, group)
                     grpstats(x, group)
                     grpstats(x, group, alpha)

Description   means = grpstats(X, group) returns the means of each column of X by group.
                     X is a matrix of observations. group is a column of positive integers that indi-
                     cates the group membership of each row in X.

                     [means, sem, counts] = grpstats(x, group, alpha) supplies the standard
                     error of the mean in sem. counts is the same size as the other outputs. The *i-th*
                     row of counts contains the number of elements in the *i-th* group.

                     grpstats(x, group) displays a plot of the means versus index with 95% confi-
                     dence intervals about the mean value of for each value of index.

                     grpstats(x, group, alpha) plots $100(1 - alpha)\%$ confidence intervals around
                     each mean.

Example   We assign 100 observations to one of 4 groups. For each observation we
                     measure 5 quantities with *true means* from 1 to 5. grpstats allows us to
                     compute the means for each group.

```
group = unidrnd(4, 100, 1);
true_mean = 1:5;
true_mean = true_mean(ones(100, 1), :);
x = normrnd(true_mean, 1);
means = grpstats(x, group)

means =

    0.7947    2.0908    2.8969    3.6749    4.6555
    0.9377    1.7600    3.0285    3.9484    4.8169
    1.0549    2.0255    2.8793    4.0799    5.3740
    0.7107    1.9264    2.8232    3.8815    4.9689
```

See Also   tabulate, crosstab

harmmean

Purpose   Harmonic mean of a sample of data.

Syntax   m = harmmean(X)

Description   harmmean calculates the harmonic mean of a sample. For vectors,
                     harmmean(x) is the harmonic mean of the elements in x. For matrices,
                     harmmean(X) is a row vector containing the harmonic means of each column.

The harmonic mean is:

$$m = \frac{n}{\displaystyle\sum_{i=1}^{n} \frac{1}{x_i}}$$

Examples   The sample average is greater than or equal to the harmonic mean.

```
x = exprnd(1, 10, 6);
harmonic = harmmean(x)

harmonic =

    0.3382    0.3200    0.3710    0.0540    0.4936    0.0907

average = mean(x)

average =

    1.3509    1.1583    0.9741    0.5319    1.0088    0.8122
```

See Also   mean, median, geomean, trimmean

Purpose   Plot histograms.

Syntax   hist(y)
                   hist(y, nb)
                   hist(y, x)
                   [n, x] = hist(y, ...)

Description   hist calculates or plots histograms.

hist(y) draws a 10-bin histogram for the data in vector y. The bins are equally spaced between the minimum and maximum values in y.

hist(y, nb) draws a histogram with nb bins.

hist(y, x) draws a histogram using the bins in the vector, x.

[n, x] = hist(y), [n, x] = hist(y, nb), and [n, x] = hist(y, x) do not draw graphs, but return vectors n and x containing the frequency counts and the bin locations such that bar(x, n) plots the histogram. This is useful in situations where more control is needed over the appearance of a graph, for example, to combine a histogram into a more elaborate plot statement.

Examples   Generate bell-curve histograms from Gaussian data.

    x = -2.9:0.1:2.9;
    y = normrnd(0, 1, 1000, 1);
    hist(y, x)
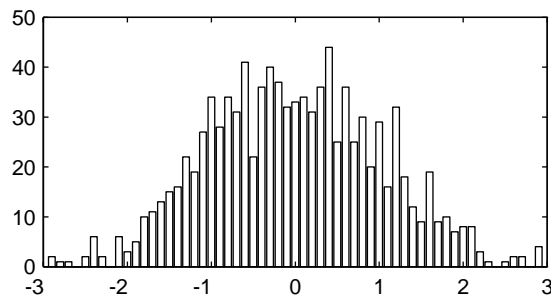
See Also   hist is a function in MATLAB.

histfit

Purpose	Histogram with superimposed normal density.
Syntax	histfit(data) histfit(data, nbins) h = histfit(data, nbins)
Description	histfit(data, nbins) plots a histogram of the values in the vector data using nbins bars in the histogram. With one input argument, nbins is set to the square root of the number of elements in data. h = histfit(data, nbins) returns a vector of handles to the plotted lines. h(1) is the handle to the histogram, h(2) is the handle to the density curve.
Example	r = normrnd(10, 1, 100, 1); histfit(r)

See Also   hist, normfit

Purpose   Hougen-Watson model for reaction kinetics.

Syntax   yhat = hougen(beta, X)

Description   yhat = hougen(beta, x) gives the predicted values of the reaction rate, yhat, as a function of the vector of parameters, beta, and the matrix of data, X. beta must have 5 elements and X must have three columns.

hougen is a utility function for rsmdemo.

The model form is

$$\hat{y} = \frac{\beta_1 x_2 - x_3 / \beta_5}{1 + \beta_2 x_1 + \beta_3 x_2 + \beta_4 x_3}$$

Reference   Bates, Douglas, and Watts, Donald, *Nonlinear Regression Analysis and Its Applications,* Wiley 1988. p. 271–272.

See Also   rsmdemo

hygecdf

Purpose   Hypergeometric cumulative distribution function (cdf).

Syntax   P = hygecdf(X, M, K, N)

Description   hygecdf(X, M, K, N) computes the hypergeometric cdf with parameters M, K, and N at the values in X. The arguments X, M, K, and N must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The hypergeometric cdf is:

$$ p = F(x | M, K, N) = \sum_{i=0}^{x} \frac{\binom{K}{i}\binom{M-K}{N-i}}{\binom{M}{N}} $$

The result, p, is the probability of drawing up to x items of a possible K in N drawings without replacement from a group of M objects.

Examples   Suppose you have a lot of 100 floppy disks and you know that 20 of them are defective. What is the probability of drawing zero to two defective floppies if you select 10 at random?

    p = hygecdf(2, 100, 20, 10)

    p =

        0.6812

Purpose   Inverse of the hypergeometric cumulative distribution function (cdf).

Syntax   X = hygeinv(P, M, K, N)

Description hygeinv(P, M, K, N) returns the smallest integer X such that the hypergeometric cdf evaluated at X equals or exceeds P. You can think of P as the probability of observing X defective items in N drawings without replacement from a group of M items where K are defective.

Examples   Suppose you are the Quality Assurance manager of a floppy disk manufacturer. The production line turns out floppy disks in batches of 1,000. You want to sample 50 disks from each batch to see if they have defects. You want to accept 99% of the batches if there are no more than 10 defective disks in the batch. What is the maximum number of defective disks should you allow in your sample of 50?

    x = hygeinv(0.99, 1000, 10, 50)

    x =

          3

What is the median number of defective floppy disks in samples of 50 disks from batches with 10 defective disks?

    x = hygeinv(0.50, 1000, 10, 50)

    x =

          0

hygepdf

Purpose Hypergeometric probability density function (pdf).

Syntax Y = hygepdf (X, M, K, N)

Description hygecdf (X, M, K, N) computes the hypergeometric pdf with parameters M, K, and N at the values in X. The arguments X, M, K, and N must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The parameters M, K, and N must be positive integers. Also X must be less than or equal to all the parameters and N must be less than or equal to M.

The hypergeometric pdf is:

$$y = f(x|M, K, N) = \frac{\binom{K}{x}\binom{M-K}{N-x}}{\binom{M}{N}}$$

The result, y, is the probability of drawing exactly x items of a possible K in n drawings without replacement from group of M objects.

Examples Suppose you have a lot of 100 floppy disks and you know that 20 of them are defective. What is the probability of drawing 0 through 5 defective floppy disks if you select 10 at random?

    p = hygepdf (0: 5, 100, 20, 10)

    p =

        0. 0951   0. 2679   0. 3182   0. 2092   0. 0841   0. 0215

Purpose   Random numbers from the hypergeometric distribution.

Syntax   R = hygernd(M, K, N)
                     R = hygernd(M, K, N, mm)
                     R = hygernd(M, K, N, mm, nn)

Description   R = hygernd(M, K, N) generates hypergeometric random numbers with param-
                     eters M, K and N. The size of R is the common size of M, K, and N if all are matrices.
                     If any parameter is a scalar, the size of R is the common size of the nonscalar
                     parameters.

                     R = hygernd(M, K, N, mm) generates hypergeometric random numbers with
                     parameters M, K, and N. mm is a 1-by-2 vector that contains the row and column
                     dimensions of R.

                     R = hygernd(M, K, N, mm, nn) generates hypergeometric random numbers with
                     parameters M, K, and N. The scalars mm and nn are the row and column dimen-
                     sions of R.

Examples   numbers = hygernd(1000, 40, 50)

                     numbers =

                          1

hygestat

Purpose   Mean and variance for the hypergeometric distribution.

Syntax   [MN, V] = hygestat(M, K, N)

Description   For the hypergeometric distribution,

- The mean is $N\dfrac{K}{M}$.

- The variance is $N\dfrac{K}{M}\dfrac{M-K}{M}\dfrac{M-N}{M-1}$.

Examples   The hypergeometric distribution approaches the binomial where $p = K/M$ as M goes to infinity.

```
[m, v] = hygestat(10.^(1:4), 10.^(0:3), 9)

m =

    0.9000    0.9000    0.9000    0.9000

v =

    0.0900    0.7445    0.8035    0.8094

[m, v] = binostat(9, 0.1)

m =

    0.9000

v =

    0.8100
```

Purpose   Inverse of a specified cumulative distribution function (icdf).

Syntax   X = icdf('*name*', P, A1, A2, A3)

Description   icdf is a utility routine allowing you to access all the inverse cdfs in the Statistics Toolbox using the name of the distribution as a parameter.

icdf('*name*', P, A1, A2, A3) returns a matrix of critical values, X. '*name*' is a string containing the name of the distribution. P is a matrix of probabilities, and A, B, and C are matrices of distribution parameters. Depending on the distribution some of the parameters may not be necessary.

The arguments P, A1, A2, and A3 must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

Examples   x = icdf('Normal', 0.1:0.2:0.9, 0, 1)

x =

    −1.2816   −0.5244   0   0.5244   1.2816

x = icdf('Poisson', 0.1:0.2:0.9, 1:5)

x =

    1   1   3   5   8

iqr

Purpose	Interquartile range (IQR) of a sample.
Syntax	$y = iqr(X)$
Description	$iqr(X)$ computes the difference between the 75th and the 25th percentiles of the sample in X. The IQR is a robust estimate of the spread of the data, since changes in the upper and lower 25% of the data do not affect it.
	If there are outliers in the data, then the IQR is more representative than the standard deviation as an estimate of the spread of the body of the data. The IQR is less efficient than the standard deviation as an estimate of the spread, when the data is all from the normal distribution.
	Multiply the IQR by 0.7413 to estimate σ (the second parameter of the normal distribution.)
Examples	This Monte Carlo simulation shows the relative efficiency of the IQR to the sample standard deviation for normal data.

```
x = normrnd(0, 1, 100, 100);
s = std(x);
s_IQR = 0.7413 * iqr(x);
efficiency = (norm(s - 1)./norm(s_IQR - 1)).^2

efficiency =

    0.3297
```

See Also	std, mad, range

Purpose   Sample kurtosis.

Syntax   k = kurtosis(X)

Description   k = kurtosis(X) returns the sample kurtosis of X. For vectors, kurtosis(x) is the kurtosis of the elements in the vector, x. For matrices kurtosis(X) returns the sample kurtosis for each column of X.

Kurtosis is a measure of how outlier-prone a distribution is. The kurtosis of the normal distribution is 3. Distributions that are more outlier-prone than the normal distribution have kurtosis greater than 3; distributions that are less outlier-prone have kurtosis less than 3.

The kurtosis of a distribution is defined as:

$$k = \frac{E(x-\mu)^4}{\sigma^4}$$

where $E(x)$ is the expected value of x.

Note: Some definitions of kurtosis subtract 3 from the computed value, so that the normal distribution has kurtosis of 0. The kurtosis function does not use this convention.

Example
```
X = randn([5 4])

X =

    1.1650    1.6961   -1.4462   -0.3600
    0.6268    0.0591   -0.7012   -0.1356
    0.0751    1.7971    1.2460   -1.3493
    0.3516    0.2641   -0.6390   -1.2704
   -0.6965    0.8717    0.5774    0.9846

k = kurtosis(X)

k =

    2.1658    1.2967    1.6378    1.9589
```

See Also   mean, moment, skewness, std, var

leverage

Purpose   Leverage values for a regression.

Syntax   h = leverage(DATA)
                 h = leverage(DATA, '*model*')

Description h = leverage(DATA) finds the leverage of each row (point) in the matrix, DATA for a linear additive regression model.

h = leverage(DATA, '*model*') finds the leverage on a regression, using a specified model type. '*model*' can be one of these strings:

- 'interaction' – includes constant, linear, and cross product terms.
- 'quadratic' – interactions plus squared terms.
- 'purequadratic' – includes constant, linear and squared terms.

Leverage is a measure of the influence of a given observation on a regression due to its location in the space of the inputs.

Example   One rule of thumb is to compare the leverage to *2p/n* where *n* is the number of observations and *p* is the number of parameters in the model. For the Hald dataset this value is 0.7692.

```
load hald
h = max(leverage(ingredients, 'linear'))

h =

    0.7004
```

Since 0.7004 < 0.7692, there are no high leverage points using this rule.

Algorithm   [Q, R] = qr(x2fx(DATA, 'model'));

                 leverage = (sum(Q'.*Q'))'

Reference   Goodall, C. R. (1993). *Computation using the QR decomposition.* Handbook in Statistics, Volume 9. Statistical Computing (C. R. Rao, ed.).   Amsterdam, NL Elsevier/North-Holland.

See Also   regstats

logncdf

Purpose   Lognormal cumulative distribution function.

Syntax   P = logncdf(X, MU, SIGMA)

Description   P = logncdf(X, MU, SIGMA) computes the lognormal cdf with mean MU and standard deviation SIGMA at the values in X.

The size of P is the common size of X, MU and SIGMA. A scalar input functions as a constant matrix of the same size as the other inputs.

The lognormal cdf is:

$$p = F(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}}\int_0^x \frac{e^{\frac{-(\ln(t)-\mu)^2}{2\sigma^2}}}{t}\,dt$$

Example
```
x = (0:0.2:10);
y = logncdf(x,0,1);
plot(x,y); grid; xlabel('x'); ylabel('p')
```
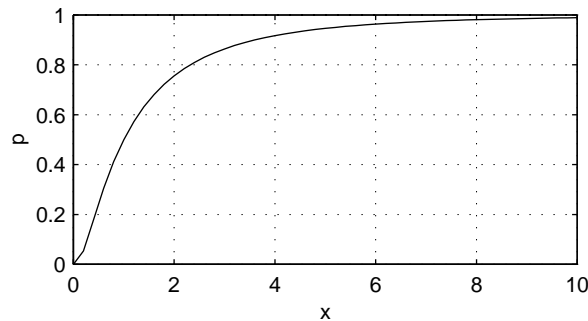

Reference   Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition,* Wiley 1993. p. 102–105.

See Also   cdf, logninv, lognpdf, lognrnd, lognstat

logninv

Purpose   Inverse of the lognormal cumulative distribution function (cdf).

Syntax   X = logninv(P, MU, SIGMA)

Description X = logninv(P, MU, SIGMA) computes the inverse lognormal cdf with mean MU and standard deviation SIGMA, at the probabilities in P.

The size of X is the common size of P, MU and SIGMA.

We define the lognormal inverse function in terms of the lognormal cdf.

$$x = F^{-1}(p|\mu, \sigma) = \{x : F(x|\mu, \sigma) = p\}$$

$$where \quad p = F(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}}\int_0^x \frac{e^{\frac{-(\ln(t) - \mu)^2}{2\sigma^2}}}{t}\, dt$$

Example
```
p = (0.005:0.01:0.995);
crit = logninv(p, 1, 0.5);
plot(p, crit)
xlabel('Probability'); ylabel('Critical Value'); grid
```
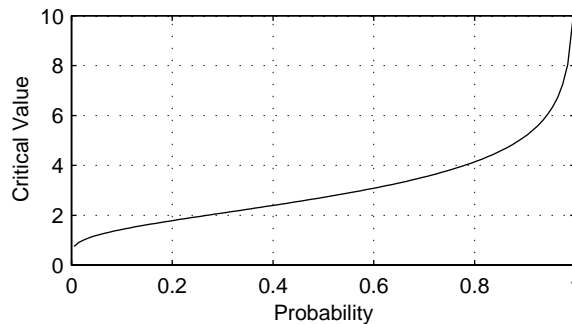

Reference   Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition,* Wiley 1993 p. 102–105.

See Also   icdf, logncdf, lognpdf, lognrnd, lognstat

Purpose   Lognormal probability density function (pdf).

Syntax   Y = lognpdf(X, MU, SIGMA)

Description Y = logncdf(X, MU, SIGMA) computes the lognormal cdf with mean MU and standard deviation SIGMA at the values in X.

The size of Y is the common size of X, MU and SIGMA. A scalar input functions as a constant matrix of the same size as the other inputs.

The lognormal pdf is:

$$y = f(x|\mu, \sigma) = \frac{1}{x\sigma\sqrt{2\pi}} e^{\frac{-(\ln(x)-\mu)^2}{2\sigma^2}}$$

Example
```
x = (0:0.02:10);
y = lognpdf(x, 0, 1);
plot(x, y); grid; xlabel('x'); ylabel('p')
```
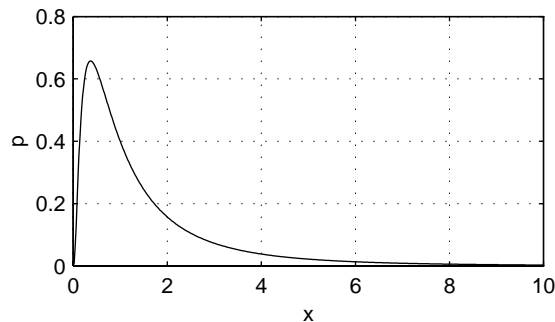

Reference   Mood, Alexander M., Graybill, Franklin A. and Boes, Duane C., *Introduction to the Theory of Statistics, Third Edition,* McGraw Hill 1974 p. 540–541.

See Also   logncdf, logninv, lognrnd, lognstat

lognrnd

Purpose	Random matrices from the lognormal distribution.

Syntax

R = lognrnd(MU, SIGMA)
R = lognrnd(MU, SIGMA, m)
R = lognrnd(MU, SIGMA, m, n)

Description

R = lognrnd(MU, SIGMA) generates lognormal random numbers with parameters, MU and SIGMA. The size of R is the common size of MU and SIGMA if both are matrices. If either parameter is a scalar, the size of R is the size of the other parameter.

R = lognrnd(MU, SIGMA, m) generates lognormal random numbers with parameters MU and SIGMA. m is a 1-by-2 vector that contains the row and column dimensions of R.

R = lognrnd(MU, SIGMA, m, n) generates lognormal random numbers with parameters MU and SIGMA. The scalars m and n are the row and column dimensions of R.

Example

```
r = lognrnd(0, 1, 4, 3)

r =

     3.2058    0.4983    1.3022
     1.8717    5.4529    2.3909
     1.0780    1.0608    0.2355
     1.4213    6.0320    0.4960
```

Reference

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition*, Wiley 1993 p. 102–105.

See Also

random, logncdf, logninv, lognpdf, lognstat

Purpose   Mean and variance for the lognormal distribution.

Syntax   [M, V] = lognstat(MU, SIGMA)

Description [M, V] = lognstat(MU, SIGMA) returns the mean and variance of the lognormal distribution with parameters MU and SIGMA. The size of M and V is the common size of MU and SIGMA if both are matrices. If either parameter is a scalar, the size of M and V is the size of the other parameter.

For the lognormal distribution, the mean is:

$$e^{\left(\mu + \frac{\sigma^2}{2}\right)}$$

The variance is:

$$e^{(2\mu + 2\sigma^2)} - e^{(2\mu + \sigma^2)}$$

Example   [m, v] = lognstat(0, 1)

m =

   1.6487

v =

   7.0212

Reference   Mood, Alexander M., Graybill, Franklin A. and Boes, Duane C., *Introduction to the Theory of Statistics, Third Edition*, McGraw Hill 1974 p. 540–541.

See Also   logncdf, logninv, lognrnd, lognrnd

lsline

Purpose	Least squares fit line(s).
Syntax	lsline h = lsline
Description	lsline superimposes the least squares line on each line object in the current axes (except LineStyles '–','––','.–'). h = lsline returns the handles to the line objects.
Example	y = [2 3.4 5.6 8 11 12.3 13.8 16 18.8 19.9]'; plot(y,'+'); lsline;

See Also	polyfit, polyval

Purpose   Mean absolute deviation (MAD) of a sample of data.

Syntax   y = mad(X)

Description   mad(X) computes the average of the absolute differences between a set of data
                   and the sample mean of that data. For vectors, mad(x) returns the mean abso-
                   lute deviation of the elements of x. For matrices, mad(X) returns the MAD of
                   each column of X.

                   The MAD is less efficient than the standard deviation as an estimate of the
                   spread, when the data is all from the normal distribution.

                   Multiply the MAD by 1.3 to estimate σ (the second parameter of the normal
                   distribution).

Examples   This example shows a Monte Carlo simulation of the relative efficiency of the
                   MAD to the sample standard deviation for normal data.

```
x = normrnd(0, 1, 100, 100);
s = std(x);
s_MAD = 1.3 * mad(x);
efficiency = (norm(s – 1)./norm(s_MAD – 1)).^2

efficiency =

    0.5972
```

See Also   std, range

mahal

Purpose   Mahalanobis distance.

Syntax   d = mahal (Y, X)

Description   mahal (Y, X) computes the Mahalanobis distance of each point (row) of the
                    matrix, Y, from the sample in the matrix, X.

                    The number of columns of Y must equal the number of columns in X, but the
                    number of rows may differ. The number of rows in X must exceed the number
                    of columns.

                    The Mahalanobis distance is a multivariate measure of the separation of a data
                    set from a point in space. It is the criterion minimized in linear discriminant
                    analysis.

Example   The Mahalanobis distance of a matrix, r, when applied to itself is a way to find
                    outliers.

```
r = mvnrnd([0 0], [1 0.9; 0.9 1], 100);
r = [r; 10 10];
d = mahal (r, r);
last6 = d(96:101)

last6 =

    1.1036
    2.2353
    2.0219
    0.3876
    1.5571
   52.7381
```

                    The last element is clearly an outlier.

See Also   classify

Purpose   Average or mean value of vectors and matrices.

Syntax   m = mean(X)

Description mean calculates the sample average.

$$\overline{x}_j = \frac{1}{n} \sum_{i=1}^{n} x_{ij}$$

For vectors, mean(x) is the mean value of the elements in vector x. For matrices, mean(X) is a row vector containing the mean value of each column.

Example   These commands generate five samples of 100 normal random numbers with mean, zero, and standard deviation, one. The sample averages in xbar are much less variable (0.00 ± 0.10).

    x = normrnd(0, 1, 100, 5);
    xbar = mean(x)

    xbar =

        0.0727   0.0264   0.0351   0.0424   0.0752

See Also   median, std, cov, corrcoef, var

mean is a function in the MATLAB Toolbox.

median

Purpose	Median value of vectors and matrices.
Syntax	m = median(X)

Description   median(X) calculates the median value, which is the 50th percentile of a sample. The median is a robust estimate of the center of a sample of data, since outliers have little effect on it.

For vectors, median(x) is the median value of the elements in vector x. For matrices, median(X) is a row vector containing the median value of each column. Since median is implemented using sort, it can be costly for large matrices.

Examples
```
xodd = 1:5;
modd = median(xodd)

modd =

      3

meven = median(xeven)

meven =

    2.5000
```

This example shows robustness of the median to outliers.

```
xoutlier = [x 10000];
moutlier = median(xoutlier)

moutlier =

      3
```

See Also   mean, std, cov, corrcoef

median is a function in MATLAB.

Purpose   Maximum likelihood estimation.

Syntax   phat = mle('*dist*', data)
                   [phat, pci] = mle('*dist*', data)
                   [phat, pci] = mle('*dist*', data, alpha)
                   [phat, pci] = mle('*dist*', data, alpha, p1)

Description   phat = mle('*dist*', data) returns the maximum likelihood estimates (MLEs) for the distribution specified in '*dist*' using the sample in the vector, data.

                   [phat, pci] = mle('*dist*', data) returns the MLEs and 95% percent confidence intervals.

                   [phat, pci] = mle('*dist*', data, alpha) returns the MLEs and 100(1−alpha) percent confidence intervals given the data and the specified alpha.

                   [phat, pci] = mle('*dist*', data, alpha, p1) is used for the binomial distribution only. p1 is the number of trials.

Example   rv = binornd(20, 0.75)
                       rv =

                            16

                       [p, pci] = mle('binomial', rv, 0.05, 20)

                       p =

                            0.8000

                       pci =

                            0.5634
                            0.9427

See Also   betafit, binofit, expfit, gamfit, normfit, poissfit, weibfit

moment

Purpose   Central moment of all orders.

Syntax   m = moment(X, order)

Description   m = moment(X, order) returns the central moment of X specified by the positive
                     integer, order. For vectors, moment(X, order) returns the central moment of
                     the specified order for the elements of x. For matrices, moment(X, order)
                     returns central moment of the specified order for each column.

                     Note that the central first moment is zero, and the second central moment is
                     the variance computed using a divisor of n rather than $n–1$, where n is the
                     length of the vector, x or the number of rows in the matrix, X.

                     The central moment of order k of a distribution is defined as:

                     $$m_n = E(x-\mu)^k$$

                     where $E(x)$ is the expected value of x.

Example   X = randn([6 5])

                     X =

1.1650	0.0591	1.2460	–1.2704	–0.0562
0.6268	1.7971	–0.6390	0.9846	0.5135
0.0751	0.2641	0.5774	–0.0449	0.3967
0.3516	0.8717	–0.3600	–0.7989	0.7562
–0.6965	–1.4462	–0.1356	–0.7652	0.4005
1.6961	–0.7012	–1.3493	0.8617	–1.3414

                     m = moment(X, 3)

                     m =

–0.0282	0.0571	0.1253	0.1460	–0.4486

See Also   kurtosis, mean, skewness, std, var

Purpose   Random matrices from the multivariate normal distribution.

Syntax   r = mvnrnd(mu, SIGMA, cases)

Description   r = mvnrnd(mu, SIGMA, cases) returns a matrix of random numbers chosen from the multivariate normal distribution with mean vector, mu, and covariance matrix, SIGMA. cases is the number of rows in r.

SIGMA is a symmetric positive definite matrix with size equal to the length of mu.

Example
```
mu = [2 3];
sigma = [1 1.5; 1.5 3];
r = mvnrnd(mu, sigma, 100);
plot(r(:,1), r(:,2), '+')
```
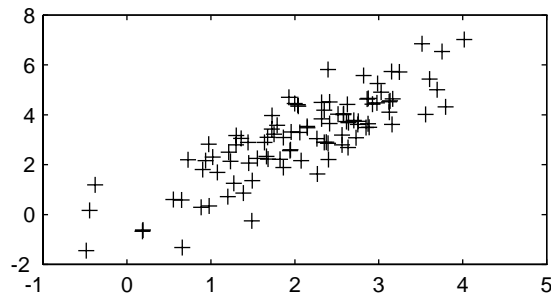

See Also   normrnd

nanmax

Purpose   Maximum ignoring NaNs.

Syntax   m = nanmax(a)
                   [m, ndx] = nanmax(a)
                   m = nanmax(a, b)

Description   m = nanmax(a) returns the maximum with NaNs treated as missing. For
                   vectors, nanmax(a) is the largest non-NaN element in a. For matrices,
                   nanmax(A) is a row vector containing the maximum non-NaN element from each
                   column.

                   [m, ndx] = nanmax(a) also returns the indices of the maximum values in vector
                   ndx.

                   m = nanmax(a, b) returns the larger of a or b, which must match in size.

Example   m = magic(3);
                   m([1 6 8]) = [NaN NaN NaN]

                   m =

                       NaN   1   6
                         3   5   NaN
                         4   NaN   2

                   [nmax, maxidx] = nanmax(m)

                   nmax =

                         4   5   6

                   maxidx =

                         3   2   1

See Also   nanmin, nanmean, nanmedian, nanstd, nansum

Purpose   Mean ignoring NaNs

Syntax   y = nanmean(X)

Description   nanmean(X) the average treating NaNs as missing values.

For vectors, nanmean(x) is the mean of the non-NaN elements of x. For matrices, nanmean(X) is a row vector containing the mean of the non-NaN elements in each column.

Example
```
m = magic(3);
m([1 6 8]) = [NaN NaN NaN]

m =

    NaN      1      6
      3      5    NaN
      4    NaN      2

nmean = nanmean(m)

nmean =

    3.5000    3.0000    4.0000
```

See Also   nanmin, nanmax, nanmedian, nanstd, nansum

nanmedian

Purpose   Median ignoring NaNs

Syntax   y = nanmedian(X)

Description   nanmedian(X) the median treating NaNs as missing values.

For vectors, nanmedian(x) is the median of the non-NaN elements of x. For matrices, nanmedian(X) is a row vector containing the median of the non-NaN elements in each column of X.

Example
```
m = magic(4);
m([1 6 9 11]) = [NaN NaN NaN NaN]

m =

    NaN      2    NaN     13
      5    NaN     10      8
      9      7    NaN     12
      4     14     15      1

nmedian = nanmedian(m)

nmedian =

     5.0000     7.0000    12.5000    10.0000
```

See Also   nanmin, nanmax, nanmean, nanstd, nansum

Purpose   Minimum ignoring NaNs

Syntax   m = nanmin(a)
                [m, ndx] = nanmin(a)
                m = nanmin(a, b)

Description m = nanmin(a) returns the minimum with NaNs treated as missing. For vectors, nanmin(a) is the smallest non-NaN element in a. For matrices, nanmin(A) is a row vector containing the minimum non-NaN element from each column.

[m, ndx] = nanmin(a) also returns the indices of the minimum values in vector ndx.

m = nanmin(a, b) returns the smaller of a or b, which must match in size.

Example
```
m = magic(3);
m([1 6 8]) = [NaN NaN NaN]

m =

   NaN     1     6
     3     5   NaN
     4   NaN     2

[nmin, minidx] = nanmin(m)

nmin =

     3     1     2

minidx =

     2     1     3
```

See Also   nanmax, nanmean, nanmedian, nanstd, nansum

nanstd

Purpose   Standard deviation ignoring NaNs

Syntax   y = nanstd(X)

Description   nanstd(X) the standard deviation treating NaNs as missing values.

For vectors, nanstd(x) is the standard deviation of the non-NaN elements of x. For matrices, nanstd(X) is a row vector containing the standard deviations of the non-NaN elements in each column of X.

Example
```
m = magic(3);
m([1 6 8]) = [NaN NaN NaN]

m =

    NaN     1     6
      3     5   NaN
      4   NaN     2


nstd = nanstd(m)

nstd =

    0.7071    2.8284    2.8284
```

See Also   nanmax, nanmin, nanmean, nanmedian, nansum

Purpose   Sum ignoring NaNs.

Syntax   y = nansum(X)

Description   nansum(X) the sum treating NaNs as missing values.

For vectors, nansum(x) is the sum of the non-NaN elements of x. For matrices, nansum(X) is a row vector containing the sum of the non-NaN elements in each column of X.

Example
```
m = magic(3);
m([1 6 8]) = [NaN NaN NaN]

m =

    NaN      1      6
      3      5    NaN
      4    NaN      2


nsum = nansum(m)

nsum =

      7      6      8
```

See Also   nanmax, nanmin, nanmean, nanmedian, nanstd

nbincdf

Purpose   Negative binomial cumulative distribution function.

Syntax   Y = nbincdf(X, R, P)

Description Y = nbincdf(X, R, P) returns the negative binomial cumulative distribution-function with parameters R and P at the values in X.

The size of Y is the common size of the input arguments. A scalar input functions as a constant matrix of the same size as the other inputs.

The negative binomial cdf is:

$$y = F(x|r, p) = \sum_{i=0}^{x} \binom{r+i-1}{i} p^r q^i I_{(0, 1, \ldots)}(i)$$

The motivation for the negative binomial is performing successive trials each having a constant probability, P, of success. What you want to find out is how many *extra* trials you must do to observe a given number, R, of successes.

Example
```
x = (0:15);
p = nbincdf(x, 3, 0.5);
stairs(x, p)
```
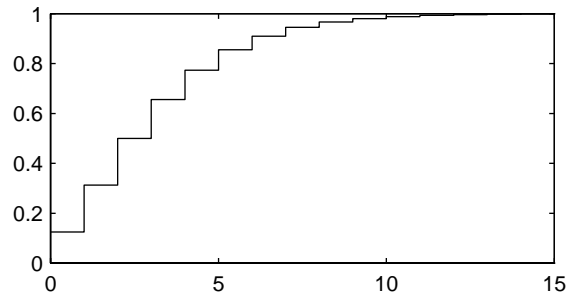

See Also   nbininv, nbinpdf, nbinrnd, nbinstat

Purpose   Inverse of the negative binomial cumulative distribution function (cdf).

Syntax   X = nbininv(Y, R, P)

Description nbininv(Y, R, P) returns the inverse of the negative binomial cdf with param-
eters R and P. Since the binomial distribution is discrete, nbininv returns the
least integer X such that the negative binomial cdf evaluated at X, equals or
exceeds Y.

The size of X is the common size of the input arguments. A scalar input func-
tions as a constant matrix of the same size as the other inputs.

The negative binomial models consecutive trials each having a constant prob-
ability, P, of success. The parameter, R, is the number of successes required
before stopping.

Example   How many times would you need to flip a fair coin to have a 99% probability of
having observed 10 heads?

```
flips = nbininv(0.99, 10, 0.5) + 10

flips =

    33
```

Note that you have to flip at least 10 times to get 10 heads. That is why the
second term on the right side of the equals sign is a 10.

See Also   nbincdf, nbinpdf, nbinrnd, nbinstat

nbinpdf

Purpose   Negative binomial probability density function.

Syntax   Y = nbinpdf(X, R, P)

Description   nbinpdf(X, R, P) returns the negative binomial probability density function
with parameters R and P at the values in X.

Note that the density function is zero unless X is an integer.

The size of Y is the common size of the input arguments. A scalar input functions as a constant matrix of the same size as the other inputs.

The negative binomial pdf is:

$$y = f(x|r, p) = \binom{r + x - 1}{x} p^r q^x I_{(0, 1, \ldots)}(x)$$

The negative binomial models consecutive trials each having a constant probability, P, of success. The parameter, R, is the number of successes required before stopping.

Example
```
x = (0:10);
y = nbinpdf(x, 3, 0.5);
plot(x, y, '+')
set(gca, 'Xlim', [-0.5, 10.5])
```
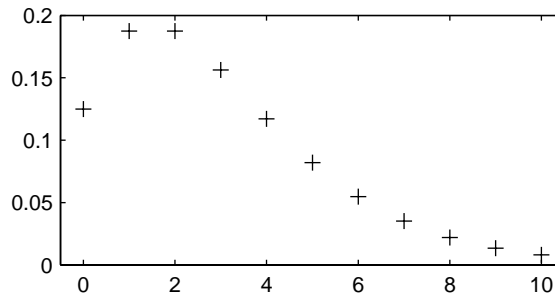

See Also   nbincdf, nbininv, nbinrnd, nbinstat, pdf

Purpose   Random matrices from a negative binomial distribution.

Syntax   RND = nbinrnd(R, P)
                   RND = nbinrnd(R, P, m)
                   RND = nbinrnd(R, P, m, n)

Description   RND = nbinrnd(R, P) is a matrix of random numbers chosen from a negative
                   binomial distribution with parameters R and P. The size of RND is the common
                   size of R and P if both are matrices. If either parameter is a scalar, the size of
                   RND is the size of the other parameter.

                   RND = nbinrnd(R, P, m) generates random numbers with parameters R and P.
                   m is a 1-by-2 vector that contains the row and column dimensions of RND.

                   RND = nbinrnd(R, P, m, n) generates random numbers with parameters R and
                   P. The scalars m and n are the row and column dimensions of RND.

                   The negative binomial models consecutive trials each having a constant prob-
                   ability, P, of success. The parameter, R, is the number of successes required
                   before stopping.

Example   Suppose you want to simulate a process that has a defect probability of 0.01.
                   How many units might Quality Assurance inspect before finding 3 defective
                   items?

                       r = nbinrnd(3, 0.01, 1, 6) + 3

                       r =

                          496   142   420   396   851   178

See Also   nbincdf, nbininv, nbinpdf, nbinstat

nbinstat

Purpose   Mean and variance of the negative binomial distribution.

Syntax   [M,V] = nbinstat(R,P)

Description [M,V] = nbinstat(R,P) returns the mean and variance of the negative bino-
mial distibution with parameters R and P.

- The mean is $\dfrac{rq}{p}$.

- The variance is $\dfrac{rq}{p^2}$.

where $q = 1 - p$.

Example
```
p = 0.1:0.2:0.9;
r = 1:5;
[R,P] = meshgrid(r,p);
[M,V] = nbinstat(R,P)
```

M =

9.0000	18.0000	27.0000	36.0000	45.0000
2.3333	4.6667	7.0000	9.3333	11.6667
1.0000	2.0000	3.0000	4.0000	5.0000
0.4286	0.8571	1.2857	1.7143	2.1429
0.1111	0.2222	0.3333	0.4444	0.5556

V =

90.0000	180.0000	270.0000	360.0000	450.0000
7.7778	15.5556	23.3333	31.1111	38.8889
2.0000	4.0000	6.0000	8.0000	10.0000
0.6122	1.2245	1.8367	2.4490	3.0612
0.1235	0.2469	0.3704	0.4938	0.6173

See Also   nbincdf, nbininv, nbinpdf, nbinrnd

Purpose   Noncentral F cumulative distribution function (cdf).

Syntax   P = ncfcdf(X, NU1, NU2, DELTA)

Description P = ncfcdf(X, NU1, NU2, DELTA) returns the noncentral F cdf with numerator
degrees of freedom (df), NU1, denominator df, NU2, and positive noncentrality
parameter, DELTA, at the values in X.

The size of P is the common size of the input arguments. A scalar input func-
tions as a constant matrix of the same size as the other inputs.

The noncentral F cdf is:

$$F(x|\nu_1, \nu_2, \delta) = \sum_{j=0}^{\infty} \left(\frac{\left(\frac{1}{2}\delta\right)^j}{j!} e^{-\frac{\delta}{2}} \right) I\left(\frac{\nu_1 \cdot x}{\nu_2 + \nu_1 \cdot x} \middle| \frac{\nu_1}{2} + j, \frac{\nu_2}{2} \right)$$

where *I(x|a,b)* is the incomplete beta function with parameters *a* and *b*.

Example   Compare the noncentral F cdf with δ = 10 to the F cdf with the same number
of numerator and denominator degrees of freedom (5 and 20 respectively).

    x = (0.01: 0.1: 10.01)';
    p1 = ncfcdf(x, 5, 20, 10);
    p = fcdf(x, 5, 20);
    plot(x, p, '--', x, p1, '-')
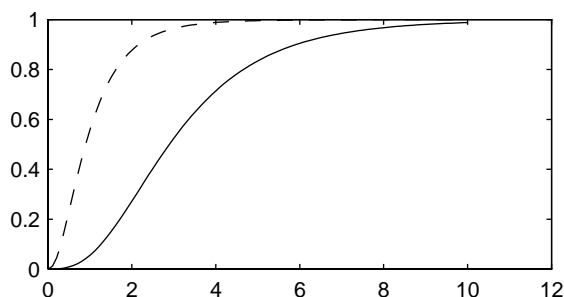
References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous
Univariate Distributions-2,* Wiley 1970. pp. 189–200.

ncfinv

Purpose	Inverse of the noncentral F cumulative distribution function (cdf).
Syntax	X = ncfinv(P, NU1, NU2, DELTA)
Description	X = ncfinv(P, NU1, NU2, DELTA) returns the inverse of the noncentral F cdf with numerator degrees of freedom (df), NU1, denominator df, NU2, and positive noncentrality parameter, DELTA, for the probabilities, P.

The size of X is the common size of the input arguments. A scalar input functions as a constant matrix of the same size as the other inputs.

Example   One hypothesis test for comparing two sample variances is to take their ratio and compare it to an F distribution. If the numerator and denominator degrees of freedom are 5 and 20 respectively then you reject the hypothesis that the first variance is equal to the second variance if their ratio is less than below:

```
critical = finv(0.95, 5, 20)

critical =

    2.7109
```

Suppose the truth is that the first variance is twice as big as the second variance. How likely is it that you would detect this difference?

```
prob = 1 - ncfcdf(critical, 5, 20, 2)

prob =

    0.1297
```

References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970 pp. 189–200.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition* Wiley 1993. pp. 73–74.

See Also   icdf, ncfcdf, ncfpdf, ncfrnd, ncfstat

Purpose   Noncentral F probability density function.

Syntax   Y = ncfpdf(X, NU1, NU2, DELTA)

Description   Y = ncfpdf(X, NU1, NU2, DELTA) returns the noncentral F pdf with with numer-
ator degrees of freedom (df), NU1, denominator df, NU2, and positive noncen-
trality parameter, DELTA, at the values in X.

The size of Y is the common size of the input arguments. A scalar input func-
tions as a constant matrix of the same size as the other inputs.

The F distribution is a special case of the noncentral F where $\delta = 0$. As δ
increases, the distribution flattens like the plot in the example.

Example   Compare the noncentral F pdf with $\delta = 10$ to the F pdf with the same number
of numerator and denominator degrees of freedom (5 and 20 respectively.)

```
x  = (0.01:0.1:10.01)';
p1 = ncfpdf(x, 5, 20, 10);
p  = fpdf(x, 5, 20);
plot(x, p, '--', x, p1, '-')
```
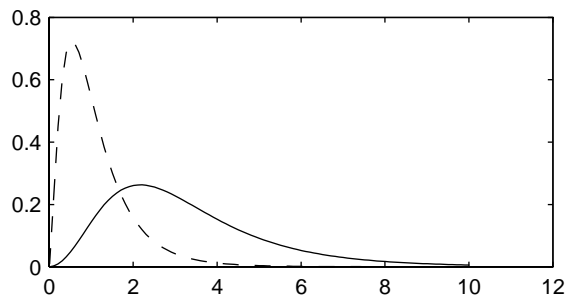

References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous
Univariate Distributions-2,* Wiley 1970. pp. 189–200.

See Also   ncfcdf, ncfinv, ncfrnd, ncfstat

ncfrnd

Purpose   Random matrices from the noncentral F distribution.

Syntax
R = ncfrnd(NU1, NU2, DELTA)
R = ncfrnd(NU1, NU2, DELTA, m)
R = ncfrnd(NU1, NU2, DELTA, m, n)

Description   R = ncfrnd(NU1, NU2, DELTA) returns a matrix of random numbers chosen from the noncentral F distribution with parameters NU1, NU2 and DELTA. The size of R is the common size of NU1, NU2 and DELTA if all are matrices. If any parameter is a scalar, the size of R is the size of the other parameters.

R = ncfrnd(NU1, NU2, DELTA, m) returns a matrix of random numbers with parameters NU1, NU2 and DELTA. m is a 1-by-2 vector that contains the row and column dimensions of R.

R = ncfrnd(NU1, NU2, DELTA, m, n) generates random numbers with parameters NU1, NU2 and DELTA. The scalars m and n are the row and column dimensions of R.

Example   Compute 6 random numbers from a noncentral F distribution with 10 numerator degrees of freedom, 100 denominator degrees of freedom and a noncentrality parameter, δ, of 4.0. Compare this to the F distribution with the same degrees of freedom.

```
r = ncfrnd(10, 100, 4, 1, 6)
r =

    2.5995    0.8824    0.8220    1.4485    1.4415    1.4864

r1 = frnd(10, 100, 1, 6)
r1 =

    0.9826    0.5911    1.0967    0.9681    2.0096    0.6598
```

References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2, Wiley* 1970. pp. 189–200.

See Also   ncfcdf, ncfinv, ncfpdf, ncfstat

Purpose   Mean and variance of the noncentral F distribution.

Syntax   [M, V] = ncfstat(NU1, NU2, DELTA)

Description [M, V] = ncfstat(NU1, NU2, DELTA) returns the mean and variance of the noncentral F pdf with NU1 and NU2 degrees of freedom and noncentrality parameter, DELTA.

- The mean is: $\dfrac{\nu_2(\delta + \nu_1)}{\nu_1(\nu_2 - 2)}$

where $\nu_2 > 2$.

- The variance is:

$$2\left(\frac{\nu_2}{\nu_1}\right)^2 \left[\frac{(\delta + \nu_1)^2 + (2\delta + \nu_1)(\nu_2 - 2)}{(\nu_2 - 2)^2(\nu_2 - 4)}\right]$$

where $\nu_2 > 4$.

Example   [m, v] = ncfstat(10, 100, 4)

        m =

            1.4286

        v =

            3.9200

References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970 pp. 189–200.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition* Wiley 1993. pp. 73–74.

See Also   ncfcdf, ncfinv, ncfpdf, ncfrnd

nctcdf

Purpose　　　　Noncentral T cumulative distribution function.

Syntax　　　　　P = nctcdf(X, NU, DELTA)

Description　　 P = nctcdf(X, NU, DELTA) returns the noncentral T cdf with NU degrees of freedom and noncentrality parameter, DELTA, at the values in X.

The size of P is the common size of the input arguments. A scalar input functions as a constant matrix of the same size as the other inputs.

Example　　　　Compare the noncentral T cdf with DELTA = 1 to the T cdf with the same number of degrees of freedom (10).

```
x = (−5:0.1:5)';
p1 = nctcdf(x, 10, 1);
p = tcdf(x, 10);
plot(x, p, '−−', x, p1, '−')
```
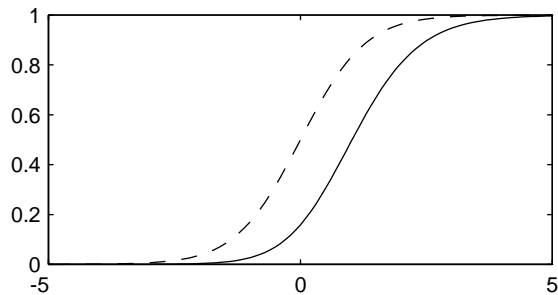

References　　 Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970 pp. 201–219.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition,* Wiley 1993 pp. 147–148.

See Also　　　 cdf, nctcdf, nctinv, nctpdf, nctrnd, nctstat

Purpose   Inverse of the noncentral T cumulative distribution.

Syntax   X = nctinv(P, NU, DELTA)

Description   X = nctinv(P, NU, DELTA) returns the inverse of the noncentral T cdf with NU degrees of freedom and noncentrality parameter, DELTA, for the probabilities, P.

The size of X is the common size of the input arguments. A scalar input functions as a constant matrix of the same size as the other inputs.

Example
```
x = nctinv([.1 .2], 10, 1)

x =

   -0.2914    0.1618
```

References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970 pp. 201–219.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition* Wiley 1993. pp. 147–148.

See Also   icdf, nctcdf, nctpdf, nctrnd, nctstat

nctpdf

Purpose   Noncentral T probability density function (pdf).

Syntax   Y = nctpdf(X, V, DELTA)

Description   Y = nctpdf(X, V, DELTA) returns the noncentral T pdf with V degrees of freedom and noncentrality parameter, DELTA, at the values in X.

The size of Y is the common size of the input arguments. A scalar input functions as a constant matrix of the same size as the other inputs.

Example   Compare the noncentral T pdf with DELTA = 1 to the T pdf with the same number of degrees of freedom (10).

```
x = (-5: 0. 1: 5)';
p1 = nctpdf(x, 10, 1);
p = tpdf(x, 10);
plot(x, p, '--', x, p1, '-')
```
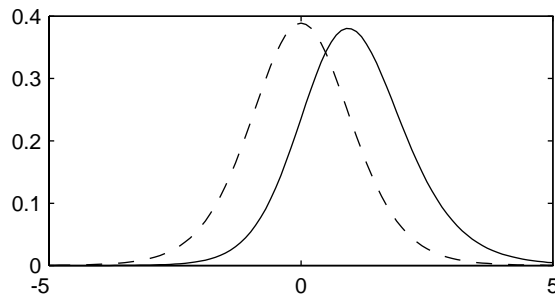

References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970 pp. 201–219.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition* Wiley 1993. pp. 147–148.

See Also   nctcdf, nctinv, nctrnd, nctstat, pdf

Purpose   Random matrices from noncentral T distribution.

Syntax   R = nctrnd(V, DELTA)
R = nctrnd(V, DELTA, m)
R = nctrnd(V, DELTA, m, n)

Description R = nctrnd(V, DELTA) returns a matrix of random numbers chosen from the
noncentral T distribution with parameters V and DELTA. The size of R is the
common size of V and DELTA if both are matrices. If either parameter is a scalar,
the size of R is the size of the other parameter.

R = nctrnd(V, DELTA, m) returns a matrix of random numbers with parameters
V and DELTA. m is a 1-by-2 vector that contains the row and column dimensions
of R.

R = nctrnd(V, DELTA, m, n) generates random numbers with parameters V and
DELTA. The scalars m and n are the row and column dimensions of R.

Example   nctrnd(10, 1, 5, 1)

ans =

1.6576
1.0617
1.4491
0.2930
3.6297

References Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous
Univariate Distributions-2,* Wiley 1970 pp. 201–219.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distribu-
tions, Second Edition* Wiley 1993. pp. 147–148.

See Also   nctcdf, nctinv, nctpdf, nctstat

nctstat

Purpose Mean and variance for the noncentral t distribution.

Syntax `[M, V] = nctstat(NU, DELTA)`

Description `[M, V] = nctstat(NU, DELTA)` returns the mean and variance of the noncentral t pdf with `NU` degrees of freedom and noncentrality parameter, `DELTA`.

- The mean is: $\dfrac{\delta(\nu/2)^{1/2}\Gamma((\nu-1)/2)}{\Gamma(\nu/2)}$

where $\nu > 1$.

- The variance is: $\dfrac{\nu}{(\nu-2)}(1+\delta^2)-\dfrac{\nu}{2}\delta^2\left[\dfrac{\Gamma((\nu-1)/2)}{\Gamma(\nu/2)}\right]^2$

where $\nu > 2$.

Example

```
[m, v] = nctstat(10, 1)

m =

    1.0837

v =

    1.3255
```

References Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970 pp. 201–219.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition* Wiley 1993. pp. 147–148.

See Also `nctcdf, nctinv, nctpdf, nctrnd`

Purpose   Noncentral chi-square cumulative distribution function (cdf).

Syntax   P = ncx2cdf(X, V, DELTA)

Description   ncx2cdf(X, V, DELTA) returns the noncentral chi-square cdf with V degrees of
   freedom and positive noncentrality parameter, DELTA, at the values in X.

                   The size of P is the common size of the input arguments. A scalar input func-
                   tions as a constant matrix of the same size as the other inputs.

                   Some texts refer to this distribution as the generalized Rayleigh,
                   Rayleigh-Rice, or Rice distribution.

                   The noncentral chi-square cdf is:

$$F(x|\nu, \delta) = \sum_{j=0}^{\infty}\left(\frac{\left(\frac{1}{2}\delta\right)^{j}}{j!}e^{-\frac{\delta}{2}}\right)Pr[\chi^{2}_{\nu+2j} \le x]$$

Example   x = (0:0.1:10)';
                   p1 = ncx2cdf(x, 4, 2);
                   p = chi2cdf(x, 4);
                   plot(x, p, '--', x, p1, '-')
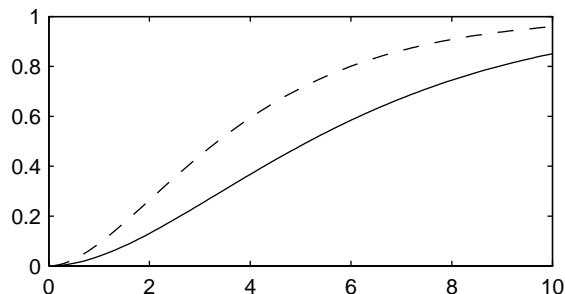
References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous
                   Univariate Distributions-2,* Wiley 1970. pp. 130–148.

See Also   cdf, ncx2inv, ncx2pdf, ncx2rnd, ncx2stat

ncx2inv

Purpose	Inverse of the noncentral chi-square cdf.
Syntax	X = ncx2inv(P, V, DELTA)
Description	X = ncx2inv(P, V, DELTA) returns the inverse of the noncentral chi-square cdf with parameters V and DELTA, at the probabilities in P.
	The size of X is the common size of the input arguments. A scalar input functions as a constant matrix of the same size as the other inputs.
Algorithm	ncx2inv uses Newton's method to converge to the solution.

Example

```
ncx2inv([0.01  0.05  0.1], 4, 2)

ans =

    0.4858    1.1498    1.7066
```

References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970 pp. 130–148.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition* Wiley 1993. pp. 50–52.

See Also   ncx2cdf, ncx2pdf, ncx2rnd, ncx2stat

Purpose   Noncentral chi-square probability density function (pdf).

Syntax   Y = ncx2pdf(X, V, DELTA)

Description   Y = ncx2pdf(X, V, DELTA) returns the noncentral chi-square pdf with v degrees of freedom and positive noncentrality parameter, DELTA, at the values in X.

The size of Y is the common size of the input arguments. A scalar input functions as a constant matrix of the same size as the other inputs.

Some texts refer to this distribution as the generalized Rayleigh, Rayleigh-Rice, or Rice distribution.

Example   As the noncentrality parameter, δ, increases, the distribution flattens as in the plot.

```
x = (0:0.1:10)';
p1 = ncx2pdf(x, 4, 2);
p = chi2pdf(x, 4);
plot(x, p, '--', x, p1, '-')
```
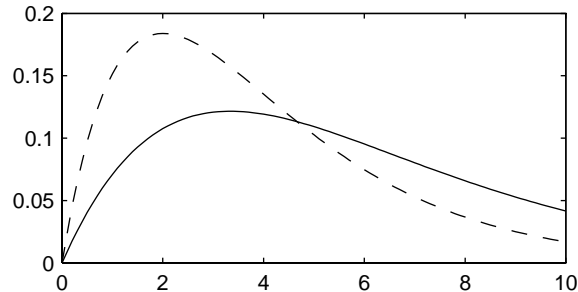

References   Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970. pp. 130–148.

See Also   ncx2cdf, ncx2inv, ncx2rnd, ncx2stat

ncx2rnd

Purpose   Random matrices from the noncentral chi-square distribution.

Syntax   R = ncx2rnd(V, DELTA)
                R = ncx2rnd(V, DELTA, m)
                R = ncx2rnd(V, DELTA, m, n)

Description R = ncx2rnd(V, DELTA) returns a matrix of random numbers chosen from the non-central chisquare distribution with parameters V and DELTA. The size of R is the common size of V and DELTA if both are matrices. If either parameter is a scalar, the size of R is the size of the other parameter.

R = ncx2rnd(V, DELTA, m) returns a matrix of random numbers with parameters V and DELTA. m is a 1-by-2 vector that contains the row and column dimensions of R.

R = ncx2rnd(V, DELTA, m, n) generates random numbers with parameters V and DELTA. The scalars m and n are the row and column dimensions of R.

Example   ncx2rnd(4, 2, 6, 3)

                ans =

                    6.8552   5.9650   11.2961
                    5.2631   4.2640   5.9495
                    9.1939   6.7162   3.8315
                   10.3100   4.4828   7.1653
                    2.1142   1.9826   4.6400
                    3.8852   5.3999   0.9282

References Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970. pp. 130–148.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition* Wiley 1993. pp. 50–52.

See Also   ncx2cdf, ncx2inv, ncx2pdf, ncx2stat

Purpose   Mean and variance for the noncentral chi-square distribution.

Syntax   `[M,V] = ncx2stat(NU,DELTA)`

Description `[M,V] = ncx2stat(NU,DELTA)` returns the mean and variance of the noncentral chi-square pdf with `NU` degrees of freedom and noncentrality parameter, `DELTA`.

- The mean is $\nu + \delta$.
- The variance is $2(\nu + 2\delta)$.

Example
```
[m,v] = ncx2stat(4,2)

m =

     6

v =

    16
```

References Johnson, Norman, and Kotz, Samuel, *Distributions in Statistics: Continuous Univariate Distributions-2,* Wiley 1970. pp. 130–148.

Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition* Wiley 1993. pp. 50–52.

See Also   `ncx2cdf`, `ncx2inv`, `ncx2pdf`, `ncx2rnd`

nlinfit

Purpose   Nonlinear least-squares data fitting by the Gauss-Newton method.

Syntax   [beta, r, J] = nlinfit(X, y, '*model*', beta0)

Description   beta = nlinfit(X, y, '*model*', beta0) returns the coefficients of the nonlinear function described in '*model*'.

'*model*' is a user supplied function having the form: $\hat{y} = f(\beta, X)$.

That is, '*model*' returns the predicted values of y given initial parameter estimates, β, and the independent variable, X.

The matrix, X, has one column per independent variable. The response, y, is a column vector with the same number of rows as X.

[beta, r, J] = nlinfit(X, y, '*model*', beta0) returns the fitted coefficients, beta, the residuals, r, and the Jacobian, J, for use with nlintool to produce error estimates on predictions.

Example
```
load reaction
betafit = nlinfit(reactants, rate, 'hougen', beta)

betafit =

    1.1323
    0.0582
    0.0354
    0.1025
    1.2801
```

See Also   nlintool

Purpose   Fits a nonlinear equation to data and displays an interactive graph.

Syntax   nlintool(x, y, '*model*', beta0)
nlintool(x, y, '*model*', beta0, alpha)
nlintool(x, y, '*model*', beta0, alpha, '*xname*', '*yname*')

Description   nlintool(x, y, '*model*', beta0) is a prediction plot that provides a nonlinear curve fit to *(x,y)* data. It plots a 95% global confidence interval for predictions as two red curves. beta0 is a vector containing initial guesses for the parameters.

nlintool(x, y, '*model*', beta0, alpha) plots a 100(1 – alpha) percent confidence interval for predictions.

nlintool displays a "vector" of plots, one for each column of the matrix of inputs, x. The response variable, y, is a column vector that matches the number of rows in x.

The default value for alpha is 0.05, which produces 95% confidence intervals.

nlintool(x, y, '*model*', beta0, alpha, '*xname*', '*yname*') labels the plot using the string matrix, '*xname*' for the *X* variables and the string '*yname*' for the *Y* variable.

You can drag the dotted white reference line and watch the predicted values update simultaneously. Alternatively, you can get a specific prediction by typing the value for *X* into an editable text field. Use the pop-up menu labeled **Export** to move specified variables to the base workspace.

Example   See the section "Nonlinear Regression Models" in Chapter 1.

See Also   nlinfit, rstool

nlparci

Purpose   Confidence intervals on estimates of parameters in nonlinear models.

Syntax   ci = nlparci(beta, r, J)

Description   nlparci(beta, r, J) returns the 95% confidence interval ci on the nonlinear least squares parameter estimates beta, given the residuals, r, and the Jacobian matrix ,J, at the solution. The confidence interval calculation is valid for systems where the number of rows of J exceeds the length of beta.

nlparci uses the outputs of nlinfit for its inputs.

Example   Continuing the example from nlinfit:

```
load reaction
[beta, resids, J] = nlinfit(reactants, rate, 'hougen', beta);
ci = nlparci(beta, resids, J)

ci =

    -1.0798    3.3445
    -0.0524    0.1689
    -0.0437    0.1145
    -0.0891    0.2941
    -1.1719    3.7321
```

See Also   nlinfit, nlintool, nlpredci

Purpose   Confidence intervals on predictions of nonlinear models.

Syntax   ypred = nlpredci('*model*', inputs, beta, r, J)
[ypred, delta] = nlpredci('*model*', inputs, beta, r, J)

Description   ypred = nlpredci('*model*', inputs, beta, r, J) returns the predicted responses, ypred, given the fitted parameters, beta, residuals, r, and the Jacobian matrix, J. inputs is a matrix of values of the independent variables in the nonlinear function.

[ypred, delta] = nlpredci('*model*', inputs, beta, r, J) also returns 95% confidence intervals, delta, on the nonlinear least squares predictions, pred. The confidence interval calculation is valid for systems where the length of r exceeds the length of beta and J is of full column rank.

nlpredci uses the outputs of nlinfit for its inputs.

Example   Continuing the example from nlinfit:

```
load reaction
[beta, resids, J]=nlinfit(reactants, rate, 'hougen', beta);
ci = nlpredci('hougen', reactants, beta, resids, J)

ci =

    8.2937
    3.8584
    4.7950
   -0.0725
    2.5687
   14.2227
    2.4393
    3.9360
   12.9440
    8.2670
   -0.1437
   11.3484
    3.3145
```

See Also   nlinfit, nlintool, nlparci

normcdf

Purpose   Normal cumulative distribution function (cdf).

Syntax   P = normcdf(X, MU, SIGMA)

Description   normcdf(X, MU, SIGMA) computes the normal cdf with parameters MU and SIGMA at the values in X. The arguments X, MU and SIGMA must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The parameter SIGMA must be positive.

The normal cdf is:

$$p = F(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{x} e^{\frac{-(t-\mu)^2}{2\sigma^2}} dt$$

The result, p, is the probability that a single observation from a normal distribution with parameters μ and σ will fall in the interval (–∞ x].

The *standard normal* distribution has $\mu = 0$ and $\sigma = 1$.

Examples   What is the probability that an observation from a standard normal distribution will fall on the interval [–1 1]?

```
p = normcdf([-1 1]);
p(2) - p(1)

ans =

    0.6827
```

More generally, about 68% of the observations from a normal distribution fall within one standard deviation, σ, of the mean, μ.

Purpose   Parameter estimates and confidence intervals for normal data.

Syntax   [muhat, sigmahat, muci, sigmaci] = normfit(X)
                     [muhat, sigmahat, muci, sigmaci] = normfit(X, alpha)

Description   [muhat, sigmahat, muci, sigmaci] = normfit(X) returns estimates, muhat and
                     sigmahat, of the parameters, μ and σ, of the normal distribution given the
                     matrix of data, X. muci and sigmaci are 95% confidence intervals. muci and
                     sigmaci have two rows and as many columns as the data matrix, X. The top row
                     is the lower bound of the confidence interval and the bottom row is the upper
                     bound.

                     [muhat, sigmahat, muci, sigmaci] = normfit(X, alpha) gives estimates and
                     100(1−alpha) percent confidence intervals. For example, alpha = 0.01 gives
                     99% confidence intervals.

Example   In this example the data is a two-column random normal matrix. Both columns
                     have $\mu = 10$ and $\sigma = 2$. Note that the confidence intervals below contain the
                     "true values."

```
r = normrnd(10, 2, 100, 2);
[mu, sigma, muci, sigmaci] = normfit(r)

mu =
   10.1455    10.0527

sigma =
    1.9072     2.1256

muci =
    9.7652     9.6288
   10.5258    10.4766

sigmaci =
    1.6745     1.8663
    2.2155     2.4693
```

See Also   betafit, binofit, expfit, gamfit, poissfit, unifit, weibfit

norminv

Purpose   Inverse of the normal cumulative distribution function (cdf).

Syntax   X = norminv(P, MU, SIGMA)

Description norminv(P, MU, SIGMA) computes the inverse of the normal cdf with parameters MU and SIGMA at the values in P. The arguments P, MU, and SIGMA must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The parameter SIGMA must be positive and P must lie on [0 1].

We define the normal inverse function in terms of the normal cdf.

$$x = F^{-1}(p|\mu, \sigma) = \{x : F(x|\mu, \sigma) = p\}$$

$$where \quad p = F(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \int_{-\infty}^{x} e^{\frac{-(t-\mu)^2}{2\sigma^2}} dt$$

The result, x, is the solution of the integral equation above with the parameters μ and σ where you supply the desired probability, p.

Examples   Find an interval that contains 95% of the values from a standard normal distribution.

    x = norminv([0.025 0.975], 0, 1)

    x =

        −1.9600   1.9600

Note the interval x is not the only such interval, but it is the shortest.

    xl = norminv([0.01 0.96], 0, 1)

    xl =

        −2.3263   1.7507

The interval xl also contains 95% of the probability, but it is longer than x.

Purpose Normal probability density function (pdf).

Syntax `Y = normpdf(X, MU, SIGMA)`

Description `normpdf(X, MU, SIGMA)` computes the normal pdf with parameters `mu` and `SIGMA` at the values in X. The arguments X, MU and SIGMA must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The parameter SIGMA must be positive.

The normal pdf is:

$$y = f(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{\frac{-(x-\mu)^2}{2\sigma^2}}$$

The *likelihood function* is the pdf viewed as a function of the parameters. Maximum likelihood estimators (MLEs) are the values of the parameters that maximize the likelihood function for a fixed value of x.

The *standard normal* distribution has $\mu = 0$ and $\sigma = 1$.

If x is standard normal, then $x\sigma + \mu$ is also normal with mean μ and standard deviation σ. Conversely, if y is normal with mean μ and standard deviation σ, then $x = (y - \mu)/\sigma$ is standard normal.

Examples
```
mu = [0:0.1:2];
[y i] = max(normpdf(1.5, mu, 1));
MLE = mu(i)

MLE =

    1.5000
```

normplot

Purpose	Normal probability plot for graphical normality testing.
Syntax	normplot(X)
	h = normplot(X)
Description	normplot(X) displays a normal probability plot of the data in X. For matrix X, normplot displays a line for each column of X.
	The plot has the sample data displayed with the plot symbol '+'. Superimposed on the plot is a line joining the first and third quartiles of each column of x. (A robust linear fit of the sample order statistics.) This line is extrapolated out to the ends of the sample to help evaluate the linearity of the data.
	If the data does come from a normal distribution, the plot will appear linear. Other probability density functions will introduce curvature in the plot.
	h = normplot(X) returns a handle to the plotted lines.
Examples	Generate a normal sample and a normal probability plot of the data.

```
x = normrnd(0, 1, 50, 1);
h = normplot(x);
```


Normal Probability Plot
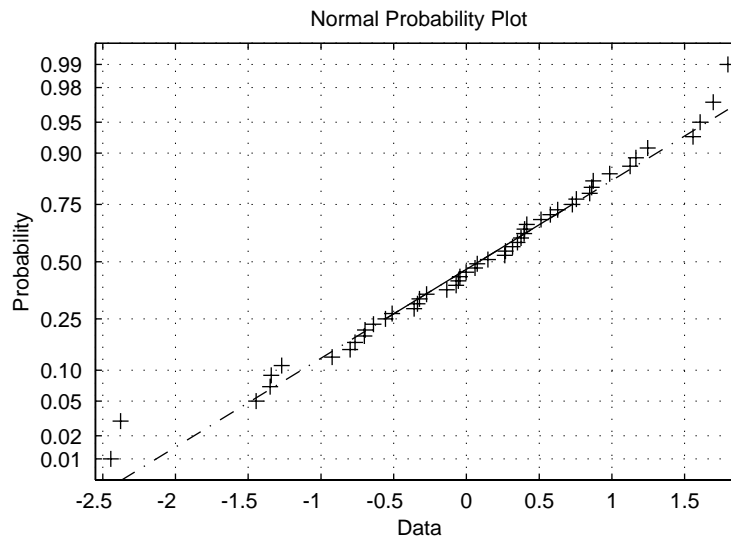
The plot is linear, indicating that you can model the sample by a normal distribution.

normrnd

Purpose   Random numbers from the normal distribution.

Syntax   R = normrnd(MU, SIGMA)
                  R = normrnd(MU, SIGMA, m)
                  R = normrnd(MU, SIGMA, m, n)

Description   R = normrnd(MU, SIGMA) generates normal random numbers with mean, MU,
                  and standard deviation, SIGMA . The size of R is the common size of MU and
                  SIGMA if both are matrices. If either parameter is a scalar, the size of R is the
                  size of the other parameter.

                  R = normrnd(MU, SIGMA, m) generates normal random numbers with parame-
                  ters MU and SIGMA. m is a 1-by-2 vector that contains the row and column dimen-
                  sions of R.

                  R = normrnd(MU, SIGMA, m, n) generates normal random numbers with param-
                  eters MU and SIGMA. The scalars m and n are the row and column dimensions of
                  R.

Examples   n1 = normrnd(1:6, 1./(1:6))

                  n1 =

                      2.1650   2.3134   3.0250   4.0879   4.8607   6.2827

                  n2 = normrnd(0, 1, [1 5])

                  n2 =

                      0.0591   1.7971   0.2641   0.8717   -1.4462

                  n3 = normrnd([1 2 3; 4 5 6], 0.1, 2, 3)

                  n3 =

                      0.9299   1.9361   2.9640
                      4.1246   5.0577   5.9864

normspec

Purpose	Plot normal density between specification limits.
Syntax	p = normspec(specs, mu, sigma)
	[p, h] = normspec(specs, mu, sigma)
Description	p = normspec(specs, mu, sigma) plots the normal density between a lower and upper limit defined by the two elements of the vector, specs. mu and sigma are the parameters of the plotted normal distribution.
	[p, h] = normspec(specs, mu, sigma) returns the probability, p, of a sample falling between the lower and upper limits. h is a handle to the line objects.
	If specs(1) is –Inf, there is no lower limit, and similarly if specs(2) = Inf, there is no upper limit.
Example	Suppose a cereal manufacturer produces 10 ounce boxes of corn flakes. Variability in the process of filling each box with flakes causes a 1.25 ounce standard deviation in the true weight of the cereal in each box. The average box of cereal has 11.5 ounces of flakes. What percentage of boxes will have less than 10 ounces?

```
normspec([10 Inf], 11.5, 1.25)
```
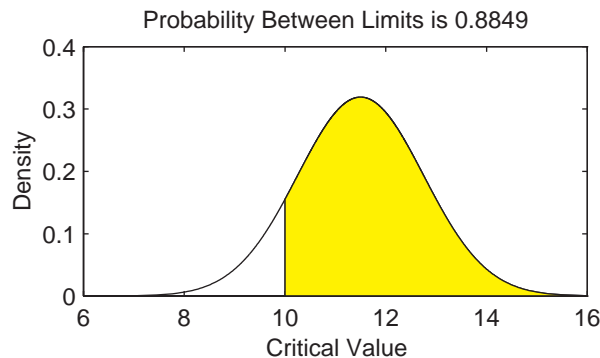

See Also	capaplot, disttool, histfit, normpdf

Purpose   Mean and variance for the normal distribution.

Syntax   [M,V] = normstat(MU,SIGMA)

Description   For the normal distribution,

- the mean is μ.
- the variance is σ^2.

Examples
```
n = 1:5;
[m,v] = normstat(n'*n,n'*n)
[m,v] = normstat(n'*n,n'*n)

m =

     1     2     3     4     5
     2     4     6     8    10
     3     6     9    12    15
     4     8    12    16    20
     5    10    15    20    25

v =

     1     4     9    16    25
     4    16    36    64   100
     9    36    81   144   225
    16    64   144   256   400
    25   100   225   400   625
```

pareto

Purpose   Pareto charts for Statistical Process Control.

Syntax   pareto(y)
                   pareto(y, '*names*')
                   h = pareto(...)

Description   pareto(y, names) displays a Pareto chart where the values in the vector y are
                   drawn as bars in descending order. Each bar is labeled with the associated
                   value in the string matrix names. pareto(y) labels each bar with the index of
                   the corresponding element in y.

                   The line above the bars shows the cumulative percentage.

                   pareto(y, '*names*') labels each bar with the row of the string matrix, '*names*',
                   that corresponds to the plotted element of y.

                   h = pareto(...) returns a combination of patch and line handles.

Example   Create a Pareto chart from data measuring the number of manufactured parts
                   rejected for various types of defects.

                   ```
                   defects = ['pits  ';'cracks';'holes ';'dents '];
                   quantity = [5 3 19 25];
                   pareto(quantity, defects)
                   ```
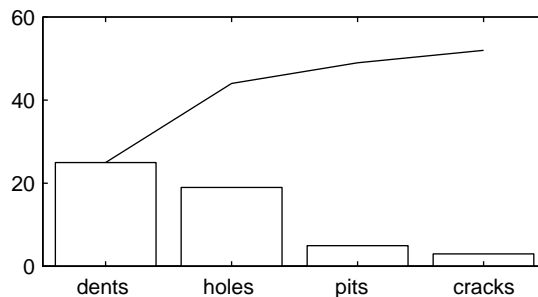

See Also   bar, capaplot, ewmaplot, hist, histfit, schart, xbarplot

Purpose   Principal Components Analysis using the covariance matrix.

Syntax   pc = pcacov(X)
                   [pc, latent, explained] = pcacov(X)

Description   [pc, latent, explained] = pcacov(X) takes the covariance matrix X and
                   returns the principal components in pc, the eigenvalues of the covariance
                   matrix of X in latent, and the percentage of the total variance in the observa-
                   tions explained by each eigenvector in explained.

Example   load hald
                   covx = cov(ingredients);
                   [pc, variances, explained] = pcacov(covx)

                   pc =

                       0.0678   −0.6460   0.5673   −0.5062
                       0.6785   −0.0200   −0.5440   −0.4933
                      −0.0290   0.7553   0.4036   −0.5156
                      −0.7309   −0.1085   −0.4684   −0.4844

                   variances =

                      517.7969
                       67.4964
                       12.4054
                        0.2372

                   explained =

                       86.5974
                       11.2882
                        2.0747
                        0.0397

Reference   J. Edward Jackson, *A User's Guide to Principal Components,* John Wiley &
                   Sons, Inc. 1991. pp. 1–25.

See Also   barttest, pcares, princomp

pcares

Purpose   Residuals from a Principal Components Analysis.

Syntax   residuals = pcares(X, ndim)

Description   pcares(X, ndim) returns the residuals obtained by retaining ndim principal components of X. Note that ndim is a scalar and must be less than the number of columns in X. Use the data matrix, *not* the covariance matrix, with this function.

Example   This example shows the drop in the residuals from the first row of the Hald data as the number of component dimensions increase from one to three.

```
load hald
r1 = pcares(ingredients, 1);
r2 = pcares(ingredients, 2);
r3 = pcares(ingredients, 3);
r11 = r1(1, :)

r11 =

    2.0350    2.8304   -6.8378    3.0879

r21 = r2(1, :)

r21 =

   -2.4037    2.6930   -1.6482    2.3425

r31 = r3(1, :)

r31 =

    0.2008    0.1957    0.2045    0.1921
```

Reference   J. Edward Jackson, *A User's Guide to Principal Components,* John Wiley & Sons, Inc. 1991. pp. 1–25.

See Also   barttest, pcacov, princomp

Purpose   Probability density function (pdf) for a specified distribution.

Syntax   Y = pdf('name', X, A1, A2, A3)

Description   pdf('*name*', X, A1, A2, A3) returns a matrix of densities. '*name*' is a string
                   containing the name of the distribution. X is a matrix of values, and A1, A2, and
                   A3 are matrices of distribution parameters. Depending on the distribution,
                   some of the parameters may not be necessary.

                   The arguments X, A1, A2, and A3 must all be the same size except that scalar
                   arguments function as constant matrices of the common size of the other argu-
                   ments.

                   pdf is a utility routine allowing access to all the pdfs in the Statistics Toolbox
                   using the name of the distribution as a parameter.

Examples   p = pdf('Normal', –2:2, 0, 1)

                     p =

                        0.0540   0.2420   0.3989   0.2420   0.0540

                     p = pdf('Poisson', 0:4, 1:5)

                     p =

                        0.3679   0.2707   0.2240   0.1954   0.1755

perms

Purpose   All permutations.

Syntax   P = perms(v)

Description   P = perms(v), where v is a row vector of length n, creates a matrix whose rows consist of all possible permutations of the n elements of v. The matrix, P, contains n! rows and n columns.

perms is only practical when n is less than 8 or 9.

Example
```
perms([2 4 6])

ans =

    6    4    2
    4    6    2
    6    2    4
    2    6    4
    4    2    6
    2    4    6
```

Purpose   Poisson cumulative distribution function (cdf).

Syntax   P = poisscdf(X, LAMBDA)

Description   poisscdf(X, LAMBDA) computes the Poisson cdf with parameter settings
                    LAMBDA at the values in X. The arguments X and LAMBDA must be the same size
                    except that a scalar argument functions as a constant matrix of the same size
                    of the other argument. The parameter, LAMBDA, is positive.

                    The Poisson cdf is:

$$p = F(x|\lambda) = e^{-\lambda} \sum_{i=0}^{floor(x)} \frac{\lambda^i}{i!}$$

Examples   Quality Assurance performs random tests of individual hard disks. Their policy
                    is to shut down the manufacturing process if an inspector finds more than four
                    bad sectors on a disk. What is the probability of shutting down the process if
                    the mean number of bad sectors (λ) is two?

                        probability = 1 – poisscdf(4, 2)

                        probability =

                            0.0527

                    About 5% of the time, a *normally functioning* manufacturing process will
                    produce more than four flaws on a hard disk.

                    Suppose the average number of flaws (λ) increases to four. What is the proba-
                    bility of finding fewer than five flaws on a hard drive?

                        probability = poisscdf(4, 4)

                        probability =

                            0.6288

                    This means that this faulty manufacturing process continues to operate after
                    this first inspection almost 63% of the time.

poissfit

Purpose   Parameter estimates and confidence intervals for Poisson data.

Syntax   lambdahat = poissfit(X)
                [lambdahat,lambdaci] = poissfit(X)
                [lambdahat,lambdaci] = poissfit(X,alpha)

Description poissfit(X) returns the maximum likelihood estimate (MLE) of the parameter of the Poisson distribution, λ, given the data X.

[lambdahat,lambdaci] = poissfit(X) also gives 95% confidence intervals in lamdaci.

[lambdahat,lambdaci] = poissfit(X,alpha) gives 100(1–alpha) percent confidence intervals. For example alpha = 0.001 yields 99.9% confidence intervals.

The sample average is the MLE of λ.

$$\hat{\lambda} = \frac{1}{n}\sum_{i=1}^{n} x_i$$

Example   r = poissrnd(5,10,2);
                [l,lci] = poissfit(r)

                l =

                     4.8000   4.8000

                lci =

                     3.5000   3.5000
                     6.2000   6.2000

See Also   betafit, binofit, expfit, gamfit, poissfit, unifit, weibfit

Purpose   Inverse of the Poisson cumulative distribution function (cdf).

Syntax   X = poissinv(P, LAMBDA)

Description   poissinv(P, LAMBDA) returns the smallest value, X, such that the Poisson cdf evaluated at X equals or exceeds P.

Examples   If the average number of defects (λ) is two, what is the 95th percentile of the number of defects?

```
poissinv(0.95, 2)

ans =

     5
```

What is the median number of defects?

```
median_defects = poissinv(0.50, 2)

median_defects =

     2
```

poisspdf

Purpose
Poisson probability density function (pdf).

Syntax
Y = poisspdf(X, LAMBDA)

Description
poisspdf(X, LAMBDA) computes the Poisson pdf with parameter settings LAMBDA at the values in X. The arguments X and LAMBDA must be the same size except that a scalar argument functions as a constant matrix of the same size of the other argument.

The parameter, λ, must be positive.

The Poisson pdf is:

$$y = f(x|\lambda) = \frac{\lambda^x}{x!} e^{-\lambda} I_{(0, 1, \ldots)}(x)$$

x can be any non-negative integer. The density function is zero unless x is an integer.

Examples
A computer hard disk manufacturer has observed that flaws occur randomly in the manufacturing process at the average rate of two flaws in a 4 Gb hard disk and has found this rate to be acceptable. What is the probability that a disk will be manufactured with no defects?

In this problem, $\lambda = 2$ and $x = 0$.

    p = poisspdf(0, 2)

    p =

        0.1353

Purpose   Random numbers from the Poisson distribution.

Syntax   R = poissrnd(LAMBDA)
                   R = poissrnd(LAMBDA, m)
                   R = poissrnd(LAMBDA, m, n)

Description   R = poissrnd(LAMBDA) generates Poisson random numbers with mean LAMBDA.
                   The size of R is the size of LAMBDA.

                   R = poissrnd(LAMBDA, m) generates Poisson random numbers with mean
                   LAMBDA. m is a 1-by-2 vector that contains the row and column dimensions of R.

                   R = poissrnd(LAMBDA, m, n) generates Poisson random numbers with mean
                   LAMBDA. The scalars m and n are the row and column dimensions of R.

Examples   Generate a random sample of 10 pseudo-observations from a Poisson distribution with $\lambda = 2$:

                   lambda = 2;
                   random_sample1 = poissrnd(lambda, 1, 10)

                   random_sample1 =

                        1   0   1   2   1   3   4   2   0   0

                   random_sample2 = poissrnd(lambda, [1 10])

                   random_sample2 =

                        1   1   1   5   0   3   2   2   3   4

                   random_sample3 = poissrnd(lambda(ones(1, 10)))

                   random_sample3 =

                        3   2   1   1   0   0   4   0   2   0

poisstat

Purpose   Mean and variance for the Poisson distribution.

Syntax   M = poisstat(LAMBDA)
                   [M,V] = poisstat(LAMBDA)

Description   M = poisstat(LAMBDA) returns the mean of the Poisson distribution with
                   parameter, LAMBDA. M and LAMBDA match each other in size.

                   [M,V] = poisstat(LAMBDA) also returns the variance of the Poisson
                   distribution.

                   For the Poisson distribution,

                   • the mean is λ.
                   • the variance is λ.

Examples   Find the mean and variance for the Poisson distribution with $\lambda = 2$:

                       [m,v] = poisstat([1 2; 3 4])

                       m =

                            1   2
                            3   4

                       v =

                            1   2
                            3   4

Purpose   Polynomial evaluation and confidence interval estimation.

Syntax   [Y, DELTA] = polyconf(p, X, S)
                 [Y, DELTA] = polyconf(p, X, S, alpha)

Description [Y, DELTA] = polyconf(p, X, S) uses the optional output, S, generated by
                 polyfit to give 95% confidence intervals Y +/− DELTA. This assumes the errors
                 in the data input to polyfit are independent normal with constant variance.

                 [Y, DELTA] = polyconf(p, X, S, alpha) gives 100(1−alpha)% confidence inter-
                 vals. For example, alpha = 0.1 yields 90% intervals.

                 If p is a vector whose elements are the coefficients of a polynomial in
                 descending powers, such as those output from polyfit, then polyconf(p, X) is
                 the value of the polynomial evaluated at X. If X is a matrix or vector, the poly-
                 nomial is evaluated at each of the elements.

Examples   This example gives predictions and 90% confidence intervals for computing
                 time for LU factorizations of square matrices with 100 to 200 columns. The
                 hardware was a Power Macintosh 7100/80.

```
n = [100 100:20:200];
for i = n
A = rand(i,i);
tic
B = lu(A);
    t(ceil((i−80)/20)) = toc;
end

[p,S] = polyfit(n(2:7),t,3);
[time,delta_t] = polyconf(p,n(2:7),S,0.1)

time =

    0.0829    0.1476    0.2277    0.3375    0.4912    0.7032

delta_t =

    0.0064    0.0057    0.0055    0.0055    0.0057    0.0064
```

polyfit

Purpose   Polynomial curve fitting.

Syntax   [p, S] = polyfit(x, y, n)

Description   p = polyfit(x, y, n) finds the coefficients of a polynomial $p(x)$ of degree n that fits the data, $p(x(i))$ to $y(i)$, in a least-squares sense. The result p is a row vector of length n+1 containing the polynomial coefficients in descending powers.

$$p(x) = p_1 x^n + p_2 x^{n-1} + \ldots p_n x + p_{n+1}$$

[p, S] = polyfit(x, y, n) returns polynomial coefficients p, and matrix, S for use with polyval to produce error estimates on predictions. If the errors in the data, y, are independent normal with constant variance, polyval will produce error bounds which contain at least 50% of the predictions.

You may omit S if you are not going to pass it to polyval or polyconf for calculating error estimates.

Example   [p, S] = polyfit(1: 10, [1: 10] + normrnd(0, 1, 1, 10), 1)

p =

   1. 0300   0. 4561

S =

   −19. 6214   −2. 8031
         0   −1. 4639
   8. 0000   0
   2. 3180   0

See Also   polyval, polytool, polyconf
polyfit is a function in MATLAB.

Purpose   Interactive plot for prediction of fitted polynomials.

Syntax   polytool(x, y)
                     polytool(x, y, n)
                     polytool(x, y, n, alpha)

Description   polytool(x, y) fits a line to the column vectors, x and y, and displays an inter-
                     active plot of the result. This plot is graphic user interface for exploring the
                     effects of changing the polynomial degree of the fit. The plot shows the fitted
                     curve and 95% global confidence intervals on a new predicted value for the
                     curve. Text with current predicted value of *y* and its uncertainty appears left
                     of the *y*-axis.

                     polytool(x, y, n) initially fits a polynomial of order, n.

                     polytool(x, y, n, alpha) plots 100(1−alpha)% confidence intervals on the
                     predicted values.

                     polytool fits by least-squares using the regression model,

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \ldots + \beta_n x_i^n + \varepsilon_i$$

$$\varepsilon_i \sim N(0, \sigma^2) \quad \forall i$$

$$Cov(\varepsilon_i, \varepsilon_j) = 0 \quad \forall i, j$$

                     Evaluate the function by typing a value in the *x*-axis edit box or dragging the
                     vertical reference line on the plot. The shape of the pointer changes from an
                     arrow to a cross hair when you are over the vertical line to indicate that the line
                     is draggable. The predicted value of *y* will update as you drag the reference line.

                     The argument, n, controls the degree of the polynomial fit. To change the
                     degree of the polynomial, choose from the pop-up menu at the top of the figure.

                     When you are done, press the **Close** button.

polyval

Purpose   Polynomial evaluation.

Syntax   Y = polyval(p, X)
[Y, DELTA] = polyval(p, X, S)

Description   Y = polyval(p, X) returns the predicted value of a polynomial given its coefficients, p, at the values in X.

[Y, DELTA] = polyval(p, X, S) uses the optional output, S, generated by polyfit to generate error estimates, Y +/– DELTA. If the errors in the data input to polyfit are independent normal with constant variance, Y +/– DELTA contains at least 50% of the predictions.

If p is a vector whose elements are the coefficients of a polynomial in descending powers, then polyval(p, X) is the value of the polynomial evaluated at X. If X is a matrix or vector, the polynomial is evaluated at each of the elements.

Examples   Simulate the function $y = x$, adding normal random errors with a standard deviation of 0.1. Then use polyfit to estimate the polynomial coefficients. Note that tredicted Y values are within DELTA of the integer, X, in every case.

```
[p, S] = polyfit(1:10, (1:10) + normrnd(0, 0.1, 1, 10), 1);
X = magic(3);
[Y, D] = polyval(p, X, S)

Y =

    8.0696    1.0486    6.0636
    3.0546    5.0606    7.0666
    4.0576    9.0726    2.0516

D =

    0.0889    0.0951    0.0861
    0.0889    0.0861    0.0870
    0.0870    0.0916    0.0916
```

See Also   polyfit, polytool, polyconf

polyval is a function in MATLAB.

Purpose   Percentiles of a sample.

Syntax   Y = prctile(X, p)

Description   Y = prctile(X, p) calculates a value that is greater than p percent of the values in X. The values of p must lie in the interval [0 100].

For vectors, prctile(X, p) is the pth percentile of the elements in X. For instance, if p = 50 then Y is the median of X.

For matrix X and scalar p, prctile(X, p) is a row vector containing the pth percentile of each column. If p is a vector, the ith row of Y is p(i) of X.

Examples   x = (1:5)'*(1:5)

                   x =

                        1   2   3   4   5
                        2   4   6   8   10
                        3   6   9   12   15
                        4   8   12   16   20
                        5   10   15   20   25

                   y = prctile(x, [25 50 75])

                   y =

                     1.7500   3.5000   5.2500   7.0000   8.7500
                     3.0000   6.0000   9.0000   12.0000   15.0000
                     4.2500   8.5000   12.7500   17.0000   21.2500

princomp

Purpose	Principal Components Analysis.
Syntax	PC = princomp(X)
	[PC, SCORE, latent, tsquare] = princomp(X)

Description   [PC, SCORE, latent, tsquare] = princomp(X) takes a data matrix X and returns the principal components in PC, the so-called Z-scores in SCORE, the eigenvalues of the covariance matrix of X in latent, and Hotelling's T^2 statistic for each data point in tsquare.

The Z-scores are the data formed by transforming the original data into the space of the principal components. The values of the vector, latent, are the variance of the columns of SCORE. Hotelling's T^2 is a measure of the multivariate distance of each observation from the center of the data set.

Example   Compute principal components for the ingredients data in the Hald dataset, and the variance accounted for by each component.

```
load hald;
[pc, score, latent, tsquare] = princomp(ingredients);
pc, latent

pc =

    0.0678   -0.6460    0.5673   -0.5062
    0.6785   -0.0200   -0.5440   -0.4933
   -0.0290    0.7553    0.4036   -0.5156
   -0.7309   -0.1085   -0.4684   -0.4844

latent =

  517.7969
   67.4964
   12.4054
    0.2372
```

Reference   J. Edward Jackson, *A User's Guide to Principal Components,* John Wiley & Sons, Inc. 1991. pp. 1–25.

See Also   barttest, pcacov, pcares

Purpose   Quantile-quantile plot of two samples.

Syntax   qqplot(X, Y)
                qqplot(X, Y, pvec)
                h = qqplot(...)

Description qqplot(X, Y) displays a quantile-quantile plot of two samples. If the samples do come from the same distribution the plot will be linear.

For matrix X and Y, qqplot displays a separate line for each pair of columns. The plotted quantiles are the quantiles of the smaller dataset.

The plot has the sample data displayed with the plot symbol '+'. Superimposed on the plot is a line joining the first and third quartiles of each distribution (this is a robust linear fit of the order statistics of the two samples). This line is extrapolated out to the ends of the sample to help evaluate the linearity of the data.

Use qqplot(X, Y, pvec) to specify the quantiles in the vector pvec.

h = qqplot(X, Y, pvec) returns handles to the lines in h.

Examples   Generate two normal samples with different means and standard deviations. Then make a quantile-quantile plot of the two samples.

```
x = normrnd(0, 1, 100, 1);
y = normrnd(0.5, 2, 50, 1);
qqplot(x, y);
```
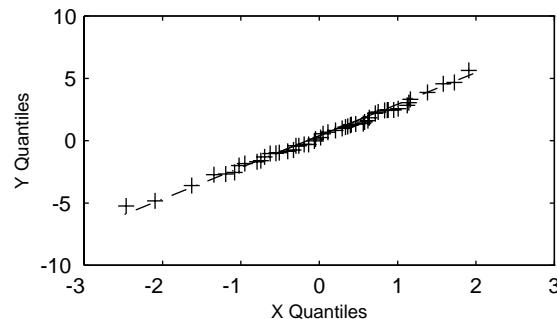
random

Purpose   Random numbers from a specified distribution.

Syntax   y = random('*name*', A1, A2, A3, m, n)

Description random is a utility routine allowing you to access all the random number generators in the Statistics Toolbox using the name of the distribution as a parameter.

y = random('*name*', A1, A2, A3, m, n) returns a matrix of random numbers. '*name*' is a string containing the name of the distribution. A1, A2, and A3 are matrices of distribution parameters. Depending on the distribution some of the parameters may not be necessary.

The arguments containing distribution parameters must all be the same size except that scalar arguments function as constant matrices of the common size of the other arguments.

The last two parameters, d and e, are the size of the matrix, y. If the distribution parameters are matrices, then these parameters are optional, but they must match the size of the other matrix arguments (see second example).

Examples
```
rn = random('Normal', 0, 1, 2, 4)

rn =

    1.1650    0.0751   -0.6965    0.0591
    0.6268    0.3516    1.6961    1.7971

rp = random('Poisson', 1:6, 1, 6)

rp =

    0    0    1    2    5    7
```

Purpose	Interactive random number generation using histograms for display.
Syntax	randtool r = randtool('output')
Description	The randtool command sets up a graphic user interface for exploring the effects of changing parameters and sample size on the histogram of random samples from the supported probability distributions.
	The M-file calls itself recursively using the action and flag parameters. For general use call randtool without parameters.
	To output the current set of random numbers, press the **Output** button. The results are stored in the variable ans. Alternatively, the command
	r = randtool('output') places the sample of random numbers in the vector, r.
	To sample repetitively from the same distribution, press the **Resample** button.
	To change the distribution function, choose from the pop-up menu of functions at the top of the figure.
	To change the parameter settings, move the sliders or type a value in the edit box under the name of the parameter. To change the limits of a parameter, type a value in the edit box at the top or bottom of the parameter slider.
	To change the sample size, type a number in the **Sample Size** edit box.
	When you are done, press the **Close** button.
	For an extensive discussion, see "The disttool Demo" on page 1–109
See Also	disttool

range

Purpose	Sample range.
Syntax	y = range(X)
Description	range(X) returns the difference between the maximum and the minimum of a sample. For vectors, range(x) is the range of the elements. For matrices, range(X) is a row vector containing the range of each column of X.
	The range is an easily calculated estimate of the spread of a sample. Outliers have an undue influence on this statistic, which makes it an unreliable estimator.
Example	The range of a large sample of standard normal random numbers is approximately 6. This is the motivation for the process capability indices C_p and C_{pk} in statistical quality control applications.

```
rv = normrnd(0, 1, 1000, 5);
near6 = range(rv)

near6 =

    6.1451    6.4986    6.2909    5.8894    7.0002
```

See Also	std, iqr, mad

Purpose   Wilcoxon rank sum test that two populations are identical.

Syntax   p = ranksum(x, y, alpha)
                  [p, h] = ranksum(x, y, alpha)

Description   p = ranksum(x, y, alpha) returns the significance probability that the popula-
                  tions generating two independent samples, x and y, are identical. x and y are
                  vectors but can have different lengths; if they are unequal in length, x must be
                  smaller than y. alpha is the desired level of significance and must be a scalar
                  between zero and one.

                  [p, h] = ranksum(x, y, alpha) also returns the result of the hypothesis test, h.
                  h is zero if the populations of x and y are not significantly different. h is one if
                  the two populations are significantly different.

                  p is the probability of observing a result equally or more extreme than the one
                  using the data (x and y) if the null hypothesis is true. If p is near zero, this casts
                  doubt on this hypothesis.

Example   This example tests the hypothesis of equality of means for two samples gener-
                  ated with poissrnd.

```
x = poissrnd(5, 10, 1);
y = poissrnd(2, 20, 1);
[p, h] = ranksum(x, y, 0.05)

p =

    0.0028

h =

     1
```

See Also   signrank, signtest, ttest2

raylcdf

Purpose	Rayleigh cumulative distribution function (cdf).
Syntax	P = raylcdf(X, B)
Description	P = raylcdf(X, B) returns the Rayleigh cumulative distribution function with parameter B at the values in X.

The size of P is the common size of X and B. A scalar input functions as a constant matrix of the same size as the other input.

The Rayleigh cdf is:

$$y = F(x|b) = \int_0^x \frac{t}{b^2} e^{\left(\frac{-t^2}{2b^2}\right)} dt$$

Example

```
x = 0:0.1:3;
p = raylcdf(x, 1);
plot(x, p)
```
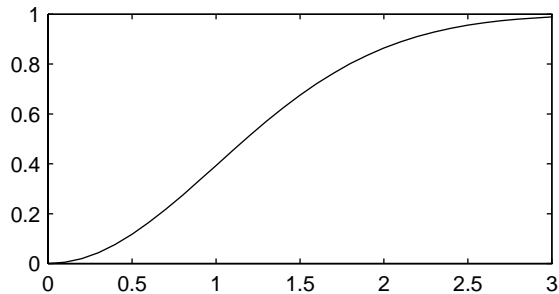

Reference Evans, Merran, Hastings, Nicholas and Peacock, Brian, *Statistical Distributions, Second Edition,* Wiley 1993. pp. 134–136.

See Also cdf, raylinv, raylpdf, raylrnd, raylstat

Purpose   Inverse of the Rayleigh cumulative distribution function.

Syntax   X = raylinv(P, B)

Description X = raylinv(P, B) returns the inverse of the Rayleigh cumulative distribution function with parameter B at the probabilities in P.

The size of X is the common size of P and B. A scalar input functions as a constant matrix of the same size as the other input.

Example
```
x = raylinv(0.9, 1)

x =

    2.1460
```

See Also   icdf, raylcdf, raylpdf, raylrnd, raylstat

raylpdf

Purpose   Rayleigh probability density function.

Syntax   Y = raylpdf(X, B)

Description   Y = raylpdf(X, B) returns the Rayleigh probability density function with parameter B at the values in X.

The size of Y is the common size of X and B. A scalar input functions as a constant matrix of the same size as the other input.

The Rayleigh pdf is:

$$y = f(x|b) = \frac{x}{b^2} e^{\left(\frac{-x^2}{2b^2}\right)}$$

Example
```
x = 0:0.1:3;
p = raylpdf(x, 1);
plot(x, p)
```
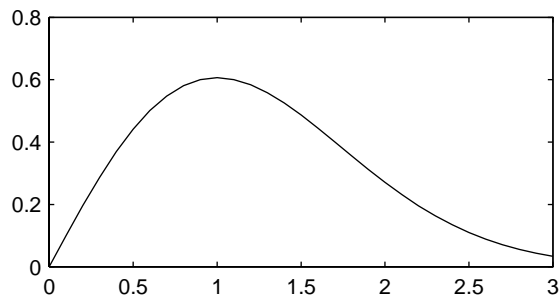

See Also   raylcdf, raylinv, raylrnd, raylstat

Purpose   Random matrices from the Rayleigh distribution.

Syntax   R = raylrnd(B)
                     R = raylrnd(B, m)
                     R = raylrnd(B, m, n)

Description   R = raylrnd(B) returns a matrix of random numbers chosen from the Rayleigh
                     distribution with parameter B. The size of R is the size of B.

                     R = raylrnd(B, m) returns a matrix of random numbers chosen from the
                     Rayleigh distribution with parameter B. m is a 1-by-2 vector that contains the
                     row and column dimensions of R.

                     R = raylrnd(B, m, n) returns a matrix of random numbers chosen from the
                     Rayleigh distribution with parameter B. The scalars m and n are the row and
                     column dimensions of R.

Example   r = raylrnd(1:5)

                         r =

                             1.7986   0.8795   3.3473   8.9159   3.5182

See Also   random, raylcdf, raylinv, raylpdf, raylstat

raylstat

Purpose   Mean and variance for the Rayleigh distribution.

Syntax   M = raylstat(B)
                 [M, V] = raylstat(B)

Description [M, V] = raylstat(B) returns the mean and variance of the Rayleigh distribution with parameter B.

- The mean is: $b\left(\dfrac{\pi}{2}\right)^{\frac{1}{2}}$

- The variance is: $\dfrac{2-\pi}{2}b^2$

Example   [mn, v] = raylstat(1)

                   mn =

                       1.2533

                   v =

                       0.4292

See Also   raylcdf, raylinv, raylpdf, raylrnd

Purpose   Residual case order plot.

Syntax   rcoplot(r, rint)

Description   rcoplot(r, rint) displays an errorbar plot of the confidence intervals on the residuals from a regression. The residuals appear in the plot in case order. r and rint are outputs from the regress function.

Example
```
X = [ones(10, 1)  (1:10)'];
y = X * [10; 1] + normrnd(0, 0.1, 10, 1);
[b, bint, r, rint] = regress(y, X, 0.05);
rcoplot(r, rint);
```
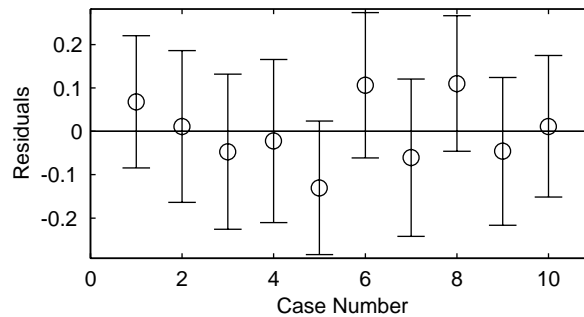

The figure shows a plot of the residuals with error bars showing 95% confidence intervals on the residuals. All the error bars pass through the zero line, indicating that there are no outliers in the data.

See Also   regress

refcurve

Purpose   Add a polynomial curve to the current plot.

Syntax   h = refcurve(p)

Description   refcurve adds a graph of the polynomial, p, to the current axes. The function for a polynomial of degree *n* is:

$$y = p_1x^n + p_2x^{(n-1)} + ... + p_nx + p_{n+1}$$

Note that p_1 goes with the highest order term.

h = refcurve(p) returns the handle to the curve.

Example   Plot data for the height of a rocket against time, and add a reference curve showing the theoretical height (assuming no air friction). The initial velocity of the rocket is 100 m/sec.

```
h = [85 162 230 289 339 381 413 437 452 458 456 440 400 356];
plot(h,'+')
refcurve([-4.9 100 0])
```
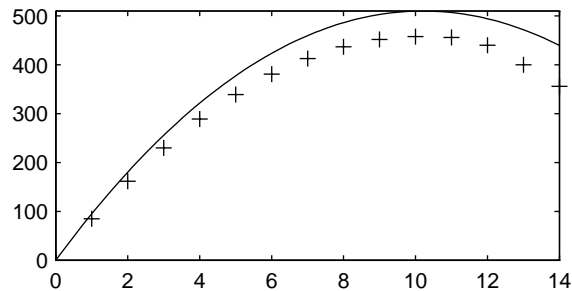

See Also   polyfit, polyval, refline

Purpose   Add a reference line to the current axes.

Syntax   refline(slope, intercept)
refline(slope)
h = refline(slope, intercept)
refline

Description refline(slope, intercept) adds a reference line with the given slope and intercept to the current axes.

refline(slope) where slope is a two element vector adds the line

$$y = SLOPE(2) + SLOPE(1)x$$

to the figure.

h = refline(slope, intercept) returns the handle to the line.

refline with no input arguments superimposes the least squares line on each line object in the current figure (except LineStyles '–',' – –',' . –'). This behavior is equivalent to lsline.

Example   y = [3.2 2.6 3.1 3.4 2.4 2.9 3.0 3.3 3.2 2.1 2.6]';
plot(y, '+')
refline(0, 3)
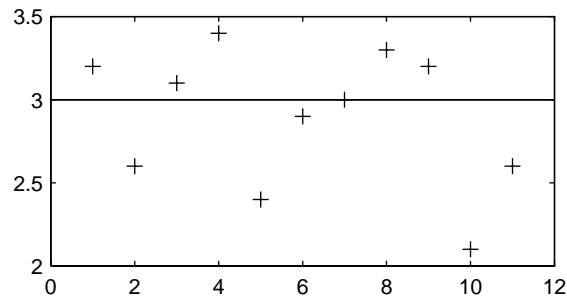
See Also   lsline, polyfit, polyval, refcurve

regress

Purpose   Multiple linear regression.

Syntax   b = regress(y, X)
                  [b, bint, r, rint, stats] = regress(y, X)
                  [b, bint, r, rint, stats] = regress(y, X, alpha)

Description   b = regress(y, X) returns the least squares fit of y on X.

regress solves the linear model:

$$y = X\beta + \varepsilon$$
$$\varepsilon \sim N(0, \sigma^2 I)$$

for β, where

- y is an nx1 vector of observations,
- X is an nxp matrix of regressors,
- β is a px1 vector of parameters, and
- ε is an nx1 vector of random disturbances.

[b, bint, r, rint, stats] = regress(y, X) returns an estimate of β in b, a 95% confidence interval for β, in the p-by-2 vector bint. The residuals are in r and a 95% confidence interval for each residual, is in the n-by-2 vector rint. The vector, stats, contains the R^2 statistic along with the F and p values for the regression.

[b, bint, r, rint, stats] = regress(y, X, alpha) gives 100(1-alpha)% confidence intervals for bint and rint. For example, alpha = 0.2 gives 80% confidence intervals.

Examples   Suppose the true model is:

$$y = 10 + x + \varepsilon$$
$$\varepsilon \sim N(0, 0.01 I)$$

where I is the identity matrix.

```
X = [ones(10, 1)  (1: 10)']
X =
      1      1
      1      2
      1      3
      1      4
      1      5
      1      6
      1      7
      1      8
      1      9
      1     10

y = X * [10; 1]  + normrnd(0, 0. 1, 10, 1)
y =
   11. 1165
   12. 0627
   13. 0075
   14. 0352
   14. 9303
   16. 1696
   17. 0059
   18. 1797
   19. 0264
   20. 0872

[b, bint]  = regress(y, X, 0. 05)

b =
   10. 0456
    1. 0030

bint =
    9. 9165    10. 1747
    0. 9822     1. 0238
```

Compare b to [10 1]'. Note that bint includes the true model values.

Reference   Chatterjee, S. and A. S. Hadi. *Influential Observations, High Leverage Points, and Outliers in Linear Regression.* Statistical Science, 1986. pp. 379–416.

regstats

Purpose	Regression diagnostics graphical user interface.
Syntax	regstats(responses, DATA) regstats(responses, DATA, '*model*')
Description	regstats(responses, DATA) generates regression diagnostics for a linear additive model with a constant term. The dependent variable is the vector, responses. Values of the independent variables are in the matrix, DATA.

The function creates a figure with a group of checkboxes that save diagnostic statistics to the base workspace using variable names you can specify.

regstats(responses, data, '*model*') controls the order of the regression model. '*model*' can be one of these strings:

- 'interaction' – includes constant, linear, and cross product terms.
- 'quadratic' – interactions plus squared terms.
- 'purequadratic' – includes constant, linear and squared terms.

The literature suggests many diagnostic statistics for evaluating multiple linear regression. regstats provides these diagnostics:

- Q from QR Decomposition.
- R from QR Decomposition.
- Regression Coefficients.
- Covariance of regression coefficients.
- Fitted values of the response data.
- Residuals.
- Mean Squared Error.
- Leverage.
- "Hat" Matrix.
- Delete-1 Variance.
- Delete-1 Coefficients.
- Standardized Residuals.
- Studentized Residuals.
- Change in Regression Coefficients.
- Change in Fitted Values.
- Scaled Change in Fitted Values.
- Change in Covariance.
- Cook's Distance.

For more detail press the **Help** button in the regstats window. This displays a hypertext help that gives formulae and interpretations for each of these regression diagnostics.

Algorithm   The usual regression model is: $y = X\beta + \varepsilon$

where y is an n by 1 vector of responses,
X is an n by p matrix of predictors,
β is an p by 1 vector of parameters,
ε is an n by 1 vector of random disturbances.

Let X = Q*R where Q and R come from a QR Decomposition of X. Q is orthogonal and R is triangular. Both of these matrices are useful for calculating many regression diagnostics (Goodall 1993).

The standard textbook equation for the least squares estimator of β is:

$$\hat{\beta} = b = (X'X)^{-1}X'y$$

However, this definition has poor numeric properties. Particularly dubious is the computation of $(X'X)^{-1}$, which is both expensive and imprecise.

Numerically stable MATLAB code for β is: b = R\(Q'*y);

Reference   Goodall, C. R. (1993). *Computation using the QR decomposition*. Handbook in Statistics, Volume 9. Statistical Computing (C. R. Rao, ed.). Amsterdam, NL Elsevier/North-Holland.

See Also   leverage, stepwise, regress

ridge

Purpose　　　　　Parameter estimates for ridge regression.

Syntax　　　　　b = ridge(y, X, k)

Description　　　b = ridge(y, X, k) returns the ridge regression coefficients, b.

Given the linear model $y = X\beta + \varepsilon$,
where X is an n by p matrix,
y is the n by 1 vector of observations,
k is a scalar constant (the ridge parameter).

The ridge estimator of β is: $b = (X'X + kI)^{-1}X'y$.

When k = 0, b is the least squares estimator. For increasing k, the bias of b increases, but the variance of b falls. For poorly conditioned X, the drop in the variance more than compensates for the bias.

Example　　　　This example shows how the coefficients change as the value of k increases, using data from the hald dataset.

```
load hald;
b = zeros(4, 100);
kvec = 0.01:0.01:1;
count = 0;
for k = 0.01:0.01:1
count = count + 1;
b(:, count) = ridge(heat, ingredients, k);
end
plot(kvec', b'), xlabel('k'), ylabel('b', 'FontName', 'Symbol')
```
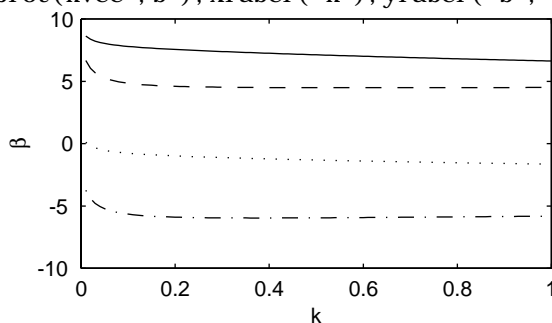

See Also　　　　regress, stepwise

rowexch

Purpose   D-Optimal design of experiments – row exchange algorithm.

Syntax   settings = rowexch(nfactors, nruns)
                   [settings, X] = rowexch(nfactors, nruns)
                   [settings, X] = rowexch(nfactors, nruns, '*model*')

Description   settings = rowexch(nfactors, nruns) generates the factor settings matrix,
                   settings, for a D-Optimal design using a linear additive model with a constant
                   term. settings has nruns rows and nfactors columns.

                   [settings, X] = rowexch(nfactors, nruns) also generates the associated
                   design matrix, X.

                   [settings, X] = rowexch(nfactors, nruns, '*model*') produces a design for
                   fitting a specified regression model. The input, '*model*', can be one of these
                   strings:

                   • 'interaction' – includes constant, linear, and cross product terms.
                   • 'quadratic' – interactions plus squared terms.
                   • 'purequadratic' – includes constant, linear and squared terms.

Example   This example illustrates that the D-optimal design for 3 factors in 8 runs, using
                   an interactions model, is a two level full-factorial design.

                   ```
                   s = rowexch(3, 8, 'interaction')

                   s =

                       -1    -1     1
                        1    -1    -1
                        1    -1     1
                       -1    -1    -1
                       -1     1     1
                        1     1     1
                       -1     1    -1
                        1     1    -1
                   ```

See Also   cordexch, daugment, dcovary, fullfact, ff2n, hadamard

Purpose   Demo of design of experiments and surface fitting.

Syntax   rsmdemo

Description rsmdemo creates a GUI that simulates a chemical reaction. To start, you have a budget of 13 test reactions. Try to find out how changes in each reactant affect the reaction rate. Determine the reactant settings that maximize the reaction rate. Estimate the run-to-run variability of the reaction. Now run a designed experiment using the model pop-up. Compare your previous results with the output from response surface modeling or nonlinear modeling of the reaction. The GUI has the following elements:

- A **Run** button to perform one reactor run at the current settings.
- An **Export** button to export the X and y data to the base workspace.
- Three sliders with associated data entry boxes to control the partial pressures of the chemical reactants: Hydrogen, n-Pentane, and Isopentane.
- A text box to report the reaction rate.
- A text box to keep track of the number of test reactions you have left.

Example   See "The rsmdemo Demo" on page 1–116.

See Also   rstool, nlintool, cordexch

rstool

Purpose	Interactive fitting and visualization of a response surface.
Syntax	rstool (x, y)
	rstool (x, y, '*model*')
	rstool (x, y, '*model*', alpha, '*xname*', '*yname*')

Description   rstool(x,y) displays an interactive prediction plot with 95% global confidence intervales. This plot results from a multiple regression of *(X,y)* data using a linear additive model.

rstool (x, y, '*model*') allows control over the initial regression model. '*model*' can be one of the following strings:

- 'interaction' – includes constant, linear, and cross product terms.
- 'quadratic' – interactions plus squared terms.
- 'purequadratic' – includes constant, linear and squared terms.

rstool (x, y, 'model', alpha) plots $100(1 - alpha)$% global confidence interval for predictions as two red curves. For example, alpha = 0.01 gives 99% confidence intervals.

rstool displays a "vector" of plots, one for each column of the matrix of inputs, x. The response variable, y, is a column vector that matches the number of rows in x.

rstool (x, y, '*model*', alpha, '*xname*', '*yname*') labels the graph using the string matrix '*xname*' for the labels to the *x*-axes and the string, '*yname*', to label the *y*-axis common to all the plots.

Drag the dotted white reference line and watch the predicted values update simultaneously. Alternatively, you can get a specific prediction by typing the value of *x* into an editable text field. Use the pop-up menu labeled **Model** to interactively change the model. Use the pop-up menu labeled **Export** to move specified variables to the base workspace.

Example   See "Quadratic Response Surface Models" on page 1–59.

See Also   nlintool

Purpose   Chart of standard deviation for Statistical Process Control.

Syntax   schart(DATA, conf)
                  schart(DATA, conf, specs)
                  schart(DATA, conf, specs)
                  [outliers, h] = schart(DATA, conf, specs)

Description   schart(data) displays an S chart of the grouped responses in DATA. The rows
                  of DATA contain replicate observations taken at a given time. The rows must be
                  in time order. The upper and lower control limits are a 99% confidence interval
                  on a new observation from the process. So, roughly 99% of the plotted points
                  should fall between the control limits.

                  schart(DATA, conf) allows control of the the confidence level of the upper and
                  lower plotted confidence limits. For example, conf = 0.95 plots 95% confidence
                  intervals.

                  schart(DATA, conf, specs) plots the specification limits in the two element
                  vector, specs.

                  [outliers, h] = schart(data, conf, specs) returns outliers, a vector of
                  indices to the rows where the mean of DATA is out of control, and h, a vector of
                  handles to the plotted lines.

Example   This example plots an S chart of measurements on newly machined parts,
                  taken at one hour intervals for 36 hours. Each row of the runout matrix
                  contains the measurements for 4 parts chosen at random. The values indicate,

schart

in thousandths of an inch, the amount the part radius differs from the target
radius.

```
load parts
schart(runout)
```
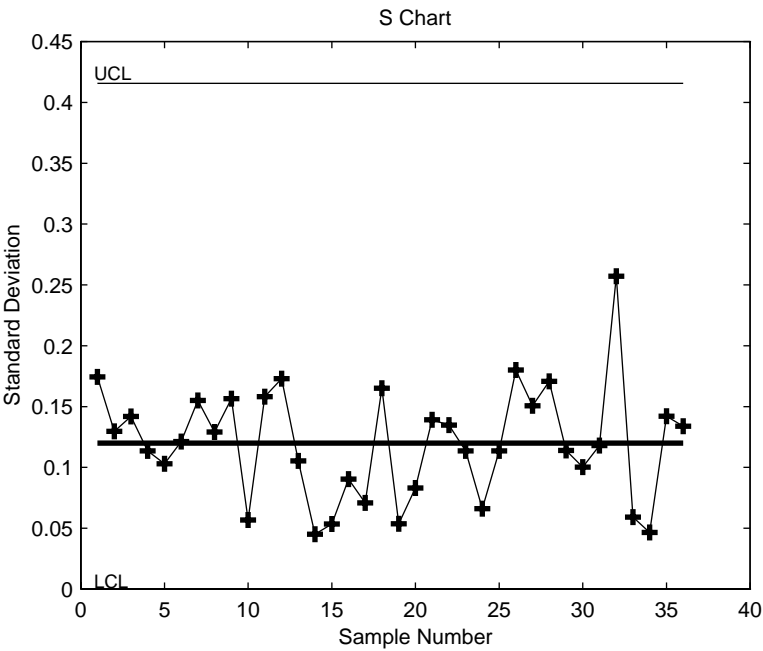

Reference   Montgomery, Douglas, *Introduction to Statistical Quality Control,* John Wiley
& Sons 1991. p. 235.

See Also   capaplot, ewmaplot, histfit, xbarplot

Purpose   Wilcoxon signed rank test of equality of medians.

Syntax   p = signrank(x, y, alpha)
                   [p, h] = signrank(x, y, alpha)

Description   p = signrank(x, y, alpha) returns the significance probability that the
                   medians of two matched samples, x and y, are equal. x and y must be vectors
                   of equal length. alpha is the desired level of significance, and must be a scalar
                   between zero and one.

                   [p, h] = signrank(x, y, alpha) also returns the result of the hypothesis test,
                   h. h is zero if the difference in medians of x and y is not significantly different
                   from zero. h is one if the two medians are significantly different.

                   p is the probability of observing a result equally or more extreme than the one
                   using the data (x and y) if the null hypothesis is true. p is calculated using the
                   rank values for the differences between corresponding elements in x and y. If
                   p is near zero, this casts doubt on this hypothesis.

Example   This example tests the hypothesis of equality of means for two samples gener-
                   ated with normrnd. The samples have the same theoretical mean but different
                   standard deviations.

                       x = normrnd(0, 1, 20, 1);
                       y = normrnd(0, 2, 20, 1);
                       [p, h] = signrank(x, y, 0.05)

                       p =

                           0.2568

                       h =

                            0

See Also   ranksum, signtest, ttest

signtest

Purpose   Sign test for paired samples.

Syntax   p = signtest(x, y, alpha)
                 [p, h] = signtest(x, y, alpha)

Description   p = signtest(x, y, alpha) returns the significance probability that the
                 medians of two matched samples, x and y, are equal. x and y must be vectors
                 of equal length. y may also be a scalar; in this case, signtest computes the
                 probability that the median of x is different from the constant, y. alpha is the
                 desired level of significance and must be a scalar between zero and one.

                 [p, h] = signtest(x, y, alpha) also returns the result of the hypothesis test,
                 h. h is zero if the difference in medians of x and y is not significantly different
                 from zero. h is one if the two medians are significantly different.

                 p is the probability of observing a result equally or more extreme than the one
                 using the data (x and y) if the null hypothesis is true. p is calculated using the
                 signs (plus or minus) of the differences between corresponding elements in x
                 and y. If p is near zero, this casts doubt on this hypothesis.

Example   This example tests the hypothesis of equality of means for two samples gener-
                 ated with normrnd. The samples have the same theoretical mean but different
                 standard deviations.

                    x = normrnd(0, 1, 20, 1);
                    y = normrnd(0, 2, 20, 1);
                    [p, h] = signtest(x, y, 0.05)

                    p =

                        0.8238

                    h =

                         0

See Also   ranksum, signrank, ttest

Purpose   Sample skewness.

Syntax   y = skewness(X)

Description   skewness(X) returns the sample skewness of X. For vectors, skewness(x) is the skewness of the elements of x. For matrices, skewness(X) is a row vector containing the sample skewness of each column.

Skewness is a measure of the asymmetry of the data around the sample mean. If skewness is negative, the data are spread out more to the left of the mean than to the right. If skewness is positive, the data are spread out more to the right. The skewness of the normal distribution (or any perfectly symmetric distribution) is zero.

The skewness of a distribution is defined as:

$$y = \frac{E(x-\mu)^3}{\sigma^3}$$

where *E(x)* is the expected value of *x*.

Example   X = randn([5 4])

X =

1.1650	1.6961	−1.4462	−0.3600
0.6268	0.0591	−0.7012	−0.1356
0.0751	1.7971	1.2460	−1.3493
0.3516	0.2641	−0.6390	−1.2704
−0.6965	0.8717	0.5774	0.9846

y = skewness(X)

y =

−0.2933	0.0482	0.2735	0.4641

See Also   kurtosis, mean, moment, std, var

std

Purpose   Standard deviation of a sample.

Syntax   y = std(X)

Description std(X) computes the sample standard deviation of the data in X. For vectors, std(x) is the standard deviation of the elements in x. For matrices, std(X) is a row vector containing the standard deviation of each column of X.

std(X) normalizes by n–1 where n is the sequence length. For normally distributed data, the square of the standard deviation is the minimum variance unbiased estimator of σ^2 (the second parameter).

The standard deviation is:

$$s = \left(\frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x})^2 \right)^{\frac{1}{2}}$$

where the sample average is $\bar{x} = \frac{1}{n} \sum x_i$.

Examples   In each column, the expected value of y is one.

    x = normrnd(0, 1, 100, 6);
    y = std(x)

    y =

        0.9536   1.0628   1.0860   0.9927   0.9605   1.0254

    y = std(-1:2:1)

    y =

        1.4142

See Also   cov, var
                std is a function in MATLAB.

Purpose   Interactive environment for stepwise regression.

Syntax   stepwise(X, y)
stepwise(X, y, inmodel)
stepwise(X, y, inmodel, alpha)

Description   stepwise(X, y) fits a regression model of y on the columns of X. It displays three figure windows for interactively controlling the stepwise addition and removal of model terms.

stepwise(X, y, inmodel) allows control of the terms in the original regression model. The values of vector, inmodel, are the indices of the columns of the matrix, X, to include in the initial model.

stepwise(X, y, inmodel, alpha) allows control of the length confidence intervals on the fitted coefficients. alpha is the significance for testing each term in the model. By default, alpha $= 1 - (1 - 0.025)^{(1/p)}$ where p is the number of columns in X. This translates to plotted 95% simultaneous confidence intervals (Bonferroni) for all the coefficients.

The least squares coefficient is plotted with a green filled circle. A coefficient is not significantly different from zero if its confidence interval crosses the white zero line. Significant model terms are plotted using solid lines. Terms not significantly different from zero are plotted with dotted lines.

Click on the confidence interval lines to toggle the state of the model coefficients. If the confidence interval line is green the term is in the model. If the the confidence interval line is red the term is not in the model.

Use the pop-up menu, **Export**, to move variables to the base workspace.

Example   See "Stepwise Regression" on page 1–61.

Reference   Draper, Norman and Smith, Harry, *Applied Regression Analysis,Second Edition*, John Wiley & Sons, Inc. 1981 pp. 307–312.

See Also   regstats, regress, rstool

surfht

Purpose   Interactive contour plot.

Syntax   surfht (Z)
                   surfht (x, y, Z)

Description   surfht (Z) is an interactive contour plot of the matrix Z treating the values in Z as height above the plane. The *x*-values are the column indices of Z while the *y*-values are the row indices of Z.

surfht (x, y, Z), where x and y are vectors specify the *x* and *y*-axes on the contour plot. The length of x must match the number of columns in Z, and the length of y must match the number of rows in Z.

There are vertical and horizontal reference lines on the plot whose intersection defines the current *x*-value and *y*-value. You can drag these dotted white reference lines and watch the interpolated *z*-value (at the top of the plot) update simultaneously. Alternatively, you can get a specific interpolated *z*-value by typing the *x*-value and *y*-value into editable text fields on the *x*-axis and *y*-axis respectively.

Purpose   Frequency table.

Syntax   table = tabulate(x)
                     tabulate(x)

Description   table = tabulate(x) takes a vector of positive integers, x, and returns a
                     matrix, table.

                     The first column of table contains the values of x. The second contains the
                     number of instances of this value. The last column contains the percentage of
                     each value.

                     tabulate with no output arguments displays a formatted table in the
                     command window.

Example   tabulate([1 2 4 4 3 4])

Value	Count	Percent
1	1	16.67%
2	1	16.67%
3	1	16.67%
4	3	50.00%

See Also   pareto

tblread

Purpose   Read tabular data from the file system.

Syntax   [data, varnames, casenames] = tblread
                   [data, varnames, casenames] = tblread('*filename*')
                   [data, varnames, casenames] = tblread('*filename*','*delimiter*')

Description   [data, varnames, casenames] = tblread displays the File Open dialog box for
                   interactive selection of the tabular data file. The file format has variable names
                   in the first row, case names in the first column and data starting in the (2,2)
                   position.

                   [data, varnames, casenames] = tblread(filename) allows command line
                   specification of the name of a file in the current directory, or the complete path-
                   name of any file.

                   [data, varnames, casenames] = tblread(filename,'*delimiter*') allows
                   specification of the field '*delimiter*' in the file. Accepted values are 'tab',
                   'space', or 'comma'.

                   • varnames is a string matrix containing the variable names in the first row.
                   • casenames is a string matrix containing the names of each case in the first
                     column. data is a numeric matrix with a value for each variable-case pair.
                   • data is a numeric matrix with a value for each variable-case pair.

Example
```
[data, varnames, casenames] = tblread('sat.dat')

data =

    470    530
    520    480

varnames =

Male
Female

casenames =

Verbal
Quantitative
```

See Also   caseread, tblwrite

tblwrite

Purpose   Writes tabular data to the file system.

Syntax   tblwrite(data, '*varnames*', '*casenames*')
                     tblwrite(data, '*varnames*', '*casenames*', '*filename*')

Description   tblwrite(data, '*varnames*', '*casenames*') displays the File Open dialog box
                     for interactive specification of the tabular data output file. The file format has
                     variable names in the first row, case names in the first column and data
                     starting in the (2,2) position.

                     '*varnames*' is a string matrix containing the variable names. '*casenames*' is
                     a string matrix containing the names of each case in the first column. data is
                     a numeric matrix with a value for each variable-case pair.

                     tblwrite(data, '*varnames*', '*casenames*', '*filename*') allows command line
                     specification of a file in the current directory, or the complete pathname of any
                     file in the string, '*filename*'.

Example   Continuing the example from tblread:

```
tblwrite(data, varnames, casenames, 'sattest.dat')
type sattest.dat

              Male      Female
Verbal        470       530
Quantitative  520       480
```

See Also   casewrite, tblread

Purpose   Student's t cumulative distribution function (cdf).

Syntax   P = tcdf(X, V)

Description   tcdf(X, V) computes Student's t cdf with V degrees of freedom at the values in
X. The arguments X and V must be the same size except that a scalar argument
functions as a constant matrix of the same size of the other argument.

The parameter, V, is a positive integer.

The t cdf is:

$$p = F(x|v) = \int_{-\infty}^{x} \frac{\Gamma\left(\frac{v+1}{2}\right)}{\Gamma\left(\frac{v}{2}\right)} \frac{1}{\sqrt{v\pi}} \frac{1}{\left(1 + \frac{t^2}{v}\right)^{\frac{v+1}{2}}} dt$$

The result, p, is the probability that a single observation from the t distribu-
tion with v degrees of freedom will fall in the interval ($-\infty$ x].

Examples   Suppose 10 samples of Guinness beer have a mean alcohol content of 5.5% by
volume and the standard deviation of these samples is 0.5%. What is the prob-
ability that the true alcohol content of Guinness beer is less than 5%?

```
t = (5.0 − 5.5) / 0.5;
probability = tcdf(t, 10 − 1)

probability =

    0.1717
```

tinv

Purpose   Inverse of the Student's t cumulative distribution function (cdf).

Syntax   X = tinv(P, V)

Description   tinv(P, V) computes the inverse of Student's t cdf with parameter V for the probabilities in P. The arguments P and V must be the same size except that a scalar argument functions as a constant matrix of the size of the other argument.

The degrees of freedom, V, must be a positive integer and P must lie in the interval [0 1].

The t inverse function in terms of the t cdf is:

$$x = F^{-1}(p|v) = \{x : F(x|v) = p\}$$

$$where \quad p = F(x|v) = \int_{-\infty}^{x} \frac{\Gamma\left(\frac{v+1}{2}\right)}{\Gamma\left(\frac{v}{2}\right)} \frac{1}{\sqrt{v\pi}} \frac{1}{\left(1 + \frac{t^2}{v}\right)^{\frac{v+1}{2}}} dt$$

The result, x, is the solution of the integral equation of the t cdf with parameter v where you supply the desired probability p.

Examples   What is the 99th percentile of the t distribution for one to six degrees of freedom?

    percentile = tinv(0.99, 1:6)

    percentile =

        31.8205   6.9646   4.5407   3.7469   3.3649   3.1427

Purpose   Student's t probability density function (pdf).

Syntax   Y = tpdf(X, V)

Description tpdf(X, V) computes Student's t pdf with parameter V at the values in X. The arguments X and V must be the same size except that a scalar argument functions as a constant matrix of the same size of the other argument.

The degrees of freedom, V, must be a positive integer.

Student's t pdf is:

$$y = f(x|\nu) = \frac{\Gamma\left(\frac{\nu + 1}{2}\right)}{\Gamma\left(\frac{\nu}{2}\right)} \frac{1}{\sqrt{\nu\pi}} \frac{1}{\left(1 + \frac{x^2}{\nu}\right)^{\frac{\nu + 1}{2}}}$$

Examples   The mode of the t distribution is at $x = 0$. This example shows that the value of the function at the mode is an increasing function of the degrees of freedom.

    tpdf(0, 1:6)

    ans =

        0.3183   0.3536   0.3676   0.3750   0.3796   0.3827

The t distribution converges to the standard normal distribution as the degrees of freedom approaches infinity. How good is the approximation for $\nu = 30$?

    difference = tpdf(-2.5:2.5, 30) - normpdf(-2.5:2.5)

    difference =

        0.0035   -0.0006   -0.0042   -0.0042   -0.0006   0.0035

trimmean

Purpose   Mean of a sample of data excluding extreme values.

Syntax   m = trimmean(X, percent)

Description trimmean(X, percent) calculates the mean of a sample X excluding the highest
and lowest percent/2 of the observations. The trimmed mean is a robust esti-
mate of the location of a sample. If there are outliers in the data, the trimmed
mean is a more representative estimate of the center of the body of the data. If
the data is all from the same probability distribution, then the trimmed mean
is less efficient than the sample average as an estimator of the location of the
data.

Examples   This example shows a Monte Carlo simulation of the relative efficiency of the
10% trimmed mean to the sample average for normal data.

```
x = normrnd(0, 1, 100, 100);
m = mean(x);
trim = trimmean(x, 10);
sm = std(m);
strim = std(trim);
efficiency = (sm/strim).^2
efficiency =

    0.9702
```

See Also   mean, median, geomean, harmmean

Purpose   Random numbers from Student's t distribution.

Syntax   R = trnd(V)
                R = trnd(V, m)
                R = trnd(V, m, n)

Description R = trnd(V) generates random numbers from Student's t distribution with V
                degrees of freedom. The size of R is the size of V.

                R = trnd(V, m) generates random numbers from Student's t distribution with
                V degrees of freedom. m is a 1-by-2 vector that contains the row and column
                dimensions of R.

                R = trnd(V, m, n) generates random numbers from Student's t distribution
                with V degrees of freedom. The scalars m and n are the row and column dimen-
                sions of R.

Examples   noisy = trnd(ones(1, 6))

                noisy =

                    19.7250   0.3488   0.2843   0.4034   0.4816   −2.4190

                numbers = trnd(1:6, [1 6])

                numbers =

                    −1.9500   −0.9611   −0.9038   0.0754   0.9820   1.0115

                numbers = trnd(3, 2, 6)

                numbers =

                    −0.3177   −0.0812   −0.6627   0.1905   −1.5585   −0.0433
                     0.2536   0.5502   0.8646   0.8060   −0.5216   0.0891

tstat

Purpose	Mean and variance for the Student's t distribution.
Syntax	[M, V] = tstat(NU)
Description	For the Student's t distribution with parameter, ν,

- The mean is zero for values of ν greater than 1. If ν is one, the mean does not exist.

- The variance, for values of ν greater than 2, is $\dfrac{\nu}{\nu - 2}$

Examples

The mean and variance for 1 to 30 degrees of freedom.

```
[m, v] = tstat(reshape(1: 30, 6, 5))

m =

    NaN      0       0       0       0
      0      0       0       0       0
      0      0       0       0       0
      0      0       0       0       0
      0      0       0       0       0
      0      0       0       0       0

v =

       NaN    1.4000    1.1818    1.1176    1.0870
       NaN    1.3333    1.1667    1.1111    1.0833
    3.0000    1.2857    1.1538    1.1053    1.0800
    2.0000    1.2500    1.1429    1.1000    1.0769
    1.6667    1.2222    1.1333    1.0952    1.0741
    1.5000    1.2000    1.1250    1.0909    1.0714
```

Note that the variance does not exist for one and two degrees of freedom.

Purpose   Hypothesis testing for a single sample mean.

Syntax   h = ttest(x, m)
               h = ttest(x, m, alpha)
               [h, sig, ci] = ttest(x, m, alpha, tail)

Description   ttest(x, m) performs a t-test at significance level 0.05 to determine whether a
                 sample from a normal distribution (in x) could have mean m when the standard
                 deviation is unknown.

                 h = ttest(x, m, alpha) gives control of the significance level, alpha. For
                 example if alpha = 0.01, and the result, h, is 1 you can reject the null hypothesis
                 at the significance level 0.01. If h = 0, you cannot reject the null hypothesis at
                 the alpha level of significance.

                 [h, sig, ci] = ttest(x, m, alpha, tail) allows specification of one or
                 two-tailed tests. tail is a flag that specifies one of three alternative hypoth-
                 eses:

                 tail = 0 (default) specifies the alternative, $\bar{x} \neq \mu$.

                 tail = 1 specifies the alternative, $\bar{x} > \mu$.

                 tail = −1 specifies the alternative, $\bar{x} < \mu$.

                 sig is the p-value associated with the T-statistic.

                 $$T = \frac{\bar{x} - \mu}{s}$$

                 sig is the probability that the observed value of T could be as large or larger *by
                 chance* under the null hypothesis that the mean of *x* is equal to *μ*.

                 ci is a 1−alpha confidence interval for the true mean.

Example   This example generates 100 normal random numbers with theoretical mean
               zero and standard deviation one. The observed mean and standard deviation
               are different from their theoretical values, of course. We test the hypothesis
               that there is no true difference.

Normal random number generator test.

```
x = normrnd(0, 1, 1, 100);
[h, sig, ci] = ttest(x, 0)
h =

     0

sig =

    0.4474

ci =

   −0.1165     0.2620
```

The result, h = 0, means that we cannot reject the null hypothesis. The significance level is 0.4474, which means that by chance we would have observed values of T more extreme than the one in this example in 45 of 100 similar experiments. A 95% confidence interval on the mean is [–0.1165 0.2620], which includes the theoretical (and hypothesized) mean of zero.

Purpose   Hypothesis testing for the difference in means of two samples.

Syntax   [h, significance, ci] = ttest2(x, y)
                [h, significance, ci] = ttest2(x, y, alpha)
                [h, significance, ci] = ttest2(x, y, alpha, tail)

Description h = ttest2(x, y) performs a t-test to determine whether two samples from a normal distribution (in x and y) could have the same mean when the standard deviations are unknown but assumed equal.

h, the result, is 1 if you can reject the null hypothesis at the 0.05 significance level alpha and 0 otherwise.

significance is the p-value associated with the T-statistic.

$$T = \frac{\bar{x} - \bar{y}}{s}$$

significance is the probability that the observed value of T could be as large or larger *by chance* under the null hypothesis that the mean of *x* is equal to the mean of *y*.

ci is a 95% confidence interval for the true difference in means.

[h, significance, ci] = ttest2(x, y, alpha) gives control of the significance level, alpha. For example if alpha = 0.01, and the result, h, is 1, you can reject the null hypothesis at the significance level 0.01. ci in this case is a 100(1−alpha)% confidence interval for the true difference in means.

ttest2(x, y, alpha, tail) allows specification of one or two-tailed tests. tail is a flag that specifies one of three alternative hypotheses:

tail = 0 (default) specifies the alternative, $\mu_x \neq \mu_y$.

tail = 1 specifies the alternative, $\mu_x > \mu_y$.

tail = −1 specifies the alternative, $\mu_x < \mu_y$.

Examples   This example generates 100 normal random numbers with theoretical mean zero and standard deviation one. We then generate 100 more normal random numbers with theoretical mean one half and standard deviation one. The observed means and standard deviations are different from their theoretical values, of course. We test the hypothesis that there is no true difference

between the two means. Notice that the true difference is only one half of the standard deviation of the individual observations, so we are trying to detect a signal that is only one half the size of the inherent noise in the process.

```
x = normrnd(0, 1, 100, 1);
y = normrnd(0.5, 1, 100, 1);
[h, significance, ci] = ttest2(x, y)

h =

    1

significance =

    0.0017

ci =

    -0.7352    -0.1720
```

The result, h = 1, means that we can reject the null hypothesis. The significance is 0.0017, which means that by chance we would have observed values of t more extreme than the one in this example in only 17 of 10,000 similar experiments! A 95% confidence interval on the mean is [–0.7352 –0.1720], which includes the theoretical (and hypothesized) difference of –0.5.

Purpose   Discrete uniform cumulative distribution (cdf) function.

Syntax   P = unidcdf(X, N)

Description   unidcdf(X, N) computes the discrete uniform cdf with parameter settings N at
                     the values in X. The arguments X and N must be the same size except that a
                     scalar argument functions as a constant matrix of the same size of the other
                     argument.

                     The maximum observable value, N, is a positive integer.

                     The discrete uniform cdf is:

                     $$p = F(x|N) = \frac{floor(x)}{N} I_{(1, ..., N)}(x)$$

                     The result, p, is the probability that a single observation from the discrete
                     uniform distribution with maximum, N, will be a positive integer less than or
                     equal to x. The values, x, do not need to be integers.

Examples   What is the probability of drawing a number 20 or less from a hat with the
                     numbers from 1 to 50 inside?

                         probability = unidcdf(20, 50)

                         probability =

                             0.4000

unidinv

Purpose   Inverse of the discrete uniform cumulative distribution function.

Syntax   X = unidinv(P, N)

Description   unidinv(P, N) returns the smallest integer X such that the discrete uniform cdf
                   evaluated at X is equal to or exceeds P. You can think of P as the probability of
                   drawing a number as large as X out of a hat with the numbers 1 through N
                   inside.

                   The argument P must lie on the interval [0 1] and N must be a positive integer.
                   Each element of X is a positive integer.

Examples   x = unidinv(0.7, 20)

                       x =

                           14

                       y = unidinv(0.7 + eps, 20)

                       y =

                           15

                   A small change in the first parameter produces a large jump in output. The cdf
                   and its inverse are both step functions. The example shows what happens at a
                   step.

Purpose   Discrete uniform probability density function (pdf).

Syntax   Y = unidpdf(X, N)

Description   unidpdf(X, N) computes the discrete uniform pdf with parameter settings, N, at the values in X. The arguments X and N must be the same size except that a scalar argument functions as a constant matrix of the same size of the other argument.

The parameter N must be a positive integer.

The discrete uniform pdf is:

$$y = f(x|N) = \frac{1}{N} I_{(1, \ldots, N)}(x)$$

You can think of y as the probability of observing any one number between 1 and n.

Examples   For fixed n, the uniform discrete pdf is a constant.

    y = unidpdf(1:6, 10)

    y =

        0.1000   0.1000   0.1000   0.1000   0.1000   0.1000

Now fix x , and vary n.

    likelihood = unidpdf(5, 4:9)

    likelihood =

             0   0.2000   0.1667   0.1429   0.1250   0.1111

unidrnd

Purpose   Random numbers from the discrete uniform distribution.

Syntax
R = unidrnd(N)
R = unidrnd(N, mm)
R = unidrnd(N, mm, nn)

Description   The discrete uniform distribution arises from experiments equivalent to drawing a number from one to N out of a hat.

R = unidrnd(N) generates discrete uniform random numbers with maximum, N. The size of R is the size of N.

R = unidrnd(N, mm) generates discrete uniform random numbers with maximum, N. mm is a 1-by-2 vector that contains the row and column dimensions of R.

R = unidrnd(N, mm, nn) generates discrete uniform random numbers with maximum, N. The scalars mm and nn are the row and column dimensions of R.

The parameter, N, must have positive integer elements.

Examples   In the Massachusetts lottery a player chooses a four digit number. Generate random numbers for Monday through Saturday.

    numbers = unidrnd(10000, 1, 6) - 1

    numbers =

            2189   470   6788   6792   9346

Purpose   Mean and variance for the discrete uniform distribution.

Syntax   [M, V] = unidstat(N)

Description   For the discrete uniform distribution,

- The mean is $\dfrac{N+1}{2}$

- The variance is $\dfrac{N^2-1}{12}$

Examples   [m, v] = unidstat(1:6)

    m =

        1.0000   1.5000   2.0000   2.5000   3.0000   3.5000

    v =

           0   0.2500   0.6667   1.2500   2.0000   2.9167

unifcdf

Purpose   Continuous uniform cumulative distribution function (cdf).

Syntax   P = unifcdf(X, A, B)

Description   unifcdf(X, A, B) computes the uniform cdf with parameters A and B at the
                   values in X. The arguments X, A and B must all be the same size except that
                   scalar arguments function as constant matrices of the common size of the other
                   arguments.

                   A and B are the minimum and maximum values respectively.

                   The uniform cdf is:

                   $$p = F(x|a, b) = \frac{x-a}{b-a} I_{[a, b]}(x)$$

                   The *standard uniform* distribution has A = 0 and B = 1.

Examples   What is the probability that an observation from a standard uniform distribu-
                   tion will be less than 0.75?

                       probability = unifcdf(0.75)

                       probability =

                           0.7500

                   What is the probability that an observation from a uniform distribution with
                   a = −1 and b = 1 will be less than 0.75?

                       probability = unifcdf(0.75, −1, 1)

                       probability =

                           0.8750

Purpose   Inverse continuous uniform cumulative distribution function (cdf).

Syntax   X = unifinv(P, A, B)

Description   unifinv(P, A, B) computes the inverse of the uniform cdf with parameters A
and B at the values in X. The arguments X, A, and B must all be the same size
except that scalar arguments function as constant matrices of the common size
of the other arguments.

A and B are the minimum and maximum values respectively.

The inverse of the uniform cdf is:

$$x = F^{-1}(p|a, b) = a + p(a - b)I_{[0, 1]}(p)$$

The *standard uniform* distribution has A = 0 and B = 1.

Examples   What is the median of the standard uniform distribution?

        median_value = unifinv(0.5)

        median_value =

            0.5000

What is the 99th percentile of the uniform distribution between –1 and 1?

        percentile = unifinv(0.99, –1, 1)

        percentile =

            0.9800

unifit

Purpose	Parameter estimates for uniformly distributed data.
Syntax	[ahat, bhat] = unifit(X)
	[ahat, bhat, ACI, BCI] = unifit(X)
	[ahat, bhat, ACI, BCI] = unifit(X, alpha)

Description [ahat, bhat] = unifit(X) returns the maximum likelihood estimates (MLEs) of the parameters of the uniform distribution given the data in X.

[ahat, bhat, ACI, BCI] = unifit(X) also returns 95% confidence intervals, ACI and BCI, which are matrices with two rows. The first row contains the lower bound of the interval for each column of the matrix, X. The second row contains the upper bound of the interval.

[ahat, bhat, ACI, BCI] = unifit(X, alpha) allows control of the confidence level alpha. For example, if alpha is 0.01 then ACI and BCI are 99% confidence intervals.

Example
```
r = unifrnd(10, 12, 100, 2);
[ahat, bhat, aci, bci] = unifit(r)

ahat =

    10.0154    10.0060

bhat =

    11.9989    11.9743

aci =

     9.9551     9.9461
    10.0154    10.0060

bci =

    11.9989    11.9743
    12.0592    12.0341
```

See Also betafit, binofit, expfit, gamfit, normfit, poissfit, weibfit

Purpose   Continuous uniform probability density function (pdf).

Syntax   Y = unifpdf (X, A, B)

Description   unifpdf (X, A, B) computes the continuous uniform pdf with parameters A and
                     B at the values in X. The arguments X, A, and B must all be the same size except
                     that scalar arguments function as constant matrices of the common size of the
                     other arguments.

                     The parameter B must be greater than A.

                     The continuous uniform distribution pdf is:

$$y = f(x|a, b) = \frac{1}{b-a} I_{[a, b]}(x)$$

                     The *standard uniform* distribution has A = 0 and B = 1.

Examples   For fixed a and b, the uniform pdf is constant.

                         x = 0. 1: 0. 1: 0. 6;
                         y = unifpdf (x)

                         y =

                             1   1   1   1   1   1

                     What if x is not between a and b?

                         y = unifpdf (−1, 0, 1)

                         y =

                             0

unifrnd

Purpose   Random numbers from the continuous uniform distribution.

Syntax   R = unifrnd(A, B)
                 R = unifrnd(A, B, m)
                 R = unifrnd(A, B, m, n)

Description R = unifrnd(A, B) generates uniform random numbers with parameters A and
                 B. The size of R is the common size of A and B if both are matrices. If either
                 parameter is a scalar, the size of R is the size of the other parameter.

                 R = unifrnd(A, B, m) generates uniform random numbers with parameters A
                 and B. m is a 1-by-2 vector that contains the row and column dimensions of R.

                 R = unifrnd(A, B, m, n) generates uniform random numbers with parameters
                 A and B. The scalars m and n are the row and column dimensions of R.

Examples   random = unifrnd(0, 1:6)

                 random =

                     0.2190   0.0941   2.0366   2.7172   4.6735   2.3010

                 random = unifrnd(0, 1:6, [1 6])

                 random =

                     0.5194   1.6619   0.1037   0.2138   2.6485   4.0269

                 random = unifrnd(0, 1, 2, 3)

                 random =

                     0.0077   0.0668   0.6868
                     0.3834   0.4175   0.5890

Purpose   Mean and variance for the continuous uniform distribution.

Syntax   [M,V] = unifstat(A,B)

Description   For the continuous uniform distribution,

- The mean is $\dfrac{a+b}{2}$

- The variance is $\dfrac{(b-a)^2}{12}$

Examples

```
a = 1:6;
b = 2.*a;
[m,v] = unifstat(a,b)

m =

    1.5000    3.0000    4.5000    6.0000    7.5000    9.0000

v =

    0.0833    0.3333    0.7500    1.3333    2.0833    3.0000
```

var

Purpose   Variance of a sample.

Syntax   y = var(X)
                   y = var(X, 1)
                   y = var(X, w)

Description   var(X) computes the variance of the data in X. For vectors, var(x) is the variance of the elements in x. For matrices, var(X) is a row vector containing the variance of each column of X.

var(x) normalizes by n–1 where n is the sequence length. For normally distributed data, this makes var(x) the minimum variance unbiased estimator MVUE of σ^2 (the second parameter) .

var(x, 1) normalizes by n and yields the second moment of the sample data about its mean (moment of inertia).

var(X, w) computes the variance using the vector of weights, w. The number of elements in w must equal the number of rows in the matrix, X. For vector x, w and x must match in length. Each element of w must be positive.

var supports both common definitions of variance. Let *SS* be the sum of the squared deviations of the elements of a vector x, from their mean. Then, var(x) = *SS*/(n-1) the MVUE, and var(x, 1) = *SS*/n the maximum likelihood estimator (MLE) of σ^2.

Examples

```
x = [-1 1];
w = [1 3];
v1 = var(x)

v1 =

     2

v2 = var(x, 1)

v2 =

     1

v3 = var(x, w)

v3 =

    0. 7500
```

See Also   cov, std

weibcdf

Purpose   Weibull cumulative distribution function (cdf).

Syntax   P = weibcdf(X, A, B)

Description   weibcdf(X, A, B) computes the Weibull cdf with parameters A and B at the
                   values in X. The arguments X, A, and B must all be the same size except that
                   scalar arguments function as constant matrices of the common size of the other
                   arguments.

                   Parameters A and B are positive.

                   The Weibull cdf is:

$$p = F(x|a, b) = \int_0^x abt^{b-1} e^{-at^b} dt = 1 - e^{-ax^b} I_{(0, \infty)}(x)$$

Examples   What is the probability that a value from a Weibull distribution with parame-
                   ters a = 0.15 and b = 0.24 is less than 500?

                       probability = weibcdf(500, 0.15, 0.24)

                       probability =

                           0.4865

                   How sensitive is this result to small changes in the parameters?

                       [A, B] = meshgrid(0.1:0.05:0.2, 0.2:0.05:0.3);
                       probability = weibcdf(500, A, B)

                       probability =

                           0.2929   0.4054   0.5000
                           0.3768   0.5080   0.6116
                           0.4754   0.6201   0.7248

Purpose   Parameter estimates and confidence intervals for Weibull data.

Syntax   phat = weibfit(x)
               [phat,pci] = weibfit(x)
               [phat,pci] = weibfit(x,alpha)

Description phat = weibfit(x) returns the maximum likelihood estimates, phat, of the
               parameters of the Weibull distribution given the data in the vector, x. phat is
               a two-element row vector. phat(1) estimates the Weibull parameter, *a*, and
               phat(2) estimates *b* in the pdf:

$$y = f(x|a, b) = abx^{b-1}e^{-ax^b}I_{(0, \infty)}(x)$$

               [phat,pci] = weibfit(x) also returns 95% confidence intervals in a matrix,
               pci, with 2 rows. The first row contains the lower bound of the confidence
               interval. The second row contains the upper bound. The columns of pci corre-
               spond to the columns of phat.

               [phat,pci] = weibfit(x,alpha) allows control over the confidence interval
               returned (100(1−alpha)%).

Example   r = weibrnd(0.5,0.8,100,1);
                   [phat,pci] = weibfit(r)

                   phat =

                       0.4746   0.7832

                   pci =

                       0.3851   0.6367
                       0.5641   0.9298

See Also   betafit, binofit, expfit, gamfit, normfit, poissfit, unifit

weibinv

Purpose   Inverse of the Weibull cumulative distribution function.

Syntax   X = weibinv(P, A, B)

Description   weibinv(P, A, B) computes the inverse of the Weibull cdf with parameters A
                   and B for the probabilities in P. The arguments P, A and B must all be the same
                   size except that scalar arguments function as constant matrices of the common
                   size of the other arguments.

                   The parameters A and B must be positive.

                   The inverse of the Weibull cdf is:

$$x = F^{-1}(p|a, b) = \left[\frac{1}{a}\ln\left(\frac{1}{1-p}\right)\right]^{\frac{1}{b}} I_{[0, 1]}(p)$$

Examples   A batch of light bulbs have lifetimes (in hours) distributed Weibull with param-
                   eters a = 0.15 and b = 0.24. What is the median lifetime of the bulbs?

                       life = weibinv(0.5, 0.15, 0.24)

                       life =

                         588.4721

                   What is the 90th percentile?

                       life = weibinv(0.9, 0.15, 0.24)

                       life =

                         8.7536e+04

Purpose   Weibull negative log-likelihood function.

Syntax   logL = weiblike(params, data)
[logL, info] = weiblike(params, data)

Description   logL = weiblike(params, data) returns the Weibull log-likelihood with parameters params(1) = *a* and params(2) = *b* given the data, x_i.

[logL, info] = weiblike(params, data) adds Fisher's information matrix, info. The diagonal elements of INFO are the asymptotic variances of their respective parameters.

The Weibull negative log-likelihood is:

$$-\log L = -\log \prod_{i=1}^{n} f(a, b|x_i) = -\sum_{i=1}^{n} \log f(a, b|x_i)$$

weiblike is a utility function for maximum likelihood estimation.

Example   Continuing the example for weibfit:

```
r = weibrnd(0.5, 0.8, 100, 1);
[logL, info] = weiblike([0.4746 0.7832], r)

logL =

   203.8216

info =

    0.0021    0.0022
    0.0022    0.0056
```

Reference   J. K. Patel, C. H. Kapadia, and D. B. Owen, *Handbook of Statistical Distributions,* Marcel-Dekker, 1976.

See Also   betalike, gamlike, mle, weibfit

weibpdf

Purpose   Weibull probability density function (pdf).

Syntax   Y = weibpdf(X, A, B)

Description   weibpdf(X, A, B) computes the Weibull pdf with parameters A and B at the
values in X. The arguments X, A and B must all be the same size except that
scalar arguments function as constant matrices of the common size of the other
arguments.

Parameters A and B are positive.

The Weibull pdf is:

$$y = f(x|a, b) = abx^{b-1}e^{-ax^b}I_{(0, \infty)}(x)$$

Some references refer to the Weibull distribution with a single parameter. This
corresponds to weibpdf with A =1.

Examples   The exponential distribution is a special case of the Weibull distribution.

```
lambda = 1:6;
y = weibpdf(0.1:0.1:0.6, lambda, 1)

y =

    0.9048    1.3406    1.2197    0.8076    0.4104    0.1639

y1 = exppdf(0.1:0.1:0.6, 1./lambda)

y1 =

    0.9048    1.3406    1.2197    0.8076    0.4104    0.1639
```

Reference   Devroye, L., *Non-Uniform Random Variate Generation*. Springer-Verlag. New
York, 1986.

Purpose   Weibull probability plot.

Syntax   weibplot(X)
                   h = weibplot(X)

Description   weibplot(X) displays a Weibull probability plot of the data in X. If X is a
                   matrix, weibplot displays a plot for each column.

                   h = weibplot(X) returns handles to the plotted lines.

                   The purpose of a Weibull probability plot is to graphically assess whether the
                   data in X could come from a Weibull distribution. If the data are Weibull the
                   plot will be linear. Other distribution types may introduce curvature in the
                   plot.

Example   r = weibrnd(1.2, 1.5, 50, 1);
                   weibplot(r)
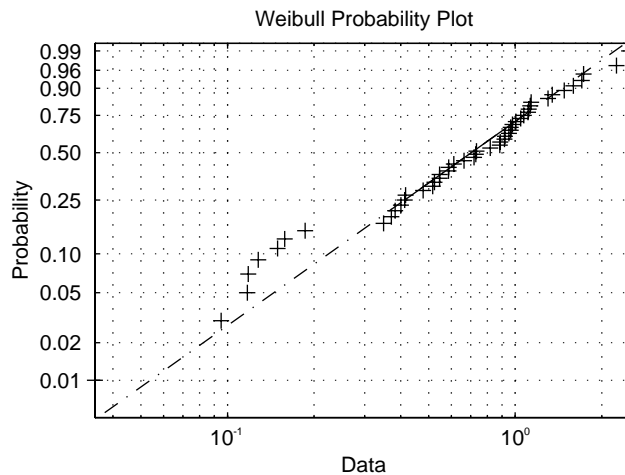
See Also   normplot

weibrnd

Purpose   Random numbers from the Weibull distribution.

Syntax   R = weibrnd(A, B)
                   R = weibrnd(A, B, m)
                   R = weibrnd(A, B, m, n)

Description   R = weibrnd(A, B) generates Weibull random numbers with parameters A and B. The size of R is the common size of A and B if both are matrices. If either parameter is a scalar, the size of R is the size of the other parameter.

R = weibrnd(A, B, m) generates Weibull random numbers with parameters A and B. m is a 1-by-2 vector that contains the row and column dimensions of R.

R = weibrnd(A, B, m, n) generates Weibull random numbers with parameters A and B. The scalars m and n are the row and column dimensions of R.

Devroye refers to the Weibull distribution with a single parameter; this is weibrnd with A = 1.

Examples   n1 = weibrnd(0.5:0.5:2, 0.5:0.5:2)

                   n1 =

                       0.0093   1.5189   0.8308   0.7541

                   n2 = weibrnd(1/2, 1/2, [1 6])

                   n2 =

                     29.7822   0.9359   2.1477   12.6402   0.0050   0.0121

Reference   Devroye, L., *Non-Uniform Random Variate Generation*. Springer-Verlag. New York, 1986.

Purpose   Mean and variance for the Weibull distribution.

Syntax   [M, V] = weibstat(A, B)

Description   For the Weibull distribution,

• The mean is:

$$a^{-\frac{1}{b}}\Gamma(1 + b^{-1})$$

• The variance is:

$$a^{-\frac{2}{b}}\left[\Gamma(1 + 2b^{-1}) - \Gamma^2(1 + b^{-1})\right]$$

Examples   [m, v] = weibstat(1:4, 1:4)

m =

    1.0000   0.6267   0.6192   0.6409

v =

    1.0000   0.1073   0.0506   0.0323

weibstat(0.5, 0.7)

ans =

    3.4073

x2fx

Purpose	Transform a factor settings matrix to a design matrix.
Syntax	D = x2fx(X)
	D = x2fx(X, '*model*')

Description   D = x2fx(X) transforms a matrix of system inputs, X, to a design matrix for a linear additive model with a constant term.

D = x2fx(X, '*model*') allows control of the order of the regression model. '*model*' can be one of these strings:

- 'interaction' – includes constant, linear, and cross product terms.
- 'quadratic' – interactions plus squared terms.
- 'purequadratic' – includes constant, linear and squared terms.

Alternatively, the argument, model, can be a matrix of terms. In this case each row of model represents one term. The value in a column is the exponent to raise the same column in X for that term. This allows for models with polynomial terms of arbitrary order.

x2fx is a utility function for rstool, regstats and cordexch.

Example
```
x = [1 2 3; 4 5 6]';  model = 'quadratic';
D = x2fx(x, model)

D =
```

1	1	4	4	1	16
1	2	5	10	4	25
1	3	6	18	9	36

Let x_1 be the first column of x and x_2 be the second. Then, the first column of D is for the constant term. The second column is x_1. The 3rd column is x_2. The 4th is $x_1 x_2$. The fifth is x_1^2 and the last is x_2^2.

See Also   rstool, cordexch, rowexch, regstats

Purpose   X-bar chart for Statistical Process Control.

Syntax   xbarplot(DATA)
                xbarplot(DATA, conf)
                xbarplot(DATA, conf, specs)
                [outlier, h] = xbarplot(...)

Description xbarplot(DATA) displays an x-bar chart of the grouped responses in DATA. The rows of DATA contain replicate observations taken at a given time. The rows must be in time order. The upper and lower control limits are a 99% confidence interval on a new observation from the process. So, roughly 99% of the plotted points should fall between the control limits.

xbarplot(DATA, conf) allows control of the the confidence level of the upper and lower plotted confidence limits. For example, conf = 0.95 plots 95% confidence intervals.

xbarplot(DATA, conf, specs) plots the specification limits in the two element vector, specs.

[outlier, h] = xbarplot(DATA, conf, specs) returns outlier, a vector of indices to the rows where the mean of DATA is out of control, and h, a vector of handles to the plotted lines.

Example   Plot an x-bar chart of measurements on newly machined parts, taken at one hour intervals for 36 hours. Each row of the runout matrix contains the

xbarplot

measurements for four parts chosen at random. The values indicate, in thousandths of an inch, the amount the part radius differs from the target radius.

```
load parts
xbarplot(runout, 0.999, [−0.5 0.5])
```
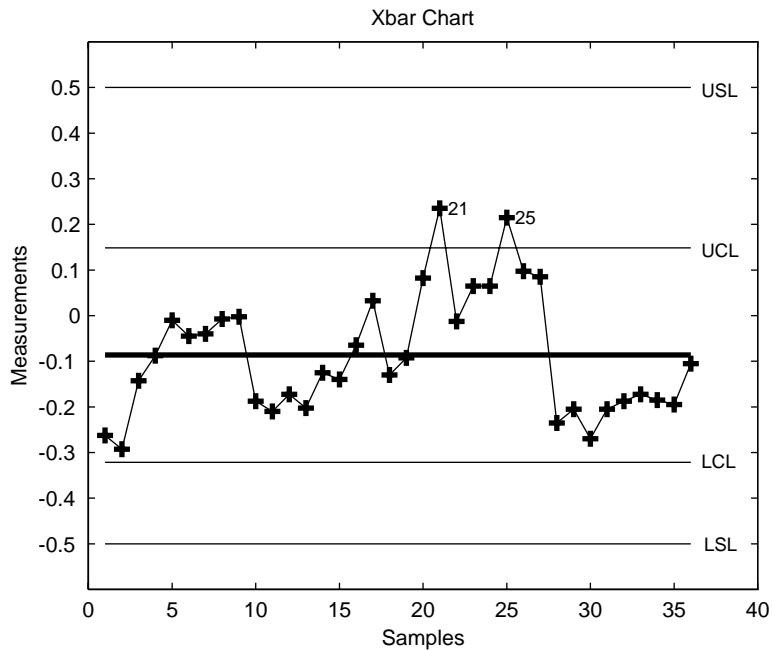

See Also   capaplot, histfit, ewmaplot, schart

Purpose   Hypothesis testing for the mean of one sample with known variance.

Syntax   h = ztest(x, m, sigma)
h = ztest(x, m, sigma, alpha)
[h, sig, ci] = ztest(x, m, sigma, alpha, tail)

Description   ztest(x, m, sigma) performs a Z test at significance level 0.05 to determine whether a sample from a normal distribution (in x) could have mean m and standard deviation, sigma.

h = ztest(x, m, sigma, alpha) gives control of the significance level, alpha. For example if alpha = 0.01, and the result, h, is 1 you can reject the null hypothesis at the significance level 0.01. If h = 0, you cannot reject the null hypothesis at the alpha level of significance.

[h, sig, ci] = ztest(x, m, sigma, alpha, tail) allows specification of one or two-tailed tests. tail is a flag that specifies one of three alternative hypotheses:

tail = 0 (default) specifies the alternative, $\bar{x} \neq \mu$.

tail = 1 specifies the alternative, $\bar{x} > \mu$.

tail = –1 specifies the alternative, $\bar{x} < \mu$.

sig is the p-value associated with the Z statistic. $z = \frac{\bar{x} - \mu}{\sigma}$

sig is the probability that the observed value of Z could be as large or larger *by chance* under the null hypothesis that the mean of *x* is equal to *μ*.

ci is a 1−alpha confidence interval for the true mean.

Example   This example generates 100 normal random numbers with theoretical mean zero and standard deviation one. The observed mean and standard deviation

are different from their theoretical values, of course. We test the hypothesis that there is no true difference.

```
x = normrnd(0, 1, 100, 1);
m = mean(x)
m =

    0.0727

[h, sig, ci] = ztest(x, 0, 1)

h =

     0

sig =

    0.4669

ci =

   -0.1232    0.2687
```

The result, h = 0, means that we cannot reject the null hypothesis. The significance level is 0.4669, which means that by chance we would have observed values of Z more extreme than the one in this example in 47 of 100 similar experiments. A 95% confidence interval on the mean is [–0.1232 0.2687], which includes the theoretical (and hypothesized) mean of zero.

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